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Design of SensoBot

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Abstract:

- ***SensoBotisasmartrobotdesignedformotionand object detection.***
- ***UtilizesIRsensorsandmotionsensors.***
- ***ControlledusinganArduinomicrocontroller.***
- ***Displaysoutputandstatusonadigitaldisplay.***
- ***Suitable for automation, security, and educational purposes.***

I. INTRODUCTION

1) SensoBotenhancesautomationandintelligentsystems.
2) Sensorsdetectenvironmentalchangesandobjects.
3) Arduinoprovidesaneasyplatformforroboticscontrol.
4) SensoBotcombinessensorsandmicrocontrollerforreal- time response.
5) Emphasisonlow-costandflexibledesign.

II. PROPOSED SYSTEM

TheSensoBotisdesignedasacompactandefficientrobot that uses infrared (IR) sensors, motion sensors, and an Arduino microcontroller to detect objects and movementin its surroundings. The system architecture consists of the following key components:

1) IRSensor(InfraredSensor):

- Function: Detectsobstaclesornearbyobjectsbyemitting and receiving infrared light.
- Working: WhenanobjectcomesinfrontoftheIRsensor, the emitted IR light reflects back and is detected by the receiver.
- UseinSensoBot: Helpsinidentifyingobjectsinclose proximity, useful for obstacle avoidance or object Detection.

2) PIRMotionSensor(PassiveInfraredSensor):

- Function:Detectsmotionbysensinginfraredradiation (heat) from humans or animals.
- Working:Whenawarmbody(likeahuman)movesinits range, the PIR sensor detects the change and sends a digitalsignal.
- UseinSensoBot:Enablesthebottodetecthumanoranimalpresenceinitssurroundings,makingitsuitablefor surveillance or automation.

3) Arduino Microcontroller(e.g.,ArduinoUNO):

- Function:Actsasthecentralprocessingunit.
- Working: Takes input from sensors, processes the data usingprogrammedlogic,andcontrolsoutputdeviceslike the display.
- UseinSensoBot:Receivesreal-timedatafromIRandPIR sensors, processes it, and executes appropriate actions such as displaying messages or triggering alarms.

4) Display Module(e.g.,LCDorOLED):

- Function:Providesvisualfeedbacktotheuser.
- Working:Showsmessagessuchas“ObjectDetected,” “Motion Detected,” or “No Movement.”
- UseinSensoBot:Enhancesuserinteractionbydisplaying the bot’s current status and sensor output.

5) Power Supply:

- Function:powerstheentirecircuit.
- Types:Rechargeablebatterypack,9Vbattery,orUSB power from a computer or adapter.
- UseinSensoBot:Ensuresportabilityanduninterrupted operation.

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6) Optional Add-Ons:

- Buzzer/Alarm:Canbeactivatedduringmotiondetection.
- MotorDriver&Wheels:Canbeaddedtomakethebot mobile.
- LEDIndicators:Forvisualsignals(blinkingondetection).

7) IntegrationFlow:

- IRandPIRsensorsmonitorthesurroundings.
- Upondetection,theysendsignalstoArduino.
- Arduinointerpretsthesignalsandsendsoutputtothe display.
- Optionalactionslikebuzzersoundormovementcanbe triggered.
- Thesystemresetsandcontinuesscanning.

8) Working Mechanism

- IRsensordetectsobjectsusingreflectedinfraredrays.
- PIRsensorsensesmotionusingheat(human/animal presence).
- Arduinocollectsandprocessessensordata. If motion/object detected:
- Arduinoactivatesoutputdisplay.
- Optional:soundalertormovementaction.





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III. FEATURES&ADVANTAGES

A. Features

1) Real-timeobjectandmotiondetection.
2) Digitaldisplayforfeedback.
3) Simple,modular,andcompactdesign.
4) Arduino-basedprogrammingandcontrol.

