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A Review on Crack Detection in Wind Turbine Blade

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Abstract: It was observed that there is a need to reduce of maintenance and operational cost of Wind Energy conversion System. The most efficient way of reducing this cost would be to carry out Non-destructive techniques (NDT) and continuously monitor the condition of the system. This allows for early detection of the blade Cracking or damage, minimizing downtime, and maximizing productivity. The importance of condition monitoring and fault diagnosis in WECS (blades) and keeping in mind the need for future research, this paper is intended as a brief status describing different type of faults, methods of detection and future aspects.

Keywords: Crack detection techniques, vibration analysis, Wind turbines blades, Fiber glass reinforced polymer, Condition monitoring.

I. INTRODUCTION

Wind energy conversion is the fastest-growing source of new electric generation in the world and it is expected to remain so for some time. At the end of 2003 the installed wind capacity stood at over 40000 MW, having doubled since 1999, and it has exceeded 95000 MW by the end of 2008[1]. But the higher target is to achieve 12% of the world's electricity from wind power. So, to achieve this target the number of wind turbine must be increased and the most important thing is to reduce the downtime of the existing wind turbine, and if we are able to achieve this target in future then we will be depending upon the renewable energy resource which is wind, then being depending upon the non-renewable energy resources such as thermal power plants[2]

Under normal working conditions, wind turbine blades suffer from the wind loads which drive the blades rotation and rotate the motor's rotor to generate electricity and store it. After a prolonged period of time, turbine blades suffer from fatigue induced degradation due to cycling loads, and cracks will initiate in the materials of the blade. Under the right conditions, the cracks will develop rapidly and lead to the failure of a wind turbine blade, or even the collapse of the whole wind turbine. In general, strong winds, lightning, climatic changes, corrosion, scratches due to wearing out of the protective film, ice saturation or even collisions with birds flying around the turbine are responsible for the damage and cracking of wind turbine blades (CWIF 2012)[3].

Wind energy capacity was observed to increase exponentially which shows the reliance of countries as increased utilization of non-convectional energy sources.

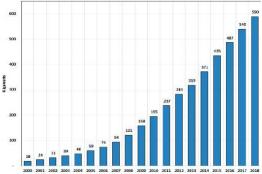


Figure 1: Wind Energy Capacity in GW.

Autonomous online condition monitoring systems with integrated fault detection algorithms allow early warnings of mechanical and electrical faults to prevent major component failures. Side effects on other components can be reduced significantly. Many faults can be detected while the defective component is still operational.



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Thus, necessary repair actions can be planned in time and need not to be taken immediately. By using the Non-destructive techniques such as the vibration analysis, ultrasonic testing, acoustic emission transducers and many more help in identifying the fault easily and carry out the remedial action in time.

II. FAULTS IN WIND TURBINE BLADES

As the number of wind turbine are increasing to increase the energy generation the faults occurring in the wind turbine are also increasing, which restrict the growth in energy generation and increases the downtime and maintenance cost. The most occurring damages in the wind turbine are in the mechanical and electrical components. The mechanical components include blades, hub, rotor, mechanical or pitch control system, hydraulic system, gearbox, air brakes, mechanical brakes and main shaft. The electrical components include generator, electrical controls, grid/ electrical system and wirings and control box[4].

The major faults occurring in the wind turbine blades are trailing edge cracking, lighting damage, pollution in the air, erosion due the daily working, contamination at leading edge, icing, delamination, longitudinal cracks, 45-degree cracks, edge wise cracks and surface stripping of edges etc.

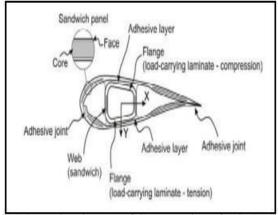


Figure 2: Schematic Diagram of Cross section of Wind turbine blade.

These faults which occur in the wind turbine blades are caused by different reasons such as wind forces acting in different directions like in a storm, natural causes like change in environmental issues or climatic changes, accidents like any bird flying around strikes the blade, faulty manufacturing, corrosion, wearing out due to regular use.

