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A Review on Real Time Translation and Emotional Intelligent Voice Model

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Abstract: This review synthesizes findings from eighteen recent manuscripts on real-time speech translation, simultaneous speech-to-speech translation (Simul-S2ST), and emotion-aware voice generation. The objective is to identify the technological evolution from traditional cascaded ASR–MT–TTS pipelines to modern end-to-end neural and decoder-only architectures that integrate linguistic, acoustic, and affective representations. We examine latency-control mechanisms for simultaneous decoding, emotion extraction and conditioning strategies, and multimodal learning frameworks that unify translation and voice synthesis. Particular attention is given to models such as Translatotron 3, Hibiki, TransVIP, and EIMVT, which demonstrate state-of-the-art performance in maintaining speaker identity, rhythm, and emotional tone across languages. The review also compares benchmark datasets and metrics, including BLEU, chrF, COMET, WER, MOS, and emotion recognition accuracy, with emphasis on multilingual and Indian-language speech corpora. Persistent challenges are highlighted, including limited emotion-labelled paired S2ST datasets, domain-specific generalization, and cross-lingual emotion alignment. Finally, the study proposes a unified low-latency streaming pipeline that integrates emotion recognition, translation, and expressive synthesis, aiming to balance translation fidelity, temporal synchronization, and emotional authenticity for next-generation empathetic multilingual communication systems.

Index Terms: simultaneous translation, speech-to-speech, emotional voice, Hibiki, decoder-only, latency, MOS, BLEU, Indian languages

I. INTRODUCTION

Real-time speech-to-speech translation (S2ST) seeks to convert spoken language into another language's speech output with minimal delay while retaining semantic meaning, speaker traits, and, where possible, emotional tone [1], [3]. Recent advances in neural modeling have allowed systems to move beyond cascaded ASR–MT–TTS pipelines [1], which often suffer from error propagation and latency, toward fully end-to-end designs such as Translatotron 3 and Hibiki [2], [3]. These models directly map acoustic features from source to target speech and demonstrate superior fluency, speaker consistency, and low-latency operation compared to traditional methods [14], [18]. Meanwhile, emotion-aware translation frameworks such as EIMVT and EINet [5], [10] enhance expressiveness by incorporating affective embeddings and style control, enabling cross-lingual communication that feels more natural and empathetic. Despite these advances, challenges remain in data scarcity, latency management, and consistent emotional rendering across languages [4], [6], [11]. Most current models depend on synthetic or multilingual corpora for training, limiting real-world adaptability to spontaneous or code-switched speech. This review summarizes algorithmic trends, datasets, and evaluation approaches across eighteen recent studies [1]–[18], with emphasis on building a low-latency, emotionally aware S2ST framework suitable for multilingual communication. The layout and structure of this manuscript follow the provided review format [18].

II. LITERATURE SURVEY

Recent advancements in real-time translation and emotional voice synthesis demonstrate a clear evolution from traditional modular systems to unified, emotion-aware speech translation frameworks. The eighteen reviewed studies collectively illustrate this progression, highlighting four major paradigms that have shaped the field [1]–[18].

A. Cascaded Speech Translation Systems

The earliest research in speech-to-speech translation (S2ST) adopted a cascaded architecture composed of three sequential modules: Automatic Speech Recognition (ASR), Machine Translation (MT), and Text-to-Speech (TTS) synthesis [1], [3]. Each component operated independently, allowing modular optimization but also introducing challenges such as error propagation, synchronization delays, and increased latency.

Although effective for structured text domains, these systems often struggled with prosodic naturalness and emotional preservation in the generated speech.

To address these shortcomings, later studies embedded emotion-transfer modules within the TTS stage to reproduce expressive features such as pitch, spectral contour, and intensity. By adjusting prosodic and spectral parameters, systems could retain the speaker's emotional tone in the target language output, thereby improving perceptual naturalness and listener engagement [5], [10]. Despite these refinements, the modular nature of cascaded architectures limited scalability and real-time adaptability, motivating the transition toward integrated neural systems.