B. Advantages

1) Low-costandenergy-efficient.
2) Easytobuildandmodify.
3) Suitableformultipleenvironments.
4) Enhancesautomationandsecurity

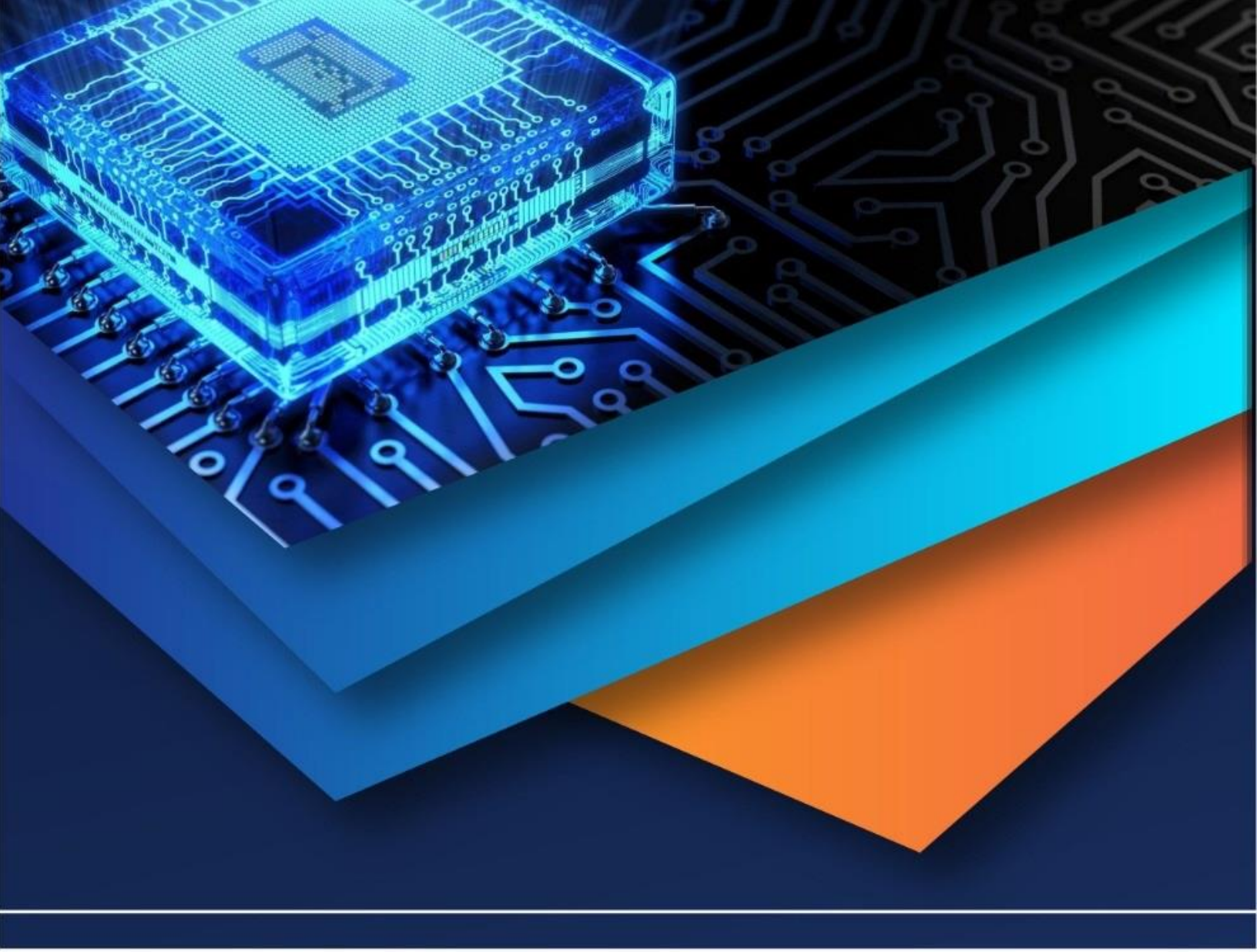
IV. APPLICATIONS

1) Homeautomationandsecuritysystems.
2) Obstacledetectionforrobots.
3) Smartindustrialautomation.
4) Surveillanceandmonitoring systems.
5) Schoolandcollegeprojectmodels.

V. CONCLUSION

1) SensoBotisaneffectiveandaffordablerobotusingbasic sensors.
2) Idealforlearning,automation,andpractical applications.
3) CanbeenhancedwithIoT,camera,orwirelessfeatures.
4) Promotesinnovationinroboticsandsmartsystems.

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