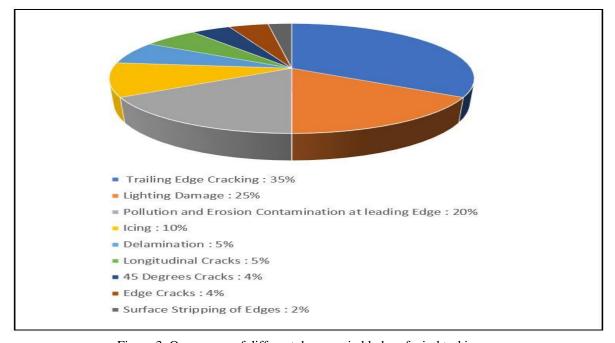


Figure 3: Occurrence of different damages in blades of wind turbine.



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A. Cracking

Cracking is the main damage mode in the trailing edge of a wind turbine blade, which is the area where the two half shells are bonded. This type of cracking is divided into longitudinal and transverse cracks. There are two more types of cracks occurring in the wind turbine blades and those are 45-degree cracks and edge cracks. A transverse crack can propagate from the trailing edge to both the pressure and suction side, while a longitudinal crack occurs at the transition region between the spar cap and the sandwich panels[5][6][7].



Figure 4(a): transverse cracking.



Figure 4(b): Longitudinal cracking.

B. Lighting Damage

Lightning strikes bring a unique set of challenges for wind turbine operators. The intense heat generated during a strike can compromise the structural integrity of various components. From blades to towers, being vigilant about potential damage is crucial for ensuring the safety and longevity of the turbines[8][9].



Figure 5: Lighting Damage.





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C. Pollution and Erosion

The Deposition of the harm chemical molecule present in the air increases the roughness of the surface of the wind turbine blade which results in the reduction of the efficiency of energy generation[10][11].

Erosion of wind turbine blades, also known as leading edge erosion (LEE), occurs when particles like rain, hail, sand, dust, insects, and ultraviolet radiation impact the blade's leading edge, removing material and causing a rough profile. This can degrade the blade's aerodynamic performance and structural integrity, and may reduce the turbine's annual energy production



Figure 6(a): Pollution on wind turbine.



Figure 6(b): Erosion of leading edge.

D. Icing

Icing can be a major threat to the integrity and efficiency of wind turbines in cold climates. Due to icing the unbalance is created in the wind turbine causing failure and unwanted breakdown[12].



Figure7: Icing on the wind turbine.



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E. Delamination

Delamination is when the layers of a composite material begin to separate. In wind turbines, delamination can occur during the manufacturing process of the unidirectional laminate in the spar cap of the blade[13][14].



Figure 8: delamination of blade.

III. METHODS OF FAULT DETECTION

The most important part is which method you are going to use for the fault detection in the wind turbine blade. The selection of the methods for fault identification is a very difficult part and may vary as per every situation.

The selection criteria of the method of fault identification in the wind turbine depends upon the cost of the components used in the identification process, we have to take a deeper look into the advance technology if any available in the method such as online condition monitoring on the component, how efficient is the method and is the fault diagnosis possible, what is the deployment or the current status of the method, what type of the sensors are used to convert the mechanical stress which is generated in the wind turbine blade to the electrical energy which can be further decoded by the data acquisition system and on which component the method can be used.

Below Given are some condition monitoring techniques which are used in day-to-day life. There different properties are also given below on which we can classify then as per our needs[15][16][17][18].

A. Condition Monitoring Techniques

Condition monitoring (CM) is a maintenance technique that combines machine sensor data with software to predict machine health and safety. CM uses real-time data to measure vibration and other parameters. Vibration analysis a well-known predictive maintenance method that uses vibration sensors to measure vibration data from previous experiments. Vibration patterns can indicate equipment failure, and vibration monitors can identify defects months before problems become serious. Thermography non-contact technique that can be performed while equipment is running, reducing the need for predictive maintenance outages. Ultrasonics a common technique in mechanical applications that measures high-frequency signals to help companies understand how friction or other bearing defects can increase.

