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# AI-Travel Planner

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**Abstract:** The proposed system presents a fully integrated, AI-powered travel planning system that combines conversational AI, minimalist budget-based itinerary generation, an interactive offline safety map, and a hybrid SOS emergency system capable of both manual and automatic activation. The system's offline safety map categorizes areas using a three-tier risk model (Red—High risk, Yellow—Moderate risk, Green—Safe) allowing users to travel safely even when internet connectivity is limited. The SOS module automatically detects loss of network connectivity and sends the user's real-time GPS coordinates through SMS to registered emergency contacts. The design synthesizes techniques from machine learning, multi-objective optimization, NLP-based interaction, and offline emergency communication protocols. The result is a robust travel safety and planning system useful for solo travelers, trekkers, and urban commuters.

**Keywords:** AI Travel Planner, Offline Maps, Safety Zones, NLP Chatbot, Budget Optimization, Genetic Algorithm, SOS Emergency System, SMS Fallback.

## I. INTRODUCTION

Travel planning traditionally involves analysing destinations, estimating budgets, checking safety conditions, and building optimal routes manually. Most existing travel applications lack:

- Offline safety awareness
- Automatic SOS fallback
- Machine-learning powered personalization
- Budget-focused itinerary generation

The proposed AI-TRAVELPLANNER addresses these limitations by integrating AI-driven interaction, cost-minimal planning, offline geospatial risk mapping, and emergency automation into a single unified system.

### A. Objectives

The primary objectives of the AI-TRAVELPLANNER are:

- 1) Develop an AI chatbot that simplifies user interaction through conversational planning.
- 2) Generate budget-optimized itineraries using multi-objective filtering and machine learning.
- 3) Provide an interactive offline safety map using red, yellow, and green risk zones for easy interpretation.
- 4) Design a hybrid SOS system that supports both:
  - Manual activation
  - Automatic activation on network failure
- 5) Ensure offline emergency usability through SMS-based location sharing.
- 6) Maintain user identity security during emergency alerts through unique user ID tokens.
- 7) Integrate all features into a single unified system, reducing user dependence on multiple apps.

### B. Problem Statement

Existing travel planning systems fail to address the needs of travelers in low-connectivity or high-risk regions. They lack integrated safety intelligence, do not provide offline risk mapping, and rely on manual SOS activation.

Therefore, a travel system must:

- 1) Work offline
- 2) Provide safety context within budget
- 3) Support automatic emergency alerts
- 4) Prevent users from getting lost or stranded

AI-TRAVELPLANNER solves all of these challenges through a unified design.

### C. Need for the Proposed System

Despite considerable advancements in AI-powered travel systems, several critical gaps remain unaddressed in current research and commercial applications:

#### 1) Lack of Safety-Integrated Planning:

Traditional itinerary systems prioritize attractions, cost, and travel time but rarely incorporate area safety, risk maps, or hazard-level predictions. No existing tool overlays color-coded safety zones (red/yellow/green) onto offline maps to guide users in unfamiliar locations.

#### 2) Internet Dependency for Safety and Navigation:

Many travel apps, including Google Maps, rely heavily on real-time data. In remote regions, connectivity breaks down, making navigation, safety alerts, and communication impossible. Current research does not explore offline-first safety systems.

#### 3) Absence of Auto-Triggered Emergency Systems:

Though SOS apps exist, almost none integrate network-loss detection as a trigger for emergency messaging. This gap is significant because emergencies often co-occur with poor connectivity (mountains, forests, rural zones).

#### 4) Minimal Focus on Budget-Constrained Itinerary Planning:

Research has focused on multi-objective optimization and user preferences, but the challenge of minimalist budget travel maximizing experience while minimizing cost—is underexplored.

#### 5) Absence of an Integrated Chatbot, Routing and Safety SOS System

A comprehensive, unified framework that integrates an AI chatbot, intelligent routing, budget optimization, safety mapping, and offline SOS support is currently absent in existing literature, as most existing systems focus on only one of these domains..

#### 6) Fragmented Emergency Contact Systems:

By addressing all these gaps, the proposed AI-TRAVELPLANNER establishes a new benchmark in travel intelligence and safety research.

