iJRASET
International Journal For Research in Applied Science and Engineering Technology

INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Volume: 13 **Issue:** I **Month of publication:** January 2025

DOI: https://doi.org/10.22214/ijraset.2025.66749

www.ijraset.com

Call: 08813907089 | E-mail ID: ijraset@gmail.com

International Journal for Research in Applied Science & Engineering Technology (IJRASET)
ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538
Volume 13 Issue I Jan 2025- Available at www.ijraset.com

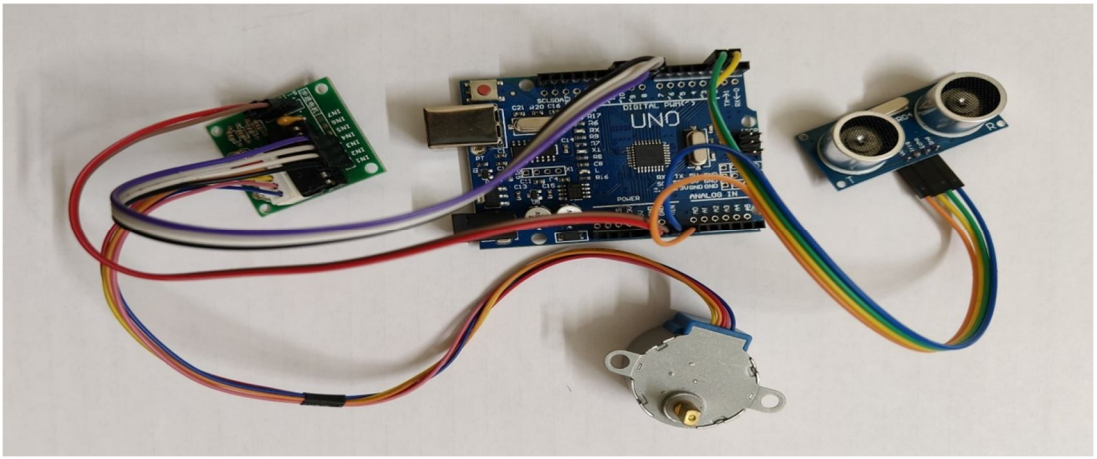
360 Degree Radar Using Ultrasonic Sensor

Prof. V. S. Gaikwad[1], Aditya Chavan[2], Viraj Bhalsing[3], Omkar Deore[4], Neerav Deshpande[5]
Department of Electronics & Telecommunication Engineering, AISSMS's Polytechnic, Pune, Maharashtra, India

***Abstract:** This paper presents the design and implementation of a 360-degree radar system using a single ultrasonic sensor, an Arduino board, and a 5V stepper motor with a driver module. The objective of this project is to create a low-cost, efficient radar-like system capable of scanning the environment over a full 360-degree range. The ultrasonic sensor, mounted on the stepper motor, allows for distance measurements at multiple angular positions, providing a comprehensive spatial mapping of the surrounding area. The Arduino board functions as the central controller, handling sensor data acquisition, motor control, and real-time data processing. The 5V stepper motor, combined with the driver module, enables precise rotational movement for accurate scanning, while ensuring smooth and reliable operation. The system's capabilities are demonstrated in various applications such as obstacle detection, environmental mapping, and basic autonomous navigation. This paper also discusses the challenges encountered during system integration, including achieving accurate motor control, sensor calibration, and managing processing speed for real-time data visualization. The results indicate that this radar system, powered by affordable components, is an effective solution for applications in robotics, surveillance, and educational projects.*

I. INTRODUCTION

In modern applications like robotics, home security, and automation, real-time environmental sensing and obstacle detection play a crucial role. Traditional radar systems are often expensive and require complex setups with multiple sensors to achieve full 360-degree coverage. This paper presents a cost-effective and simple alternative—a 360-degree radar system using a single ultrasonic sensor, an Arduino board, and a stepper motor. The system enables efficient spatial mapping by rotating the ultrasonic sensor in a full circle, capturing distance measurements at multiple angles. This data is processed and displayed for applications such as obstacle detection, environmental mapping, and basic autonomous navigation. The approach ensures affordability and ease of use, making it accessible for educational purposes, small-scale robotics projects, and surveillance applications.