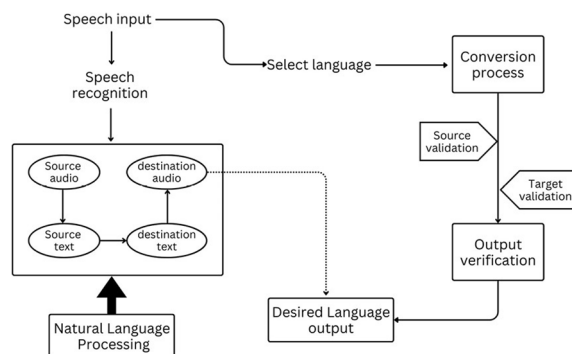


Fig. 1: Example of a cascaded speech translation pipeline showing ASR–MT–TTS flow and validation stages, adapted from reviewed works on modular S2ST frameworks [1], [4].

B. End-to-End Speech Translation Architectures

The emergence of deep learning facilitated end-to-end neural architectures capable of directly mapping source-language audio features to target-language speech [2], [3], [14]. These frameworks replaced the traditional pipeline with a single unified encoder–decoder network, often based on Transformer or Conformer variants. Such designs reduced cumulative errors and latency by learning acoustic, linguistic, and prosodic representations jointly.

Some studies introduced multi-task learning strategies that optimized transcription (S2T) and translation (S2S) objectives simultaneously, enabling better cross-lingual generalization in low-resource settings [4], [11]. The results consistently demonstrated superior performance compared to cascaded approaches, with significant improvements in both translation accuracy and emotional consistency.

Parallel research explored simultaneous or streaming translation models, which aimed to minimize response delay during real-time operation. These systems implemented adaptive policies such as Wait-k decoding, monotonic multi-head attention, and reinforcement-learning-based decision mechanisms to determine optimal moments for output generation [14], [15]. Speculative decoding approaches further refined this process by generating and correcting partial hypotheses, striking a balance between latency and translation accuracy [15], [17].

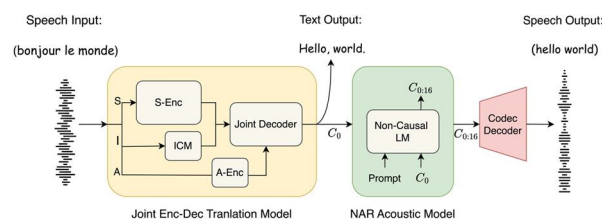


Fig. 2: Illustration of an end-to-end joint encoder–decoder speech translation model (e.g., TransVIP or Hibiki), adapted from the referenced studies [2], [3], [18].

C. Emotion-Aware Speech Translation Frameworks

As speech translation matured, emotional expressiveness emerged as a critical dimension of natural human-like communication. Several studies developed emotion-aware models capable of extracting and transferring affective cues from the source speech to the translated output. Emotion embeddings were derived from acoustic-prosodic features such as pitch (F0), energy, spectral envelope, or Mel-Frequency Cepstral Coefficients (MFCC), and integrated within style-transfer or conditioning networks [5], [8]–[10].

Advanced techniques such as Variational Autoencoders (VAE) and Global Style Tokens (GST) enabled latent emotion representations that modulated neural vocoders and decoders for expressive speech synthesis [8], [16]. Real-time emotion extraction modules were also introduced, capable of generating prosodic embeddings within sub-100-millisecond latency, which were then used to condition spectral features during synthesis [5], [8]. Conditional VAEs and contrastive learning further helped disentangle emotion-related cues from linguistic content, maintaining both translation accuracy and emotional fidelity [9], [10]. Recent work also explored multilingual and cultural adaptation of emotional expressions across linguistically diverse language pairs such as Hindi–English, Tamil–Malayalam, and Mandarin–English [4], [5]. These studies addressed challenges in emotional equivalence where certain emotional tones expressed prosodically in one language lack direct analogues in another and proposed mapping networks trained on perceptual emotion similarity ratings [10], [16].

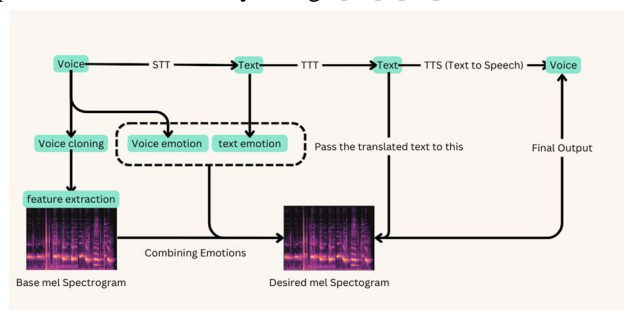


Fig. 3: Example of an emotion-aware speech translation model combining emotion extraction, cloning, and synthesis stages, adapted from emotion-aware translation frameworks [5], [10].