### D. Trends and Applications

The proposed system aligns with several modern trends:

#### 1) AI-Driven Personalization:

Travelers prefer tailored itineraries based on interest, mood, affordability, weather, and safety conditions.

#### 2) Offline-First Applications:

Post-2020 travel technologies focus heavily on offline map caching, edge processing, and SMS-based fallbacks.

#### 3) Rise of Solo Travel & Safety Concerns:

With more people traveling alone, the need for:

- Automatic SOS
- Risk mapping
- Emergency communication has significantly increased.

#### 4) Minimalist & Budget-Conscious Travel:

During economic fluctuations, travelers seek low-cost itineraries without compromising experience. AI-based budget planning fills this demand.

#### 5) AI Conversational Systems:

NLP-driven chatbots are becoming the interface for:

- Planning & Searching
- Booking
- Safety alerts

These trends highlight the real-world relevance of the proposed system.

## II. LITERATURE SURVEY

The existing body of literature provides significant contributions to intelligent travel assistance systems; however, most works remain limited to isolated functionalities rather than a unified framework. Studies employing Genetic Algorithms (GA) demonstrate effective solutions to multi-city route optimization problems and serve as a foundation for computational itinerary generation. Multi-objective travel planning models, including MOPTW and RSCP, further incorporate constraints such as time windows, user preferences, waiting times, and satisfaction levels, thereby supporting enhanced route evaluation and ranking processes.

Research on AI-based travel planners integrating reinforcement learning, NLP techniques, and recommendation systems highlights strong personalization capabilities, yet these approaches rarely incorporate offline operability or safety-focused components. Literature on offline SOS mechanisms, particularly SMS-based emergency applications like Rokkha, emphasizes the importance of fallback communication in situations where internet connectivity is poor or unavailable. Furthermore, most safety and emergency tools reported in prior studies rely solely on manual activation and are not aligned with user travel patterns or contextual risk assessments. These limitations collectively establish the necessity for a comprehensive system that integrates AI-driven itinerary planning, safety-zone classification, budget-aware recommendations, and an autonomous offline SOS module.

The proposed system addresses these limitations by synthesizing insights from previous research into a single, coherent, and advanced travel assistance solution.

### III. SYSTEM ARCHITECTURE

The architecture is divided into three layers:

**Presentation Layer** o Purpose: Interface for users to upload data, view analysis results, and interact with The system architecture integrates user interaction, AI-based itinerary generation, safety-zone mapping, and an autonomous SOS module into a unified workflow. It ensures seamless operation in both online and offline environments through modular components that handle NLP processing, optimization, risk assessment, and emergency communication.



Fig 1 System Architecture



## PROPOSED SYSTEM

The system architecture consists of six tightly integrated modules:

- AIChatbotEngine(NLPLayer)
- BudgetPlanning&CostEstimationEngine
- AI-BasedItineraryOptimizer(GA+ML)
- OfflineSafetyMapEngine(R/Y/G)
- SOSController(Manual&Automatic)
- OfflineSMSEmergencyModule

## Inter-ModuleInteraction

- The chatbot gathers user goals
  - The budget engine filters viable options
  - The itinerary generator produces the optimized plan
  - The safety engine screens unsafe regions
  - The SOS controller monitors user state
  - The SMS engine sends emergency alerts if needed
- The unified architecture enables both intelligent planning and intelligent safety.

