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Adaptive Honking System for Smart Cities Using IOT

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Abstract: This project has an aim to control the horn volume in cities and also in restricted area as such schools, parks, hospitals, old age homes, college, government offices and in speed limited areas etc. Some peoples are driving vehicles in a high speed and create noise of horn of vehicle. So the police are not able to monitor all those things. Driver does control the speed of vehicle at places. This paper provides a way for how to control the speed of vehicle and control the noise of horn without harming others. This project has an aim to control noise of horn automatically. The speed of any vehicles will be detected using accelerometer if the speed of vehicle is exceed in honking zone then the buzzer can buzz and get alert to driver about . cities and also in restricted area as such schools, parks, hospitals, old age homes, college, government offices and in speed limited areas etc. Nowadays in a fast moving world all the peoples are not have self-control. Controls are taken automatically by the use of electronic system. In this project we use GPS for indicating the nearby honking zone. Speed is measured by the help of accelerometer in the vehicle. The controller compares the speed. If it exceeds the limited speed the pizzobuzzer buzz and alerts the driver and controls taken automatically by driver and when vehicle is near at honking zone the switch can automatically decrease the volume of horn if it on. In this way our smart honking zone for smart cities project will be perform.
Keywords: Speed control, inter-vehicular communication, honking, Arduino, switch, GPS, Pizzobuzzer, noise control.

I. INTRODUCTION

Current accidents are primarily caused by rash driving and over speeding on roads, which are increasing year to year due to more vehicles on the road. The government has taken several steps to prevent this issue, but it is not enough. Most manufacturers have developed laser-based control systems, but their cost is too high. To control these things in a simple manner, the current speed will be monitored by the separate module or the use of an ultrasonic sensor that sends information to the controller. The controller compares both speeds and the driver does not decrease the speed automatically, but the driver still operates it manually and exceeds the limited speed. The increase in vehicle pollution has caused disruptions, and in some areas, such as central cities, hospitals, and schools, honking is prohibited by law or regulation. There are many traffic signals in various areas to notify drivers not to operate horns, and local governments issue permanent or temporary regulations for honking operations. However, some drivers ignore these signs or do not know about these regulations, leading them to operate horns in a wrong way.

There is always a conscious effort to reduce speed in honking zones and avoid anger among residents. The annoyance level of traffic speed may be personal, but the community is highly sensitive to traffic noise, especially honking by vehicles. L10 is a measure of daily exposure to traffic speed and provides an indication of how much the preceding traffic noise will affect the exposed residents. According to WHO, an adverse effect of speed is a change in the morothoralogy and physiology, resulting in impairment of functional capacity.

II. DESIGN ISSUES

Many researchers have contributed to this field. Various combinations of existing technologies have been used

1) "Run-Off-Road" accidents cause tens of thousands of serious injuries and thousands of highway deaths annually. Everything is responsible, including easy driver inattention, weariness, emotionlessness, and intoxicated driving. Simple sensors that are implanted with features like speed control, vehicle security, and automatic crash warning can be installed inside cars to encourage the development of effective road safety systems. During this effort, the following features are proposed: Automatic collision notice that notifies the victim's relative, Vehicle security is implemented to avoid theft, speed control modifies speed-indistinct zones, horn control forbids honking in prohibited areas, and red light control ensures that the vehicle doesn't breach signals.[1].[1]

2) The ultrasonic sensor described in this work is prepared to measure the distance from the bottom of specific spots on an automobile. Based on the measurement of an ultrasonic pulse's time of flight, which is reflected by the bottom, the sensor operates. A threshold comparator is used to obtain reflected pulses that are easily observable through a limited optimization technique. This approach, which considers the ultrasonic transducers' frequency response, makes it possible to acquire a sub-wavelength detection. The sensor is capable of self-adapting to various settings in order to provide the simplest results. It is composed solely of inexpensive components, making it suitable for initial automobile equipment in many cases.[2]