Table 1: Condition Monitoring Techniques and their properties[19][20][21][22].

						Bearing, Generator,
1	Thermocouple	Low	Yes	No	Already Used	Convertor, Transformer
	Oil Particle					
2	Counter	Low	Yes	No	Already Used	Gearbox and bearing
						Main Shaft, Main Bearing,
3	Vibration Analysis	Low	Yes	Yes	Already Used	Generator, Gearbox
		Low to				
4	Ultrasonic Analysis	Medium	Yes	No	Being Tested	Tower and Blade



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5	Eddy current	Low	Yes	No	Already Used	Generator
	Vibro-acoustic				·	Blade, Main Bearing and
6	Measurement	Medium	Yes	No	No	gearbox
		Medium to				
7	Oil Quality Analysis	high	No	Yes	No	Gearbox, Bearing
	Acoustic Emission					Blade, Main Bearing and
8	Transducers	High	Yes	No	No	gearbox
	Torsional vibration					
9	(encoder-based)	Low	Yes	No	Being Tested	Main Shaft, Gearbox
	Fibre optic strain					
10	gauges	Very High	Yes	No	Already Used	Blade
						Blade, Main Shaft, Main
11	thermography	Very High	Yes	No	No	bearing and generator
	Shaft torque					Blades, Main shaft and Main
12	measurement	Very High	Yes	No	Being Tested	bearing
	Shock pulse					
13	method	Low	Yes	No	No	Gearbox and bearing

B. Fault Detection Techniques

Fault detection is the process of discovering the presence of a fault in any equipment before it manifests itself in the form of a breakdown. There are many techniques used for the fault detection method in the blades of the wind turbine, we are going to concentrate on the Non-destructive techniques of the fault detection, which are as follows.

Table 2: Fault Detection Techniques and their properties[23][24][25][26][27].

G	Table in the Abilities of James Jetation		Associated		G
Sr.	Techniques	Sechniques Abilities of damage detection.		Sensitivity	Contact type
No.			Cost		
1	Acoustic Emission	Very small location and size of damage	Expensive	High	Contact
2	Vibration based	Moderate size	Cheap	Moderate	Contact
3	Fiber optical	Adhesive failure	Expensive	High	Contact
4	Strain Measurement	Small	Moderate	Moderate	Contact
5	X rays	Location and size	-	-	Non-Contact
6	Ultrasonic	Location and size (Delamination)	Moderate	High	Contact
7	Digital Image Correlation	Full-field identification	-	-	Non-Contact
8	Shearography	Full-field identification	-	-	Non-Contact
9	Thermal Imaging	Full-field identification	Expensive	High	Non-Contact
10	Pattern Recognition	Full-field identification	Moderate	High	Non-Contact

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Chart 1: Brief Classification of the Fault Detection techniques (NDT)[27].

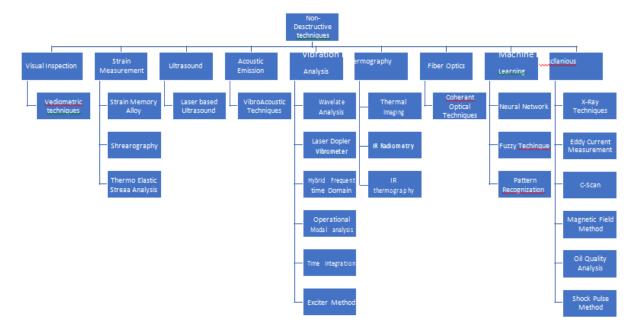


Table 3: Techniques used to identify defects in wind turbine[27][3][28].