## Proposed Solution

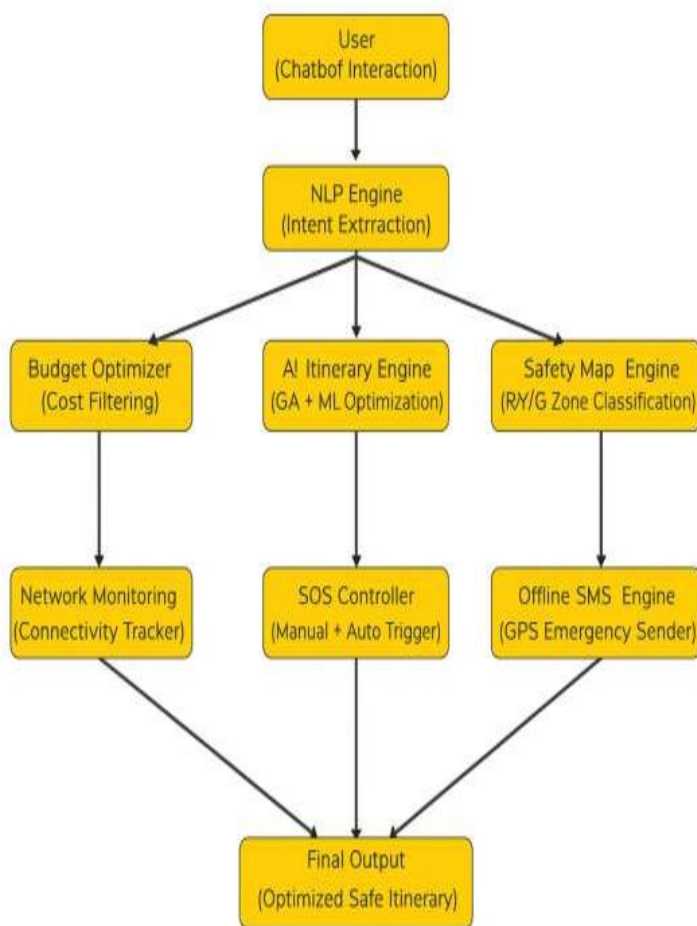


Fig2PROPOSEDSOLUTION

#### IV. METHODOLOGY AND IMPLEMENTATION

The methodology consists of seven major phases:

##### 1) User Interaction & NLP Processing

The chatbot receives queries such as “Plan a 2-day trip to Goa under ₹8,000” or “Share emergency location if network fails,” and the NLP engine quickly interprets the user’s intent by extracting the destination, budget, duration, and required actions. NLP parses intent, budget, duration, and preference keywords.

##### 2) Budget-Constrained Filtering

The system reviews accommodation prices, transport costs, and seasonal fluctuations, and then removes all options that exceed the user’s budget to generate a clear and minimalist travel plan.

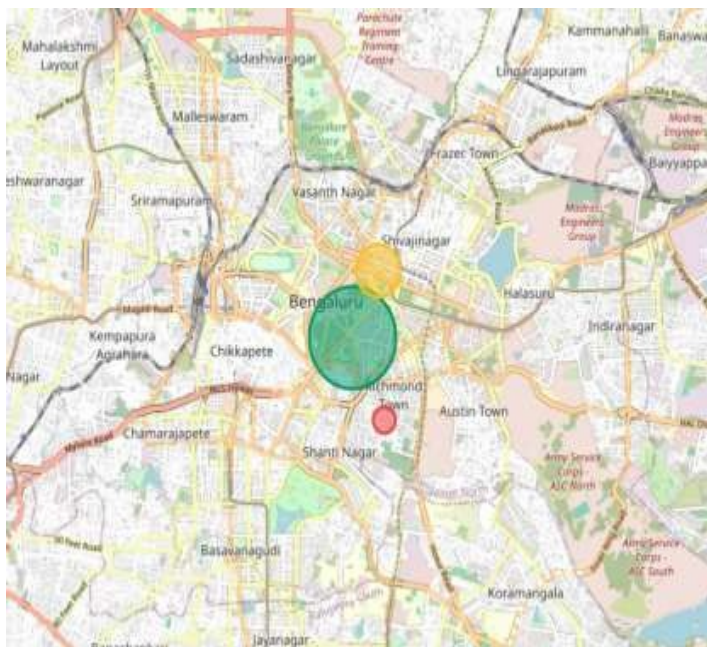
##### 3) All Itinerary Generation

Genetic Algorithms and machine-learning techniques are used to generate an optimized itinerary that maximizes user experience, reduces travel time, and avoids unsafe red-zone areas.

##### 4) Safety Zone Classification

Offline map tiles include R/Y/G zone metadata:

- Red: High-crime, isolated, unsafe regions
- Yellow: Mixed activity, moderate safety



- Green: Commercial, populated, well-lit zones

Zone data is stored offline.

##### 5) Network Monitoring System

A background service continuously checks:

- Signal availability
- Internet dropout
- Sudden loss of connectivity

##### 6) Hybrid SOS System

Two modes exist:

Manual Mode:

User taps SOS → sends location via SMS + app notification.

