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# Designing and Modelling of Wind Turbine Simulation Using MATLAB / SIMULINK

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**Abstract:** *The renewable energy, Malaysia hopes to lessen its reliance on oil and gas. Wind energy is one of the more promising renewable sources of electricity. Malaysia is situated in an area with low wind speeds, with an annual mean wind speed of 1.2-4.1 m/s, close to the equator. The northeast monsoon and the southwest monsoon are the two monsoon seasons that Malaysia experiences. While wind speeds during the northeast monsoon can approach 15 m/s, they can only reach 7 m/s during the southwest monsoon season. The potential for wind energy in Sarawak, Malaysia, has only received a limited amount of research and study. In this article, MATLAB/SIMULINK will be used for modelling and simulation of numerous wind energy conversion systems (WESC) utilizing different generators operating under the same conditions in order to analysis the generators' efficiency. Although ultimately all of them are equally efficient, PMSG has shown to be more efficient than SCIG and DFIG at lower wind speeds. SCIG, DFIG, and PMSG efficiency are, respectively, 66.25%, 69.38%, and 71.88% at the rated wind speed.*

**Keywords:** *Horizontal Axis Wind Turbine, Wind Energy, Induction generator, MATLAB Software.*

## I. INTRODUCTION

The kinetic energy of the wind is converted into the mechanical energy that turns the rotor blades of a wind turbine, which are connected to a low-speed shaft. This process is carried out by a wind turbine. After that, the mechanical energy will be transferred, with the help of a gearbox, into the high-speed shaft in order for the generator to be able to convert it into electrical energy [1]. Wind turbines with a horizontal axis revolve on an axis that is perpendicular to the direction in which the wind is blowing [2]. If the blades of the wind turbine are spun in such a way that they point in the direction that the wind is blowing, then it is possible to harness the power of the wind. In addition, HAWT often feature towers that are higher, which assists the turbine in meeting the challenges posed by a wind that is stronger. This is since the speed of the wind increases with height, and HAWT towers often have a greater altitude than average. It is feasible to extract the maximum amount of wind energy possible when employing wind turbines that have variable pitch angles. This is accomplished by adjusting the angle at which the blades rotate to either enhance or decrease the amount of power that is created by the wind turbine. Because of this, it is now feasible to harvest the greatest quantity of wind energy that is practicable. Because HAWT models provide more accurate results, we will concentrate our modeling and simulation efforts on those models for the whole of this work. The characteristics of a wind turbine that are most often seen are shown in figure 1.1 below. These are some of the most crucial things to think about while shopping for an ideal turbine, so keep them in mind. The cut-in speed is the minimal wind speed necessary to overcome the friction of the turbine blades and spin the blades. This is the speed at which the blades begin to rotate. This is the speed at which the blades start to revolve after the fan has been turned on. When traveling at this speed, the blades will start to spin in the opposite direction of a clockwise motion. The lowest wind speed at which the turbine can create the power output that is specified for its rating is referred to as the rated speed of the turbine. This is the minimum wind speed at which the turbine is able to generate the power output.

## II. CONVERSION WIND ENERGY SYSTEM

In order to generate mechanical energy, a wind energy conversion system, more often referred to as a WECS, is propelled by the force of the wind. After that, this kind of mechanical energy is transferred to an electrical generator so that it may be used in the process of producing electricity. The connection that can be made with a WECS is shown in figure 1.3. It is possible that the generator of the wind turbine is a permanent magnet synchronous generator (PMSG), a doubly fed induction generator, an induction generator, a synchronous generator, or one of the many alternative designs that are feasible. The wind energy that is collected by the wind turbine and used by the generator is what makes up the source of the electricity. The WECS makes use of a pulse width modulation converter in order to keep the spinning speed of the generator at the optimal level so that it may produce the most amount of power that is technically possible.

The electricity that is produced by the generator is sent into the grid by means of an inverter that is located on the side of the grid and a converter that is located on the side of the generator. Both devices are connected to each other through cables. Wind farms may be in a wide variety of environments, some of which include onshore, offshore, hilly terrain, and coastal locations. It is possible that the WECS DG may end up being the most important one in the not-too-distant future. This is something that can be expected to happen.