3) Due The rapidly growing number of vehicles on the road in recent years has led to a significant increase in traffic, which has prohibited noise pollution and made it more difficult for law enforcement to supervise vehicles. This study proposes the design of SHARP, an on-board equipment that applies a soundless horn, a traffic noise reduction mechanism for cars, and a remote watcher to help the civil force observe the vehicles remotely with an improved hit ratio of vehicles on the black list. For implementation, the suggested concept combines image processing and intersegment vehicle communication technology. The intended on-board gear is intended for four-wheelers, and a standard SHARP system consists of a camera, CPU, GPS, and DSRC transmitter. GPS device and an LCD display.[3]

III. PROBLEM STATEMENT

The ever developing times of ailments because of tempo of vehicle every physical and highbrow affords the direst need for a sustainable and an economically possible solution. The affordability and the overall performance of the solution system have to be optimized. The module moreover includes the provision of avoidance of accidents taking place because of immoderate tempo of vehicle. Mostly during the , the immoderate tempo will create an entire lot of noise pollution occurs that motives infection to the overall public nearby and people dwelling in residential areas, faculties and hospitals, antique age homes and government offices. The immoderate tempo of vehicle is may be reason of unstable accidents. The incapacity of the cause pressure to pay interest the buzzer is because of the immoderate tempo of the vehicle. Integrating with the accelerometer system of the vehicle, vehicle that routinely pauses buzzer system and allows the buzzer to be heard resulting in avoidance of avenue accidents. The affordability and the overall performance of the solution system have to be optimized. Mostly during the , the immoderate quantity of horn will create an entire lot of noise pollution occurs that motives infection to the overall public nearby and people dwelling in residential areas, faculties and hospitals, antique age homes and government offices.

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IV. METHODOLOGY

The proposed methodology aims to address the issue of excessive noise pollution caused by vehicle horns in urban areas and restricted zones such as schools, parks, hospitals, old age homes, colleges, government offices, and speed-limited areas. The system design will integrate GPS technology to identify and indicate nearby honking zones and incorporate accelerometers in vehicles to accurately measure vehicle speed. Data collection and processing will involve continuous monitoring of vehicle speed using the accelerometer and identifying the vehicle's location through GPS to determine if it's in a honking-restricted zone. An automated control mechanism will be implemented to trigger alerts if the vehicle exceeds the speed limit within a honking zone, coupled with an automatic volume adjustment feature to reduce horn volume near these restricted areas. Drivers will be alerted through visual indicators on the dashboard and audible alerts via a buzzer. A user-friendly interface will be provided for drivers to adjust settings or receive notifications. Continuous monitoring and feedback collection will be integral to assessing the system's effectiveness and making necessary improvements, aiming to promote responsible driving behavior, reduce unnecessary honking, and contribute to a quieter and safer urban environment.
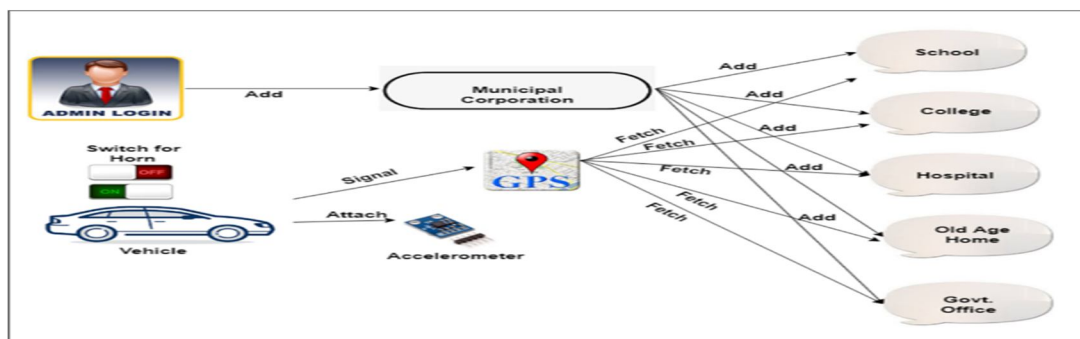

Fig.1 Proposed System

V. PROPOSED SYSTEM

A. Hardware Requirement

1) Processor i3: An Intel i3 processor, typically found in entry-level computers, providing basic performance for everyday tasks like web browsing and office work.

2) Hard Disk 5 GB: Storage device capable of holding up to 5 gigabytes of data, suitable for basic file storage needs but limited for modern software and multimedia.

3) RAM 1 GB: Random Access Memory with a capacity of 1 gigabyte, used by the computer to temporarily store data for quick access, suitable for light multitasking and basic applications.

4) Arduino V 1.8: An open-source electronics platform popular for creating interactive projects, version 1.8 likely refers to the software IDE used for programming Arduino boards.

5) GPS NEO-6M: A compact GPS module commonly used in electronics projects to provide accurate location data, featuring low power consumption and easy integration.

6) Switch (Horn) 5V: A simple electronic switch powered by 5 volts, typically used to control a horn or other devices in electrical circuits.

7) Buzzer 5V: An audible signalling device powered by 5 volts, commonly used in electronic projects for generating tones or alert sounds.

8) Accelerometer: A sensor capable of measuring acceleration forces, commonly used in electronic devices to detect motion, tilt, and vibration.
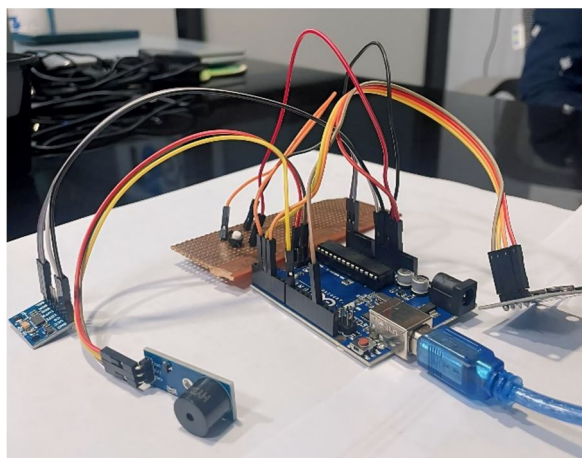

Fig.2: Hardware model

B. Software Requirement

1) Operating System: Windows XP and later versions - A computer operating system developed by Microsoft, supporting various software and hardware configurations for running applications and managing system resources.

2) Front End: HTML, CSS, Bootstrap - Technologies used for creating the user interface and designing the layout of web applications. HTML is for structuring content, CSS for styling elements, and Bootstrap for responsive design and pre-designed components.

3) Programming Language: Java - A widely-used programming language known for its platform independence and object-oriented approach, commonly used for developing Android applications within the Android Studio environment.

4) Algorithm: Eclat - Eclat algorithm, typically used for association rule mining, isn't directly applied to finding honking zones. However, it could be adapted or integrated into a broader data mining or machine learning approach aimed at identifying areas where honking is prevalent. By analyzing various factors such as traffic patterns, road conditions, and urban density, alongside data collected from sensors or traffic cameras, one could potentially infer regions where honking is more frequent. Integrating Eclat into such a system might help in discovering patterns or associations related to honking behavior within specific zones.

a) *Admin:* Admin can add the municipal corporation and view the honking zones which are included by the municipal corporation on GPS. He also view and delete the of municipal corporation and also view all details and data of others which is included by the municipal corporation.
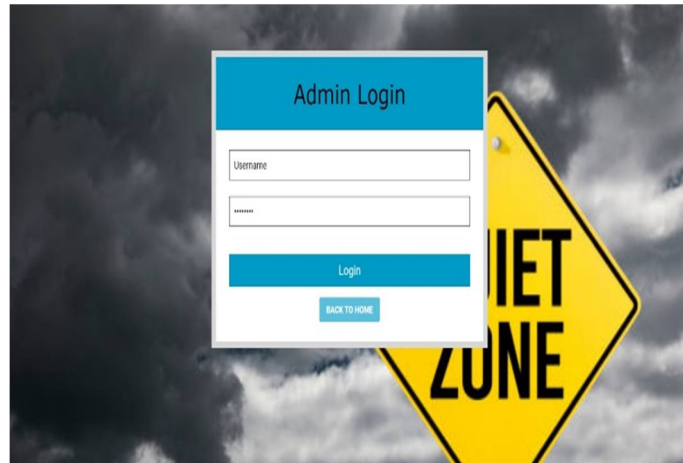
Fig.3: Admin Login page

b) *Municipal Corporation:* In our system the municipal corporation can add the honking zones like hospital, school, college, and old age home and government offices in cities as a honking zone with their longitude, latitude, Name, Type, and other description and decide the speed level of the vehicle which is travel from near the honking zone.
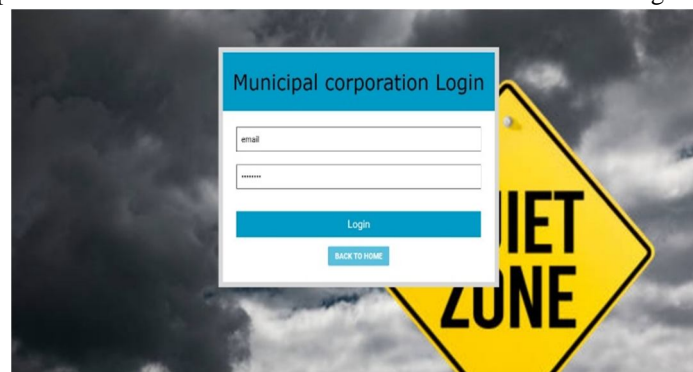

Fig.4: Municipal Login Page

System: In this web application when any car or vehicle goes from any honking zone the accelerometer can track the current speed limit of that vehicle. This accelerometer can built in the vehicle which is note the speed of vehicle during honking zone which is declare and saved on GPS by municipal corporation, if the detected speed of vehicle is greater than the speed which is allowed in honking area then the pizzobuzzer will buzz and get alert to driver to drive slowly in honking zone area. It also check the horn of vehicle if it on then the in-built switch press action will automatically decrease the noise level of the horn and keep safe and noise pollution free drive.

Fig.5: Web View

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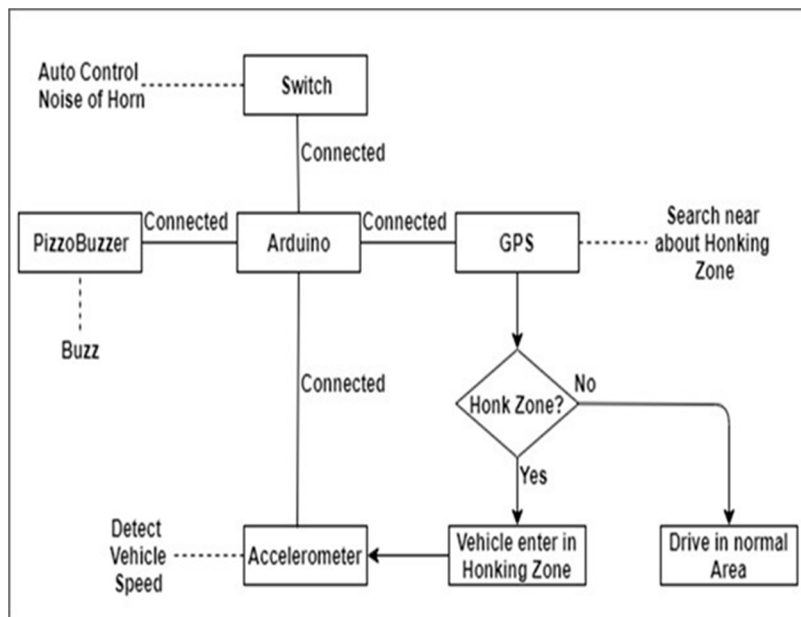Volume 12 Issue IV Apr 2024- Available at www.ijraset.com

Fig.6: System Architecture

VI. ALGORITHM

The ECLAT (Equivalence Class Transformation) algorithm is commonly used for frequent itemset mining in data mining. However, for a smart honking system using IoT in Java, you might want to consider a different approach that involves sensor data, event handling, and communication with IoT devices.