II. LITERATURE SURVEY

A. Ultrasonic Sensors

Effective for short to medium-range distance measurement.
Performance can be affected by environmental noise, surface angles, and material type.

B. Rotating Mechanism

A single sensor mounted on a servo or stepper motor enables 360-degree coverage.
Simple and cost-effective compared to using multiple sensors.

ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538
Volume 13 Issue I Jan 2025- Available at www.ijraset.com

C. Arduino Uno
Widely used due to its affordability, ease of programming, and sensor compatibility.
Capable of processing sensor data and controlling motor movements efficiently.

D. Applications
Used in robotics for obstacle detection and avoidance.
Applied in security systems for perimeter monitoring.
Useful in parking assistance and other automation tasks.

E. Challenges
Limited sensor range and susceptibility to environmental interference.
Slower scan speeds due to the rotational mechanism.

F. Future Improvements
Integrating other sensors (e.g., infrared, lidar) for better accuracy.
Adding wireless communication for remote monitoring.
Using AI or machine learning for intelligent object detection and classification.

III. PROBLEM STATEMENT
In many applications, such as robotics, home security, and autonomous systems, there is a need for a cost-effective, reliable, and compact solution to detect objects and monitor surroundings in all directions. Traditional radar systems are often expensive, complex, or require multiple sensors to achieve 360-degree coverage, making them less accessible for small-scale projects or low-budget implementations. The challenge lies in developing a simple yet efficient 360-degree radar system using only one ultrasonic sensor and an Arduino Uno, capable of accurately detecting objects within a specified range while maintaining affordability, ease of use, and scalability for various real-world applications.

IV. PROPOSED METHODOLOGY
To build a 360-degree radar system using a single ultrasonic sensor and Arduino Uno, we'll follow a straightforward and organized approach:

A. Choosing Components
The system will use an ultrasonic sensor (like HC-SR04) for detecting objects, a servo or stepper motor for rotation, and an Arduino Uno as the main controller. These components are cost-effective and easy to work with.

B. Setting Up Hardware
The ultrasonic sensor will be mounted on the rotating motor to enable full 360-degree coverage. All components will be connected to the Arduino, which will manage both the sensor and motor. A stable power supply will ensure smooth operation.

C. Calibrating the System
The ultrasonic sensor will be calibrated to measure distances accurately, while the motor's speed and angles will be adjusted for smooth and complete rotation.

D. Collecting Data
The Arduino will control the sensor to take distance measurements at regular intervals while the motor rotates. This synchronization will allow us to map the surroundings accurately.

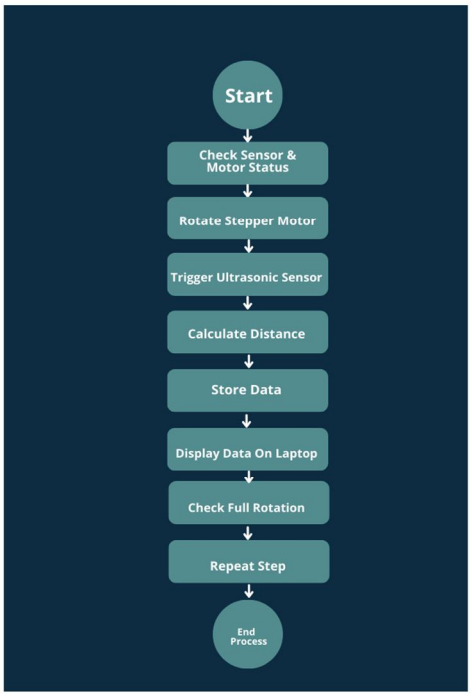
E. Processing and Displaying Data
The collected distance data will be processed and displayed visually as a 2D map of the area. Tools like Processing or Python can be used for real-time visualization, and an LCD screen can be added for on-device display.

ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538
Volume 13 Issue I Jan 2025- Available at www.ijraset.com

V. SYSTEM OPERATION

1) *Start Process:* The system initializes and prepares for operation.
2) *Check Sensor & Motor Status:* The system verifies if the ultrasonic sensor and stepper motor are functioning properly.
3) *Rotate Stepper Motor:* The stepper motor rotates to a specific angle to begin distance measurement.
4) *Trigger Ultrasonic Sensor:* The ultrasonic sensor emits a signal to measure the distance of an object.
5) *Calculate Distance:* The system processes the ultrasonic signal to determine the distance to the detected object.
6) *Store Data:* The calculated distance data is stored for further use.
7) *Display Data on Laptop:* The collected distance measurements are sent to a laptop for visualization or analysis.
8) *Check Full Rotation:* The system verifies whether the stepper motor has completed a full rotation.
9) *Repeat Step:* If the rotation is incomplete, the process repeats from step 3.
10) End Process: Once a full rotation is completed, the system stops its operation.

Flow Chart



VI. COMPONENTS USED

1) Arduino Uno
2) Stepper motor with Module
3) HC-SR04 Ultrasonic Sensor
4) Jumper Wires
5) USB Connector

VII. FUTURE SCOPE

The future of a 360-degree radar using a single ultrasonic sensor with an Arduino Uno is full of exciting possibilities. With further development, the system can be enhanced by combining it with other sensors like infrared or cameras to improve accuracy and expand its functionality. It has great potential in areas like robotics, drones, and autonomous vehicles for obstacle detection and avoidance, as well as in home security for monitoring surroundings. Future upgrades could include features like real-time mapping, wireless connectivity, and energy-efficient designs to make it more practical for battery-powered devices. By using faster motors, the radar could collect data more quickly and operate more smoothly. Adding machine learning capabilities could take it a step further by enabling it to identify and respond intelligently to objects.

While challenges like limited range and noise interference exist, advancements in noise-canceling techniques and sensor technologies could overcome these issues, making this system even more versatile for applications like industrial automation, parking assistance, and beyond.