Techniques	Fiber	Fatigue	Crack	Severity	Wave	Delamina	Mass	Edgewise	Internal	Damage
	Defect	Damage	Location	of damage	Defect	tion	Change	crack	deformation	length
Shearography	Yes	Yes	-	-	-	-	-	-	-	-
Digital Image Correlation	-	-	Yes	-	Yes	-	-	-	-	Yes
Fiber Optics	-	Yes	-	-	-	-	-	-	-	-
Piezoelectric sensors	-	Yes	-	-	-	-	-	-	-	-
Thermal Imaging	-	Yes	Yes	-	-	Yes	-	-	-	Yes
Acoustic Emission	-	Yes	Yes	Yes	-	-	-	-	-	-
Vibration Based Techniques	-	Yes	Yes	-	-	-	Yes	Yes	-	-
Video Metric Techniques	-	-	-	-	-	-	-	-	Yes	-
OMA	-	-	-	-	-	-	Yes	-	-	-





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The above given techniques provide the information that which of the technique is most likely suitable for the particular defect. Each and every technique has its own ability and capacity of fault detection. Shearography, also known as speckle pattern shearing interferometry, is a non-destructive optical technique that uses laser speckle patterns to measure surface and subsurface damage in structures. It's similar to holographic interferometry and uses coherent light or coherent soundwaves to provide information about the quality of different materials. Digital Image Correlation (DIC) is a non-contact optical technique that measures strain and displacement. It is a 3D, full-field technique that tracks grey value patterns to measure deformation and strain on almost any material. Piezoelectric sensors are devices that convert physical parameters such as pressure, strain, or acceleration into electrical signals without the need for an external voltage or current source. The prefix piezo- means "press" or "squeeze" in Greek. The sensors are small and highly sensitive, making them well-suited to everyday objects. Thermal imaging is simply the process of converting infrared (IR) radiation (heat) into visible images that depict the spatial distribution of temperature difference in a scene viewed by a thermal camera.

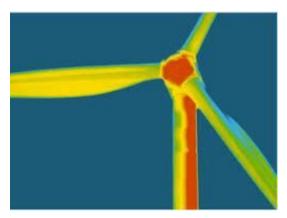


Figure 4: Thermal image of wind turbine.

Acoustic emission (AE) is the phenomenon of radiation of acoustic (elastic) waves in solids that occurs when a material undergoes irreversible changes in its internal structure.

C. Ultrasonic

There are many methods used in the fault identification in the wind turbine blade which come under the category of Non-destructive Methods of identification, but the mostly used method which is having high efficiency is the Ultrasonic testing method.

High-speed Ultrasonic (UT) Systems enable a full volumetric examination of materials and are designed to detect surface, subsurface, internal and dimensional flaws.

This type of testing utilizes high-frequency sound waves that are transmitted throughout the material being tested in order to conduct a thorough inspection.

Ultrasonic inspection can be used to detect surface flaws, such as cracks, seams, and internal flaws such as voids or inclusions of foreign material. It's also used to measure wall thickness in tubes and diameters of bars.

An ultrasonic wave is a mechanical vibration or pressure wave similar to audible sound, but with a much higher vibration frequency. For NDT purposes, the range is usually from 1MHz to 30MHz.

Depending on the test requirements, these waves can be highly directional and focused on a small spot or thin line, or limited to a very short duration.

Predictive maintenance vibration sensors are a proactive approach to maintenance that aims to predict when equipment failure might occur and to prevent it before it does. Ultrasonic sensors are a key tool in predictive maintenance, as they can be used to detect early-stage failures for example in slow rotating machinery which may not be easily detectable with vibration analysis alone[29].

The idea is that certain sound frequencies over the 20kHz range (over the human hearing limit) are produced when rotating machinery starts experiencing issues. These soundwaves called ultrasounds have short wavelengths and low energy, which does not allow them to travel long distances (materials attenuate them heavily). On the other hand, this short wavelength results in a high frequency (they are inversely proportional), which makes them very directional and it is easy to detect and filter them out from other acoustic signals, allowing them to pinpoint their source, thus the source of the machine fault.