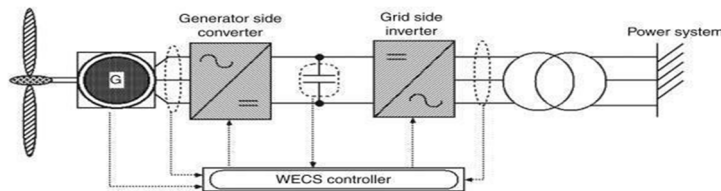


Fig:1- Wind Energy Conversion System.

Wind power is an alternative to the use of fossil fuels because it does not produce any emissions while it is functioning; it only requires a very small amount of land; it is abundant; it is renewable; it is widely scattered; it is clean; it is affordable; it is abundant; it is widely dispersed; it is clean; it is inexpensive; it is an alternative to the use of fossil fuels [14]. In general, the impacts on the environment are of far less concern than the problems that are caused by other traditional sources of electricity. The fluctuating wind speed causes the wind energy conversion system's output power to vary, which in turn has the potential to cause the frequency of the power grid to diverge in an unexpected way. Already, a sizeable amount of investigation has been carried out in the pursuit of finding a resolution to this issue in the not-too- distant future. The main data that was used for the 2013 edition of the World Wind Energy Report was gathered by an organization known as the World Wind Energy Association (WWEA). The global capacity for wind energy reached 318.5 GW at the end of 2013, which is an increase above the capacity of 282.2 GW that was reached in the previous year. There are now 103 nations throughout the world that allow the commercial use of wind power in some capacity. With a total capacity of 91.3 GW and a new capacity of 16 GW, China has retained its position as the most important participant in the worldwide wind industry.

### A. Wind Turbine

There is a chance that the HAWT market might be further subdivided into wind turbines that operate at fixed speeds and wind turbines that operate at variable speeds [7]. This is an extra possibility that may be pursued. For one of the wind turbines to be able to keep its speed consistent while it is operating, it is equipped with a component known as a squirrelcage induction generator, or SCIG for short. A wind turbine that has a speed that can be altered will always have the same rotational speed for its rotor, regardless of how quickly the wind is blowing. This is because of the speed's ability to be adjusted. This is because the pace may be adjusted. It is reliant on a variety of various elements, some of which include the frequency of the grid, the gear ratio, and the design of the generator.

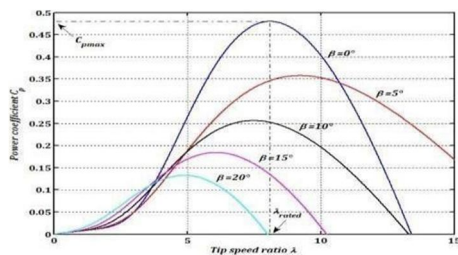


Fig:2- Power Coefficient Vs TSR for Wind Turbine.

### B. Generator

One might further subdivide the term "electric generator" into "asynchronous generator" and "synchronous generator." These two categories of generators are both capable of producing electrical current. The most important distinction between the two is that synchronous generators do not need the power supply from the grid in order to excite their windings, in contrast to asynchronous generators, which do require the power supply from the grid in order to excite their windings. This is the most significant difference between the two types of generators. This is the primary point of distinction between the two distinct varieties of generators. This distinction between the two types of generators is the more significant of the two.



Synchronous generators, on the other hand, do not need the power source that is supplied by the grid in order to excite the windings of their machines. Synchronous generators can achieve this without the grid's assistance. The low rotational speed of the turbine blades must be increased by the gearbox to the greater rotating speed of the rotor shaft before the turbine can fulfill the duties for which it was designed. Because of this, the generator is now able to accept power from the turbine. This came about as a direct result of the previous sentence.

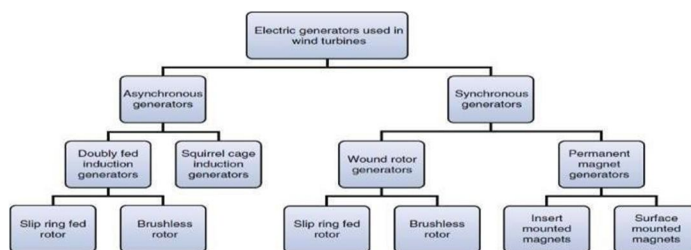


Fig:3-Types of Generators in WESC.

### C. Block Diagram Of A Wind Turbine

The hub that is located at the base of the turbine blades is the component that oversees dictating the orientation of the blades. The blades are attached to the central hub with the help of a rotating mechanism that consists of gears, a small electric motor, and either a hydraulic or mechanical system for producing rotational motion. This arrangement ensures that the blades remain securely attached to the hub. Control of the system may be attained either electrically or mechanically, depending on how the system was planned out in the first place. The relative speed of the wind is what decides which direction the blades will rotate when they are turned on their axis. Pitch control is the term that describes the approach in issue. It does this by ensuring that the blades of the wind turbine are aligned in the most efficient way possible in the direction that the wind is blowing in order to harvest the most amount of power possible from the wind.

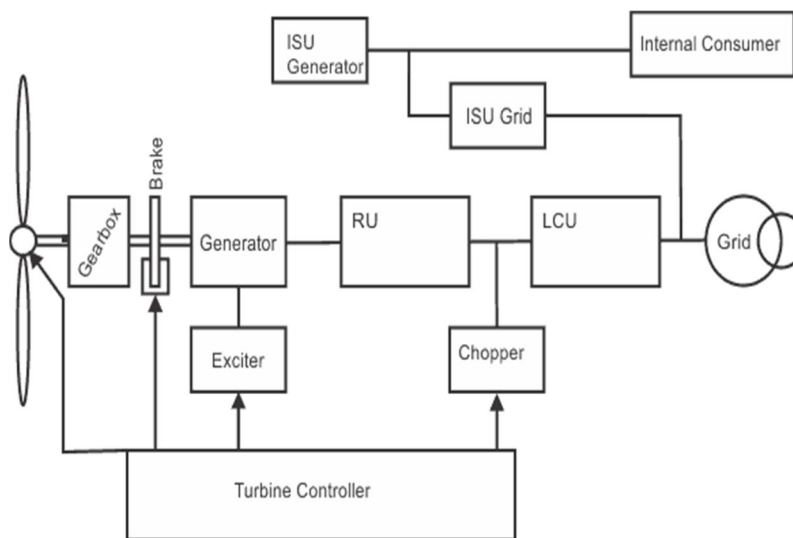


Fig:4-Block Diagram of a Wind Turbine.

### III. DOUBLY FED INDUCTION GENERATOR

Doubly fed induction generator (DFIG), which is receiving a growing amount of interest for applications that need power in the range of megawatts [13], is one solution. The windings on both the stator and the rotor of this generator are set up in a three-phase arrangement, which is why the generator is referred to as a three-phase device. After the rotor, the stator windings, and the back-to-back converters have been connected to the grid, it is the responsibility of the back-to-back converters to regulate the speed of the rotor. The grid will provide an electrical current that will excite the rotor windings, and the magnetic field that will be created by the rotor windings will revolve in time with the blades of the rotating turbine. This will be accomplished by the rotor windings. Alternating current will be produced because of the interaction between the revolving magnetic flux and the stator windings in an electric generator. This interaction will produce alternating current.

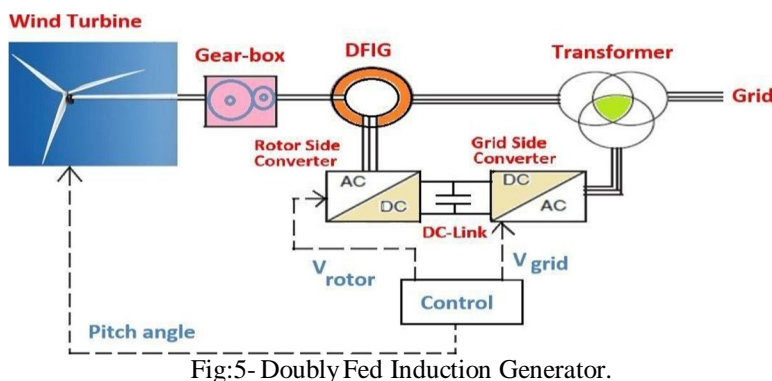


Fig:5- Doubly Fed Induction Generator.

Both the rotor's rotational speed and the frequency of the grid's rotation influence the rate at which the magnetic field of the stator rotates. It is important to condition the frequency of the grid signal that is operating on the rotor windings in order to keep the level of frequency that is being produced constant. This is done in order to maintain the current that is being created. This is done so that there is no variation in the frequency of the current that is being carried. A back-to-back converter is made up of its two individual components, which are known as a machine-side converter and a grid-side converter. A DC voltage connection connects these two converters to one another so that they may work together.

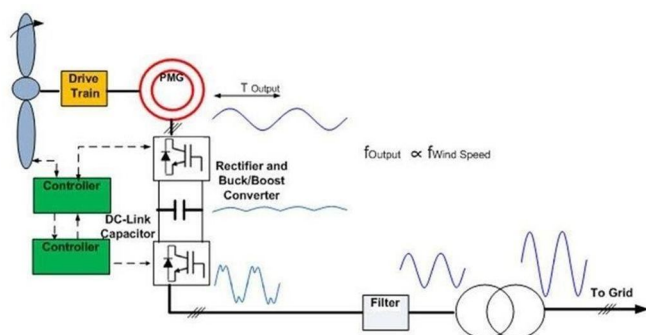


Fig:6- Permanent Magnet Synchronous Generator.

This effect is created by the wind turbine. One can achieve this objective by following the strategy described in the previous paragraph. The presentation of the PMSG wind turbine model that is shown here in figure 3.7 should provide for an enjoyable viewing experience for you. The fact that modern computers have a basic organizational framework is one of the key reasons that has led to the widespread usage of these machines. [Case in point:] [C]omputers have a fundamental organizational framework. Since the brushes, sliprings, and commutators of a WRSG are held in place by permanent magnets, disassembling and removing these components from the WRSG may be accomplished with relative ease. Disassembling a WRSG needs permanent magnets. This task may be completed in its entirety if one so chooses. As a result of this, the system's level of dependability will considerably increase, and as a direct consequence of this, it will become an alternative to the WRSG that is, in some circumstances, preferable. A PMSG's overall design must have both a rectifier and an inverter for the device to perform as intended when put into operation. This is because the PMSG is a generator with variable speed.

#### IV. MODELING OF WIND TURBINE

An example of this would be a wind turbine, which is a piece of technology that converts the kinetic energy provided by the wind into electrical energy. The rotor is one of the three primary components that come together to produce the overall system that is the wind turbine. The blades that are responsible for transforming the high-velocity wind energy into a lower-velocity rotational energy are housed inside this component. The generator is the third and final component of the system. The second component is known as the generator, and it is made up of an electrical generator in addition to all the control circuits and gears that are necessary to convert the low-speed rotation into electric power. This second component is referred to as the generator. The structure is the very final part of the generator, and it is responsible for housing all the earlier parts inside its own boundaries. This structure, which consists of the tower as well as the nacelle, is the component that brings the generator to its final form.

There are essentially two different types of wind turbines, and the distinction between the two is based on the axis that the machine revolves around. One may make a distinction between a horizontal axis and a vertical axis when they are contained inside it. There is a consensus among experts that wind turbines with a horizontal axis are more prevalent and ubiquitous in comparison to wind turbines with a vertical axis [1]. Wind energy may be harnessed and converted into usable forms of power via the use of a device called a wind turbine. Wind power generation is the term used to describe this process. The following equation demonstrates how the air density, power coefficient, air density, and turbine swept area are all elements that impact the total amount of energy that is collected from the wind:

$$P = 0.5 \times \rho \times C_p \times V^3 \times A \dots (1)$$

Where: P = Mechanical power in the moving air (Watt).

$\rho$  = Air density (kg/m<sup>3</sup>).

A = Area swept by the rotor blades (m<sup>2</sup>) V = Velocity of the air (m/s)

C<sub>p</sub> = Power coefficient.

Scientist Betz made the discovery that the greatest amount of power that can be extracted from the wind by using an ideal turbine rotor with an infinite number of blades under ideal conditions is 59.26% (or 0.5926 times) of the power that is present in the wind. This maximum amount of power can be taken from the wind by utilizing an ideal turbine rotor with an unlimited number of blades. The limit in question is referred to as the Betz limit. Due to the structural requirements and economical constraints involved, wind turbines typically feature either two or three rotor blades depending on the size of the turbine. As a direct result of this, the amount of power that they can gather is closer to being around half (0.5 times) of the total amount of power that is available to them. Tip speed ratio (TSR) of a wind turbine is defined as:

$$\lambda = (\Omega \times R) / V \dots (2)$$

Where:  $\Omega$  = Mechanical speed at the rotor shaft of the wind turbine (rad/s) R = Radius of the blade (m).

V = Velocity of the air (m/s).

The TSR, in addition to the blade pitch angle, which is represented by, is necessary in order to compute the rotor power coefficient, which is denoted by the symbol C<sub>p</sub>. This is because the TSR is directly proportional to the rotor power coefficient. The following is a list of the mathematical computations that may be done in order to determine the rotor power coefficient:

C<sub>p</sub> = (Extracted power) / (Power in wind) C<sub>p</sub> = P<sub>rotor</sub> / P<sub>wind</sub> ... (3) Equation 1 can be written as:

$$\text{Power} = 0.5 \times \rho \times C_p(\lambda, \beta) \times V^3 \times A$$

Wind turbines that are capable of running at changing speeds often come equipped with a device that is known as a pitch change mechanism (pitch angle control). This device allows the pitch angle of the blades to be varied in order to produce a more appropriate power coefficient profile [3, 4]. Wind turbines that are not capable of operating at varying speeds typically do not come equipped with this kind of device. The rotational speed of the turbine may be altered as a direct result of this feature of its design.

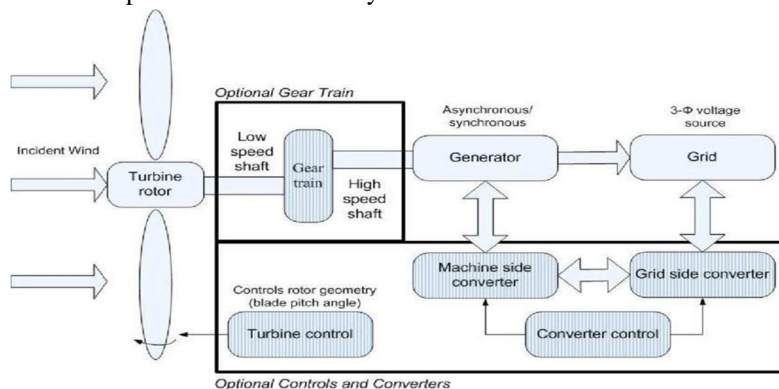


Fig:7- Modern Wind Turbine Diagram.

Wind turbines that can run at changing speeds often come equipped with a device that is known as a pitch change mechanism (pitch angle control). This device allows the pitch angle of the blades to be varied in order to produce a more appropriate power coefficient profile [3, 4]. Wind turbines that are not capable of operating at varying speeds typically do not come equipped with this kind of device. The rotational speed of the turbine may be altered as a direct result of this feature of its design.

## V. RESULT AND ANALYSIS

The wind turbine generator is the most important component of a wind turbine (WT) system since it is the component that is accountable for transforming the mechanical energy that is produced by the turbine into electrical energy. Most of the time, problems that occur with wind turbines are due to components in the generator being damaged in some way. As a direct result of this, the analysis of the generator model in wind turbines is developing into a subject of research that is becoming more important. This is because, in order to avoid problems with wind turbines, it is vital to be aware of the special attributes of the generator. The objective of this study is to construct a mathematical model of a generator that can easily be adjusted to account for any fault that may occur in the generator. This research will be used to conduct research on WT dynamic systems, and the goal of this study is to contribute to that research. The primary objective of this line of study is going to be the formulation of a mathematical model of a generator that is appropriate for implementation in wind turbines. This is a result of the fact that the most of the WT models that have been developed up to this point either include protection for intellectual property or are relatively straightforward in the generator modeling that they use. Both MATLAB and Simulink were used throughout the whole of the process of constructing the mathematical model of the wind turbine-based induction generator for the purpose of this project. The model of a wind turbine that was built includes not only an aerodynamic model but also a model of an induction generator and a drive train for the wind turbine that is based on a model with two masses. The construction of the induction generator was based on electrical equations that were arranged inside Park's reference system. The building of the model incorporates not just one but two distinct subsystems: a mechanical one and an electrical one. The suggested model of the wind turbine fitted with an induction generator was verified by means of a MATLAB software simulation of a wind farm fitted with a detailed model of a doubly-fed induction generator (DFIG).

### A. Methodology Of The Wind Turbine

With several simulations, we are going to present several distinct WECS in this part. The following building pieces are utilized to construct the simulation's portrayal of the wind speed, as seen in Figure 8. The modeling of the simulation will be done using these pieces. Between the time  $t = 1$  second and  $t = 10$  seconds, the speed of the wind is going to grow from a speed of 0 meters per second to a speed of 9 meters per second. This increase is going to take place. After  $t = 15$  seconds, it will then begin to raise its speed to 15 meters per second, having previously been at 9 meters per second. This will take place after the initial speed of 9 meters per second has been maintained.

Up until the time equals thirty seconds, there is not going to be any change at all in the speed of the wind. This simulation's goal is to investigate the performance of a variety of generators when subjected to three distinct levels of wind speed: 0 meters per second (the "zero wind speed" condition), 9 meters per second (the "base wind speed"), and wind speeds that are greater than the "rated wind speed." All these aspects are evaluated, including the apparent power, the apparent reactive power, the rotor speed, the mechanical torque, and the pitch angle. Measurements are taken, and records are kept. The actual power output, the rotor speed, and the pitch angle are all aspects of the wind turbine that will be the subject of conversation.

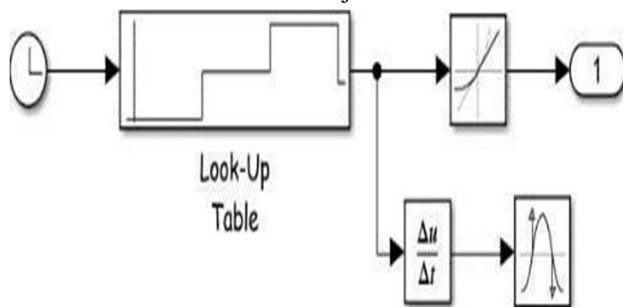


Fig:8-Simulation Model of Wind Turbine Generator.

### B. SCIG Wind Turbine

Figure :9 provides a visual representation of the modeled SCIG wind turbine that was created using SIMULINK. Together with the 30-kilometer transmission line, the 575V/25kV step-up transformer and the 25kV/120kV step-up transformer make it possible for the 1.5 MW induction generator to be directly connected to the power grid. We will be using the SIMULINK model of the wind turbine in order to offer the required quantity of mechanical torque for moving the rotor of the generator. After SCIG has transformed the mechanical torque into electrical power, that power will be delivered to the grid through the stator windings. The VI-measurement blocks are going to take readings of the voltage, current, active power, and reactive power.

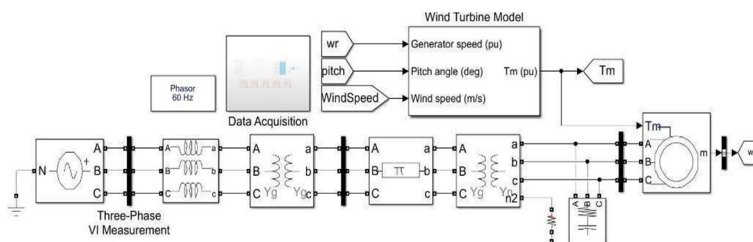


Fig:9-Simulink Model of SCIG Wind Turbine.