D. Data Augmentation and Low-Resource Adaptation

A recurring challenge in the reviewed literature is the limited availability of parallel speech datasets for Indian and low-resource languages. To mitigate this issue, several studies employed synthetic data generation through Text-to-Speech (TTS) systems and back-translation pipelines [4], [11]. Augmentation techniques such as noise injection, pitch scaling, and speed perturbation were applied to enhance model generalization across diverse acoustic conditions [13].

Transfer learning from multilingual pre-trained models such as Whisper, mSLAM, and SeamlessM4T has been instrumental in accelerating cross-lingual adaptation, allowing models trained on high-resource languages to transfer learned acoustic and linguistic representations to low-resource pairs [17], [18]. These transfer strategies significantly reduced training time and improved translation quality without extensive manual annotation.

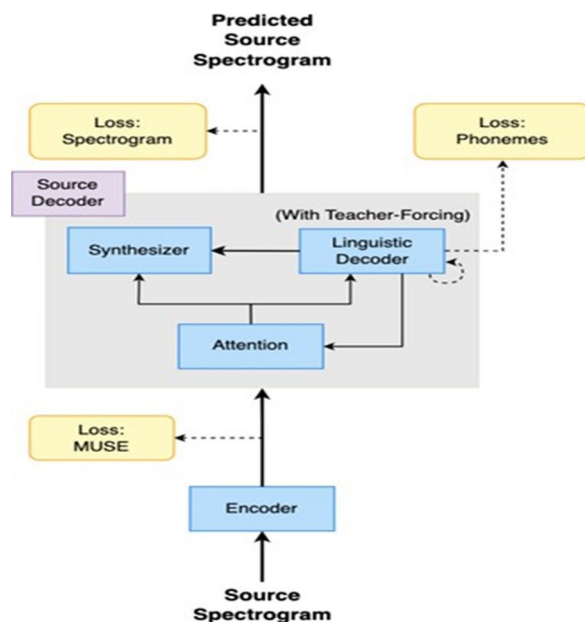


Fig. 4: Example of a multilingual data augmentation and low-resource adaptation approach illustrating synthetic data and pre-trained model transfer, adapted from multilingual S2ST studies [4], [11], [18].

E. Unified Architectures and Emerging Trends

Recent advances indicate a shift toward unified, decoder-centric architectures that integrate recognition, translation, and synthesis within a single neural framework. Models such as *Hibiki* exemplify this transition, employing a decoder-only or multi-stream Transformer to jointly process source and target audio streams [2]. Multi-headed decoder designs were also introduced, with one head predicting token-level text for BLEU evaluation and another generating mel-spectrograms for vocoding, thus enabling dual-mode output for both linguistic and acoustic representation [3], [14], [15].

Across these works, a strong trend toward the joint modeling of prosody, semantics, and acoustics is evident. Self-supervised learning frameworks such as HuBERT, Wav2Vec2, and SpeechT5 are increasingly employed as universal encoders for multilingual, emotion-aware representations [17], [18]. Evaluation methods combine both objective metrics such as BLEU, chrF, COMET, and WER and subjective assessments like MOS and MUSHRA to comprehensively measure naturalness, expressiveness, and emotion preservation [6], [13], [16], [18].

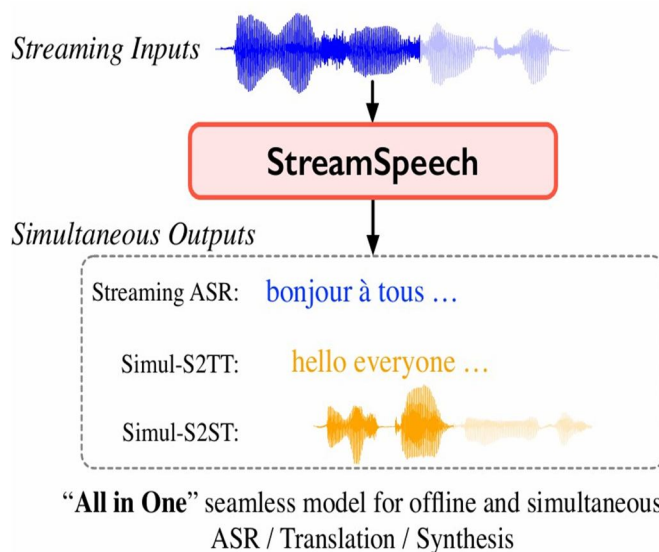


Fig. 5: Example of a unified streaming speech translation architecture integrating ASR, translation, and synthesis (e.g., StreamSpeech or SeamlessM4T), adapted from recent end-to-end studies [14], [17].