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There is no shortage of industrial applications where low RPM machinery requires maintenance. Vibration monitoring systems for Pumps, fans, entire HVAC systems, etc. have system components that rotate at low speeds. These are more difficult to monitor than ones that operate at higher speeds as several factors influence measurements in low frequencies:

Amplitudes (g levels) of vibrations for low RPS machines are very small, which makes them hard to detect unless a very sensitive accelerometer is utilized, however, these are expensive (500mV/g or better).



Figure 9: Wavelength of the different frequency.

Vibrations are in the 0 to 50 Hz range, which complicates detection as well and there is more noise in this band.

One could use a vibration sensor, however for the aforementioned reasons, it would have to be very sensitive and noise resistant, which would greatly increase its cost. To put it bluntly, the cost is simply not worth it when one could use a way simpler and cheaper ultrasound sensor[30][31].

In bearings ultrasound is produced by friction between the bearings and the raceway, the impacts produce acoustics in the ultrasound band (which has no direct relation to the RPM), thus it can be easily measured with an ultrasound sensor. As a rule of thumb bearing defects are in the 35 to 45 kHz band, thus it is suitable for sensors to work with a 37 kHz resonant frequency[32][33].



Figure 10: Ultrasonic sensors.

IV. **SENSORS**

Sensors are the most important thing or we can say the backbone of the non-destructive techniques used in the fault analysis of the wind turbine blades. There are different types of sensors and each and every sensor has its own advantages and limitations regarding its resolution and fault identification capacity. Below given sensors are mostly used in the fault identification methods, there advantages and limitations are also given which helps us to understand them perfectly[34][35][36].

	Table 4: Types of sensors and the	
Sensor Type	Advantages	Limitations
Strain Gauge	Inexpensive	Vulnerable to electrical disturbances
	Common, mature technology	Prone to failures and noise
		Relatively low sensitivity
Accelerometer	Inexpensive	Vulnerable to electrical disturbances



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	Common, mature technology	Usefulness focused mainly for modal analysis in vibration-based monitoring		
Acoustic	High sensitivity to many different types of	Must be near damage source for		
emission	damage	accurate measurement		
	Helpful for vibration and wave	Requires high sampling rate		
	propagation-based methods			
	Possible for use in damage visualization	Influenced by material anisotropy		
	and localization	found in wind turbine blades		
PZT/MFC	Active sensing possible	Vulnerable to electrical disturbances		
	Wide range of applications (i.e. impedance, wave propagation, vibration	Piezoceramics may be brittle		
	based) High sensitivity to structural changes	Power amplification may be needed for active sensing applications		
	Wide range of sensor geometries for different applications			
	Inexpensive			
	Potential for energy harvesting			
Optical fibre sensor	Immune to electromagnetic interference	Fragile		
	Multiplexing possible (FBGs)	May need temperature compensation due to cross sensitivities		
	High precision	Interrogator unit is expensive and bulky		
	High sensitivity			
	Individual sensor is inexpensive	•		
Scanning laser doppler vibrometer	Noncontact sensing possible (nonintrusive)	Requires pre-marking of the target surface		
	High sensitivity	Expensive		
	More accurate than conventional sensors in obtaining deflection and mode shapes	Precise setup required		
	Does not affect structure due to lack of	Surface optical properties affect		
	mass load	readings		

V. CONCLUSION

This paper provides an over view of the types of faults which can occur in the wind turbine blade, present fault identification techniques and also the condition monitoring techniques. Brief classification of the Non-destructive techniques are also given in this paper. The brief explain of the most used process which is Ultrasonic method is provided. The most important thing in the fault identification is the sensors, the various types of the sensors are provided with their advantage and limitation. In present study, almost all aspects of damage detection in wind turbine blade is presented up to date.



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This review will help the researchers to differentiate between various techniques involved in damage detection of wind turbine blade and selection of feasible approach on application to a structure more likely wind turbine blade.

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