Pseudocode for Smart Honking System

PSEUDO CODE:

```
function ECLAT(database, minSupport):
 frequentItemSets = { }
 for each item in database:
 for each pair of items in item:
 if isFrequent({pair}, database, minSupport):
 frequentItemSets[{pair}] = support({pair}, database)
 return frequentItemSets
 function isFrequent(itemSet, database, minSupport):
 count = 0
 for each transaction in database:
 if containsItems(transaction, itemSet):
  count++
 return count >= minSupport
 function support(itemSet, database):
   count = 0
 for each transaction in database:
   if containsItems(transaction, itemSet):
 count++
 return count
 function containsItems(transaction, itemSet):
 for each item in itemSet:
 if item not in transaction:
 return False
 return True
```

VII. RESULT

Fig 7 : Added Municipal Corporation
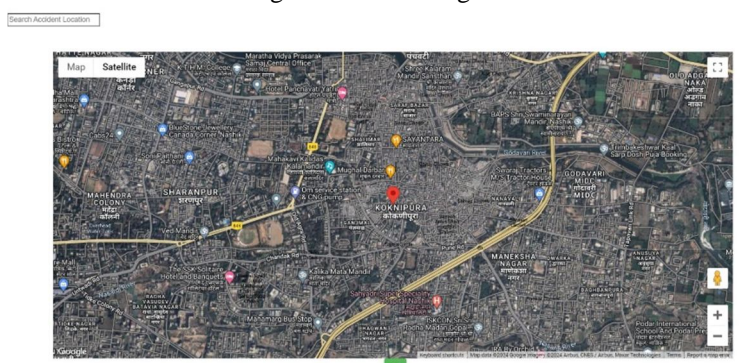

Fig.8: Add Honking Area

Fig.9: Map view For Longitude and latitude

VIII. CONCLUSION

The accidents that are caused due to loud music inside the vehicle, which inhibits the ability of the driver to alert mitigate by this system. In this paper we developed a new design to control the speed of the vehicle. In normal driving mode, we can expect other vehicles interfering nearby and possibly blocking or attenuating RF signals. In this aspect, we are going to use GPS location for restricted areas. Noise pollution seems to be a general problem, but when seen through global perspective it is a major issue. When honking unnecessarily is reduced it results in a peaceful environment and less stress for the daily travelers. Travelling is a part of day to day life for every human, so when noise due to unnecessary honking is eliminated humans will be able to sleep, concentrate and improvise their memory efficiently. Therefore, with this initiative overall stress is reduced and a peaceful journey will begin.

IX. FUTURE SCOPE

Creating a smart honking zone with a speed breaker detector has the potential for various applications and benefits in the future. As self-driving cars become more prevalent, smart honking zones can enhance communication between vehicles and the infrastructure, improving overall road safety. The speed breaker detector can be extended to monitor traffic flow and congestion, providing valuable data for traffic management and optimization.

The technology can be integrated into broader smart city frameworks, enabling more efficient transportation and contributing to overall urban development. Smart honking zones can be linked to eco-friendly transportation incentives, encouraging the use of electric or hybrid vehicles in certain areas. The system can be designed to recognize emergency vehicles and prioritize their passage through certain zones, improving response times during emergencies. As technology continues to advance, the scope for smart honking zones with speed breaker detectors is likely to expand, offering innovative solutions for safer and more efficient transportation systems.

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