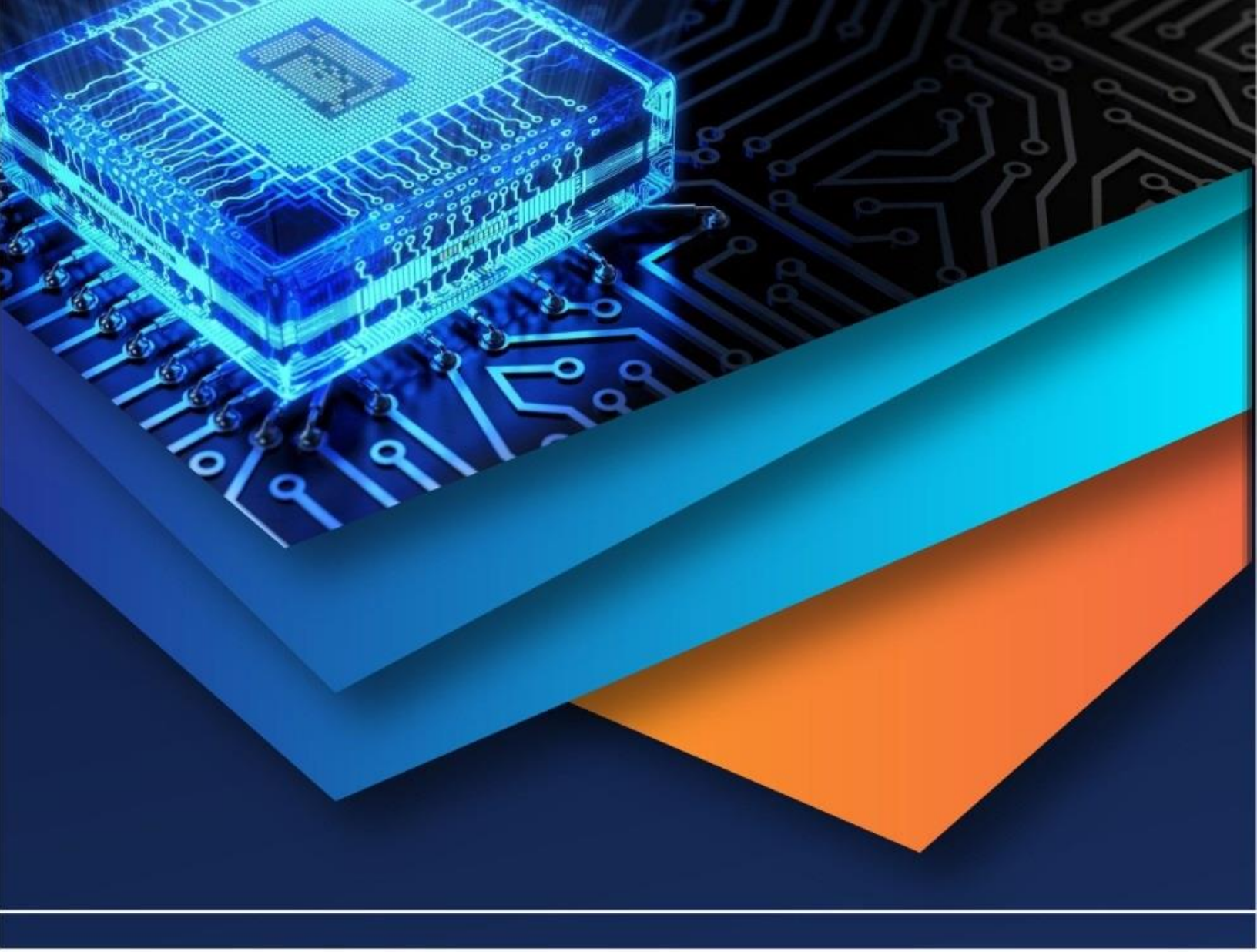
VIII. CONCLUSION

Creating a 360-degree radar system with a single ultrasonic sensor and Arduino Uno shows how affordable and simple technology can be used for practical purposes. This system offers an effective way to detect obstacles and map the environment, making it useful for applications like robotics, home security, and automation. By using a rotating motor and an ultrasonic sensor, it can gather data from all directions and display it in a simple way, with the Arduino handling the control and data processing.

While the system has some limitations—such as range and environmental interference—these can be improved with better calibration, noise reduction, and adding other sensors. The flexibility of this design allows for further upgrades, like wireless connectivity and machine learning for smarter functionality. In the end, this project proves that even with basic components, it's possible to build a reliable and cost-effective radar system that has plenty of potential for real-world use.

REFERENCES

[1] "Low-Cost Mini Radar: Design Prototyping and Tests", 20 July 2017 Dario Tarchi, Michele Vespe, Ciro Gioia, Francesco Sermi, Vladimir Kyovtorov and Giorgio Guglieri. Designed a surveillance radar system.
[2] Shreyes Mehta, Shashank Tiwari-"RADAR SYSTEM USING ARDUINO AND ULTRASONIC SENSOR", Volume 3, Issue 4 April 2018.
[3] Anuj Dutt (Author), 2014, Arduino-based RADAR System, Munich, GRIN Verlag.
[4] Srijan Dubey,Supragya Tiwari, Simit Roy -" IMPLEMENTATION OF RADAR USING ULTRASONIC SENSOR" Indian J.Sci.Res. 2017.
[5] J. L. Crowley, "World Modelling and Position Estimation for a Mobile Robot Using Ultrasonic Ranging," Proc. IEEE Int. Conf. Robotics and Automation, pp. 674-680, 1989.



10.22214/IJRASET

45.98

IMPACT FACTOR: 7.129

IMPACT FACTOR: 7.429

INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY