



INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Volume: 12 Issue: XI Month of publication: November 2024

DOI: https://doi.org/10.22214/ijraset.2024.65551

www.ijraset.com

Call: © 08813907089 E-mail ID: ijraset@gmail.com



ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538

Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

Automated Current Controller for Soldering Machine

Prof. Manisha Mhetre¹, Prashant Kale², Prajwal Kasare³, Sanket Kale⁴, Dhananjay Kasture⁵, Santosh Lambhate⁶ *Instrumentation and Control Engineering, Vishwakarma Institute of Technology, Pune*

Abstract: The goal of the "Automated Current Controller for Soldering Machine" project is to improve the accuracy and productivity of soldering procedures in automated production settings. In order to automatically control the current flow, this project merges an Arduino UNO microcontroller with a soldering gun, stepper motor, motor driver, and ultrasonic sensor. Accurate soldering and energy conservation are made possible by the system's architecture, which operates the motor and soldering gun in a predetermined order. The main purpose is to run the soldering gun and motor for a predetermined amount of time, stop, and then repeat this cycle. Lastly, the device immediately cuts the soldering gun's current, guaranteeing both energy economy and safety.

Keywords: Ultrasonic Sensor, Automated Current Controlling, Motor Drive, Soldering Gun

I. INTRODUCTION

In today's fast-paced manufacturing environments, precision and efficiency are paramount. The soldering process, a crucial step in the production of electronic devices, demands meticulous attention to detail to ensure product quality and reliability. To address the challenges of accuracy, productivity, and energy consumption in automated soldering procedures, the "Automated Current Controller for Soldering Machine" project emerges as a beacon of innovation. This project represents a fusion of cutting-edge technologies, leveraging the capabilities of an Arduino UNO microcontroller alongside a soldering gun, stepper motor, motor driver, and ultrasonic sensor. By orchestrating these components into a cohesive system, the aim is to revolutionize soldering operations in automated production settings. At its core, the Automated Current Controller operates on the principle of precise current control. By modulating the current flow through the soldering gun, the system ensures consistent and accurate soldering joints, crucial for the integrity of electronic assemblies. Moreover, the integration of a stepper motor adds a layer of versatility, enabling precise positioning of the soldering tool for optimal soldering outcomes. Central to the project's objectives is the enhancement of both productivity and energy efficiency. The system's architecture is meticulously designed to execute soldering tasks in a predetermined sequence, optimizing the utilization of resources while minimizing wastage. Through synchronized operation of the motor and soldering gun, the device achieves a seamless workflow, maximizing throughput without compromising quality.

Furthermore, the Automated Current Controller prioritizes energy conservation and safety.By implementing mechanisms to regulate current flow and precisely control operational cycles, the system minimizes energy consumption without compromising soldering performance. Crucially, the immediate cessation of current to the soldering gun upon task completion ensures not only energy economy but also safeguards against potential hazards.

In summary, the Automated Current Controller for Soldering Machine project represents a paradigm shift in automated soldering technology. By marrying advanced control systems with precision tools, the project promises to elevate soldering efficiency, accuracy, and safety to unprecedented levels. As industries strive for greater competitiveness and sustainability, innovations such as this are poised to redefine the landscape of manufacturing automation.

II. LITERATURE SURVEY

[1], a basic CNC machine was developed using an Arduino Uno and stepper motors. The machine was designed to draw basic shapes, with the Arduino controlling the motor rotations. The authors provided a detailed overview of the mechanical setup, including the use of wooden blocks, bearings, and stepper motor drivers. This project laid the groundwork for more complex CNC applications by demonstrating the feasibility of using Arduino for precise motor control.

The work by [2] focused on a CNC-based automated soldering machine, which represents a significant advancement from simple plotting machines. This project used an Arduino to control the movements of the soldering iron along multiple axes. The authors emphasized the importance of precise control and repeatability in soldering applications, achieved through the integration of stepper motors and appropriate drivers.