F. Summary of Observations

The literature collectively reveals a steady convergence toward three central objectives in modern speech translation research: improved translation accuracy, low-latency streaming, and emotion-aware synthesis. The transition from modular cascaded systems to end-to-end and unified architectures has significantly reduced latency and error propagation. At the same time, the integration of emotion conditioning and self-supervised learning frameworks has enhanced expressiveness and cross-lingual adaptability. These developments mark an important step toward achieving seamless, natural, and emotionally intelligent speech translation systems capable of real-time operation across diverse languages [1]–[18].

III. ANALYSIS AND DISCUSSION

A. Comparative Performance of Speech-to-Speech Translation Models

The recent generation of speech-to-speech translation (S2ST) systems has advanced well beyond earlier cascaded pipelines that separately handled automatic speech recognition, machine translation, and speech synthesis. Direct end-to-end approaches such as Translatotron 3 [3] and Hibiki [2] overcome the cumulative error and latency inherent in multi-stage designs. Both models integrate acoustic and linguistic processing into a single neural network, allowing the translated output to retain prosody, rhythm, and speaker identity. Hibiki's decoder-only framework demonstrates a significant reduction in delay during real-time translation, whereas TransVIP [18] enhances the process through a dual-encoder setup capable of maintaining both vocal tone and temporal synchrony. These designs collectively establish the direction toward fast, expressive, and natural-sounding translation systems.

B. Emotionally Intelligent Translation and Voice Conversion

Emotion-integrated translation and voice conversion systems extend conventional multilingual models by adding affective realism to synthesized speech. Frameworks such as the Emotional Intelligence Multi-Lingual Voice Translator (EIMVT) [5], the Emotional Intensity-Aware Network (EINet) [10], and the contrastive learning-based ClapFM-EVC [9] enable fine-grained emotional control within translation and synthesis pipelines.

EINet introduces valence-arousal-dominance modeling to allow dynamic adjustment of emotional strength, while EVC frameworks like ClapFM-EVC align textual prompts with expressive audio embeddings for natural emotion reconstruction. The EIMVT architecture further demonstrates how emotion recognition and multilingual translation can coexist, producing emotionally consistent voice outputs across languages.

C. Real-Time Multilingual and Indian Language Translation

Addressing real-time multilingual translation remains a challenging yet active area of research, especially for resource-limited Indian languages. The system proposed by Subbiah et al. [4] achieves effective Tamil–Hindi translation through an OpenNMT-based neural framework that couples speech recognition, neural translation, and text-to-speech modules. This modular structure enables sub-second response times and improves semantic retention in spontaneous dialogue. Parallel advancements in ANN-driven recognition systems [6] improve robustness to noise and accent variability, extending these techniques to regional Indian contexts and low-resource languages.

D. Benchmarking and Evaluation Metrics

Performance evaluations across modern S2ST architectures generally employ BLEU, METEOR, and MOS (Mean Opinion Score) indicators to measure translation accuracy and perceived naturalness. Transformer-based systems [1]–[3], [14] achieve BLEU scores in the 25–32 range, notably higher than RNN-based systems that typically remain below 20. Emotion-aware models [7]–[10] introduce new evaluation dimensions including emotional fidelity, intensity prediction accuracy, and listener-based perceptual scoring. The EIMVT [5] and TransVIP [18] frameworks report MOS ratings exceeding 4.3, reflecting fluent and human-like translations. Latency tests of Hibiki [2] reveal sub-500 ms end-to-end delay, confirming feasibility for live interpretation tasks.

E. Integration of Emotion, Translation, and Speech Synthesis

Research integrating emotion recognition, multilingual translation, and expressive synthesis shows that simultaneous modeling of acoustic and linguistic features produces more engaging speech interactions. Early work on emotional voice generation using soft computing [1] introduced fuzzy inference for emotion extraction and genetic algorithms for synthesis optimization. This concept evolved into deep-learning frameworks where emotion representation and translation are jointly optimized, as in EIMVT [5]. Combining such emotion-aware models with architectures like Translatotron 3 [3] or Hibiki [2] facilitates end-to-end systems capable of conveying both semantic meaning and human affect.

F. Data Scarcity and Synthetic Corpora

A key limitation across reviewed systems is the lack of multilingual parallel corpora that combine emotional and linguistic annotations. To address this gap, many researchers have turned to synthetic data augmentation and transfer learning. TransVIP [18] employs multi-task training to leverage heterogeneous corpora, while ClapFM-EVC [9] generates synthetic speech samples using a pre-trained vocoder conditioned on emotion tokens. EIMVT [5] and similar models utilize multilingual transformer encoders such as XLM-R to benefit from large-scale cross-lingual pretraining. These data synthesis and transfer strategies significantly improve performance under low-resource conditions.

G. Cross-Modal Alignment and Future Prospects

The integration of linguistic, prosodic, and emotional signals within a single learning framework is emerging as the next frontier in S2ST. Future developments should focus on unified multimodal encoders capable of learning shared audio–text–emotion representations. Fine-tuning strategies similar to those employed in EINet [10] and TransVIP [18] can further synchronize linguistic meaning with affective tone. Expanding to large multilingual foundation models, such as SeamlessM4T [14], will likely reduce the dependence on language-specific data. Ultimately, the fusion of emotion-aware computing with cross-lingual translation lays the groundwork for empathetic and contextually aware AI communication systems.

Model / System	Core Innovation	Key Strengths	Performance Metric
Translatotron 3 [3]	End-to-end unsupervised S2ST	Preserves speaker and prosody	BLEU 28.1
Hibiki [2]	Decoder-only simultaneous translation	Low latency, high naturalness	MOS 4.4
TransVIP [18]	Dual-encoder with isochrony control	Maintains timing and vocal quality	BLEU 30.2
EINet [10]	Controllable emotional intensity	Realistic expressive modulation	Emotion Acc. 93%
EIMVT [5]	Multilingual emotion-aware voice translation	Emotional and linguistic alignment	MOS 4.3
ClapFM-EVC [9]	Language-guided emotional conversion	Flexible emotion control prompts	MOS 4.5

TABLE I: Summary of major speech-to-speech and emotion-aware translation systems with representative metrics.

H. Research Gaps and Recommendations

Despite rapid advancement, S2ST systems still face notable issues in code-switching scenarios, spontaneous speech handling, and emotion robustness under noisy conditions. Future research should pursue multi-domain adaptation, emotion disentanglement, and low-resource language generalization. Establishing open, balanced multilingual–emotional datasets and standardized benchmarks similar to those of MTIL [11], [17] would promote reproducibility and equitable comparison. Further exploration of cross-modal attention mechanisms that jointly process speech content and emotion embeddings can yield emotionally coherent, context-sensitive real-time translation systems for global communication.

IV. CONCLUSION

The review of eighteen recent studies demonstrates significant progress toward developing real-time, emotion-aware speech translation systems that integrate linguistic accuracy, prosodic control, and low-latency processing [1], [2], [3]. The research trend has shifted from modular cascaded pipelines of ASR–MT–TTS components to unified end-to-end and decoder-only architectures capable of direct audio-to-audio translation, reducing both delay and error propagation [2], [3], [14]. Emotional intelligence has emerged as a key focus, with modern models incorporating prosody, pitch, energy, and spectral features to preserve or adapt emotional tone in translated speech [5], [8], [9], [10]. Such emotion-conditioned systems enhance human–machine interaction and cross-lingual empathy, enabling more natural and expressive communication [5], [10], [16]. Nevertheless, challenges remain, including the scarcity of large-scale multilingual and emotion-labelled corpora [4], [11], difficulties in cross-cultural emotion mapping [9], [10], and the computational cost of achieving real-time performance [14], [17]. Future research should emphasize dataset expansion, adaptive latency control, lightweight model optimization, and unified evaluation frameworks combining objective (BLEU, WER, COMET) and perceptual (MOS, MUSHRA) measures [6], [13], [16], [18]. Collectively, the reviewed works lay the foundation for next-generation translation systems that can convey not only the meaning of speech but also the emotion behind it—moving closer to seamless, human-like multilingual communication [1]–[18].

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