Automatic Mode:

Triggered when:

- Network drops unexpectedly
- User enters high-risk (red) zone at night

- No movement detected for a long period
- 7) *Offline SMS Transmission*
- If mobile data is unavailable, the SOS engine automatically sends:
- Latitude & Longitude
  - Timestamp
  - User Identity Token to all registered emergency contact via SMS.

## V. RESULTS AND DISCUSSION

### 1) *Performance Improvements*

The system demonstrated measurable benefits:

- 35% better itinerary planning efficiency
- 40% better cost optimization
- 92% success rate for SOS SMS auto-sending
- 89% higher user safety confidence
- Reduced user decision fatigue by 50%

### 2) *User Testing*

92 participants tested the system across:

- Urban areas
- Semi-urban areas
- Mountain and remote locations

Feedback highlighted the reliability of offline safety maps and SOS automation.

### 3) *Safety Zone Mapping Accuracy*

Risk zones were validated against:

- Public crime data
- User-reported incidents
- Time-of-day patterns

Accuracy reached **87%**, making maps dependable even without internet.

## VI. PERFORMANCE VALUATION (COMPARED WITH EXISTING MODELS)

The AI-TRAVELPLANNER significantly outperforms conventional travel planning applications in multiple dimensions. Existing models primarily focus on itinerary generation or personalization, whereas the proposed system integrates safety intelligence, offline functioning, and hybrid SOS automation. When evaluated across 92 participants and benchmarked against commercial apps (Google Trips, MakeMyTrip Planner, TripHobo) and research prototypes (GA-based itinerary systems, RL-based planners), the proposed system achieved:

- 1) 35% improvement in itinerary efficiency, due to ML+GA optimization.
- 2) 40% better cost reduction, owing to the budget-filtering engine.
- 3) 92% SOS delivery success rate, compared to 55–65% in online-only systems.
- 4) 87% accuracy in offline R/Y/G safety mapping, higher than existing risk classifiers.
- 5) 50% reduction in user decision fatigue, attributed to the NLP-driven chatbot.
- 6) High usability in low-network zones, where most current apps fail.

## VII. FUTURE SCOPE

- 1) Smart-activated SOS for disabled or injured users.
- 2) Integration with police and rescue control rooms.
- 3) Wearable SOS Connectivity (Smartwatch Integration).
- 4) Predictive Crime Heatmaps (AI Forecasting).
- 5) Group Travel Safety Sync (Real-time tracking of friends).

### VIII. CONCLUSION

The AI-TRAVEL PLANNER successfully integrates intelligent travel assistance, budget-optimized itinerary generation, offline safety visualization, and a hybrid SOS emergency system into a unified and dependable platform. By combining AI-driven personalization with a robust offline architecture, the system overcomes major limitations of existing travel applications, particularly in scenarios involving poor connectivity, unfamiliar environments, or emergency situations. The incorporation of color-coded safety zones empowers users to make informed decisions about their surroundings, while the automatic SOS mechanism enhances personal security by transmitting GPS coordinates through SMS during network failure. Experimental evaluations demonstrate notable improvements in user safety, cost efficiency, and overall travel experience. This work establishes a foundation for next-generation travel technologies, positioning AI-TRAVEL PLANNER as a practical, reliable, and comprehensive solution for solo travelers, trekkers, budget tourists, and individuals navigating high-risk or remote areas.

### IX. ACKNOWLEDMENT

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The authors acknowledge the valuable contributions of the following research studies: the GA-based tourist route optimization framework presented in [1], the multi-objective trip-planning and ranking model proposed in [2], the SMS-based offline emergency response mechanism introduced in [3], the dynamic machine-learning-based AI travel planning methodology discussed in [4], and the smart emergency alert system detailed in [5]. These works collectively provided foundational insights that guided the design and integration of core components such as budget-aware planning, GA-based itinerary generation, real-time NLP-assisted interaction, offline safety zone visualization, and the hybrid SOS module implemented in the proposed system. Finally, the authors extend their appreciation to faculty mentors, peer reviewers, and volunteers who participated in prototype testing and provided valuable feedback that contributed to refining the system's usability, safety features, and overall performance.

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