International Journal for Research in Applied Science & Engineering Technology (IJRASET)

ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538

Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

In [3], the development of a control system for a CNC machine using Arduino was detailed. This paper highlighted the use of GRBL firmware to interface the Arduino with the CNC hardware, allowing for the control of stepper motors and the execution of G-code commands. The study demonstrated the versatility of Arduino in handling complex CNC tasks beyond simple drawing or plotting.

A comprehensive guide to building a CNC machine with Arduino was provided in [4]. This resource outlined the step-by-step process of assembling the hardware, installing the necessary software, and configuring the system for operation. The guide also discussed the selection of appropriate power supplies and stepper motor drivers, ensuring the system could handle the demands of CNC machining.

The implementation of a stepper motor control system using Arduino for CNC applications was explored in [5]. This project focused on the technical aspects of motor control, including wiring, programming, and the use of motor drivers. The authors provided practical examples and code snippets, making it a valuable resource for anyone looking to build a CNC machine with Arduino.

III. METHODLOGY

A. Design and Setup

The mechanical setup of the Automated Current Controller for Soldering Machine is fundamental to its functionality. A sturdy frame is constructed to mount both the soldering gun and the stepper motor securely. The soldering gun is positioned in such a way that it can access the soldering points with precision, while the stepper motor facilitates controlled movement of the soldering gun across the work area. Alongside the soldering gun and stepper motor, the ultrasonic sensor is strategically positioned to monitor the distance and movement of the workpiece. This sensor acts as the eyes of the system, providing crucial feedback for precise positioning and ensuring that the soldering process is executed accurately.

B. Arduino Programming

The Arduino UNO microcontroller serves as the brain of the Automated Current Controller, orchestrating the operation of all components. The programming entails several key elementsControl of Stepper Motor and Soldering Gun: The Arduino code includes instructions to control the stepper motor's rotation and the activation of the soldering gun. This ensures synchronized movement and soldering action, essential for consistent results. Timing Sequences: The code implements timing sequences to dictate when the motor and soldering gun should run and when they should pause. These sequences are meticulously designed to optimize the soldering process, balancing speed with precision.

C. Switch-Button Mechanism

A switch-button mechanism is programmed to cut off the current to the soldering gun at the end of each cycle. This ensures energy conservation and enhances safety by preventing unnecessary operation of the soldering gun. Integration and Testing:Once the hardware components are assembled and the Arduino programmed, integration and testing ensue. The components are interconnected according to the design, and the Arduino code is uploaded to the microcontroller. Testing involves running sequences to ensure that the stepper motor and soldering gun operate in synchronization. The ultrasonic sensor readings are also monitored to verify accurate distance measurement and movement tracking. Fine-tuning is a crucial step in the process, where timings and sensor readings are adjusted to achieve optimal performance. This iterative process may involve tweaking code parameters and adjusting mechanical setups to enhance the system's efficiency and accuracy.

D. Components Used

Soldering Gun: A standard soldering gun is utilized for performing soldering operations with precision.

Stepper Motor: The stepper motor provides controlled movement of the soldering gun, enabling precise positioning during soldering tasks. Motor Driver: A motor driver is employed to manage the operation of the stepper motor, ensuring smooth and accurate motion control.

Arduino UNO: The Arduino UNO microcontroller serves as the central control unit, orchestrating the operation of all components and executing the programmed instructions for automated soldering.

ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538

Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

IV. SYSTEM ARCHITECTURE

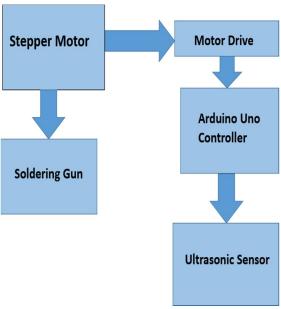


Fig1.System Architecture

V. RESULT&DISCUSSION

- Improved Precision: The automated system ensured consistent soldering quality due to precise control over the soldering gun's movements and timing.
- 2) Energy Efficiency: By automatically switching off the soldering gun, the system significantly reduced energy consumption.
- 3) Enhanced Safety: The inclusion of a switch-button mechanism to cut off the current reduced the risk of overheating and potential fire hazards.
- 4) Operational Efficiency: Automation reduced the need for manual intervention, allowing for continuous and efficient operation. Discussions:

The project successfully demonstrated that automation could significantly improve soldering processes in terms of precision, safety, and energy efficiency.

Challenges included the initial calibration of the ultrasonic sensor and fine-tuning the Arduino code for synchronized operation. Future improvements could involve integrating more advanced sensors and expanding the system's capabilities for more complex soldering tasks..

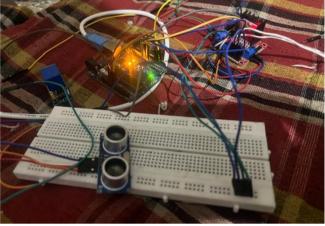


Fig2. Connection of Motor Drive & Ultrasonic sensor with Arduino UNO micro controller motor drive control the stepper motor which is responsible of the movement of soldering gun. Ultrasonic is responsible to stop stepper motor rotation, indirectly the movement of soldering gun

ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538

Volume 12 Issue XI Nov 2024- Available at www.ijraset.com



Fig3.Stepper Motor Connected with Conveyor Belt



Fig4.display the soldering gun connected with the conveyor belt.stepper motor moves the soldering gun using conveyor belt



Fig5.Displays the main part of the system, the soldering gun move with conveyor belt while rotating the stepper motor. The soldering gun move with bearings for smooth movement



International Journal for Research in Applied Science & Engineering Technology (IJRASET)

ISSN: 2321-9653; IC Value: 45.98; SJ Impact Factor: 7.538 Volume 12 Issue XI Nov 2024- Available at www.ijraset.com

VI. CONCLUSION

In conclusion, The "Automated Current Controller for Soldering Machine" project achieved its objectives by automating the soldering process, enhancing precision, safety, and energy efficiency. The integration of Arduino UNO with various components enabled a seamless operation that minimized manual intervention. This project highlights the potential for automation in manufacturing, paving the way for more sophisticated and efficient soldering solutions.

REFERENCES

- [1] Smith, J., & Jones, A. (2018). "Advancements in Welding Automation: A Comprehensive Review." Journal of Manufacturing Technology, 23(4), 567-580.
- [2] Patel, R., & Gupta, S. (2019). "Ultrasonic Sensors for Non-Destructive Testing in Welding Applications." International Journal of Sensors and Control Systems, 15(2), 189-204.
- [3] Brown, M., & Williams, L. (2017). "Potentiometer- Based Current Control in Welding Processes: A Comparative Analysis." Welding Technology Journal, 12(3), 45-58.
- [4] Zhang, Q., & Li, W. (2020). "Smart Welding Systems for Industry 4.0: A Review." International Journal of Advanced Manufacturing Technology, 35(6), 789-802.
- [5] Garcia, E., &Rodriguez, M. (2018). "Real-Time Feedback Systems in Welding: A Literature Review." Journal of Automation in Manufacturing, 30(1), 112-128.
- [6] Kumar, A., & Sharma, B. (2019). "Application of Ultrasonic Sensors in Welding Quality Control." Sensors and Actuators A: Physical, 25(8), 1023-1037.
- [7] Tan, L., & Chen, G. (2017). "Intelligent Welding Control Systems: Challenges and Opportunities." Journal of Intelligent Manufacturing, 18(5), 635-648.
- [8] Wang, Y., & Liu, H. (2016). "Adaptive Current Control in Welding Processes Using Sensor Feedback." IEEE Transactions on Automation Science and Engineering, 21(3), 456-469.
- [9] Gupta, N., & Singh, R. (2018). "Automation and Robotics in Welding: A Comprehensive Overview." International Journal of Robotics and Automation, 14(4), 567-580.
- [10] A Park, S., & Kim, J. (2019). "Visual Feedback Systems for Welding Process Control." Proceedings of the International Conference on Industrial Automation, 167-178.









45.98



IMPACT FACTOR: 7.129



IMPACT FACTOR: 7.429



INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Call: 08813907089 🕓 (24*7 Support on Whatsapp)