### C. DFIG Wind Turbine

Figure 10 presents a DFIG model that is quite comparable to the SCIG model. This comparison may be seen by comparing the two models. The sole difference between the two models is the way in which step-up transformers and power converters link the rotor windings of the DFIG type to the grid. This is the only difference between the two versions. Transformers are used so that a connection may be made between the stator windings and the grid of the power supply. Because there is no other source, the reactive power that is necessary to activate the generator stator will be drawn from the grid. This is because the grid is the only source that is now accessible. When a rectifier and an inverter are replaced inside of a universal bridge, the process of modeling a DFIG wind turbine is said to be complete.

The total number of components is now up to four as a result of this. After first converting the fluctuating AC electrical power that is produced into stable DC power with the help of a rectifier, the DC power will then be transformed back into AC electrical power with the assistance of an inverter. While the rectifier control system oversees determining the speed at which the generator spins, the inverter control system oversees controlling the amount of electricity that is sent out to the grid. Alternating current will be produced as a direct result of the interaction between the spinning magnetic flux and the stator windings of the generator. This will take place as a direct consequence of the interaction. Both the rotor's rotational speed and the frequency of the grid's rotation influence the rate at which the magnetic field of the stator rotates. It is important to condition the frequency of the grid signal that is operating on the rotor windings in order to keep the level of frequency that is being produced constant. This is done in order to maintain the current that is being created. This is done so that there is no variation in the frequency of the current that is being carried. A back-to-back converter is made up of its two individual components, which are known as a machine-side converter and a grid-side converter. A DC voltage connection connects these two converters to one another so that they may work together.

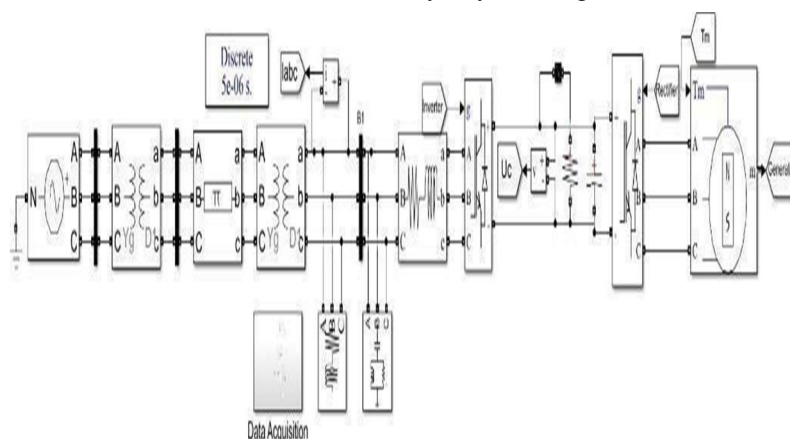


Fig:10-Simulink Model of DFIG Wind Turbine.

### D. PMSG SIMULINK Model in Wind Turbine

The PMSG SIMULINK model, which is fairly like the SCIG and can be seen in Figure 5.4, may be downloaded here. The fact that the generator in the PMSG model does not need a feed from the grid for its windings to be excited is the primary contrast that can be made between the two models. Because a PMSG is a wind turbine that may run at different speeds, it is required to include power converters. These speeds can range from very slow to very fast. In contrast, the stator windings will be directly linked to the grid via the use of a rectifier, an inverter, step-up transformers, and a transmission line that is thirty kilometers in length. The rotor windings will be excited by permanent magnets.





The grid will suffer considerable voltage disruptions because of this increase in the initial current. Because of this, a soft starter is necessary to regulate the high beginning current of the generator in order to reduce these voltage disturbances and guarantee that the grid continues to work in the proper way. This is because a lack of control over the high starting current might lead the generator to fail. As a direct consequence of the occurrence, the grid will be subject to major voltage disturbances on account of the rise in the initial current that it will be experiencing. DFIGs' windings, regardless of whether they are on the stator or the rotor, are simply linked to the grid in the same way. This is the case regardless of which side of the device they are on. Because of this, the generator may be managed with a greater degree of precision in terms of both its active and reactive power. This applies to both aspects of the generator's power. This is true for both the amount of electricity it generates and the amount of power it uses. At the absolute least, the power converter has the capacity to exercise some degree of control on the quantity of power that is generated by the DFIG. This is the case because of the power converter's ability to convert one kind of energy to another.

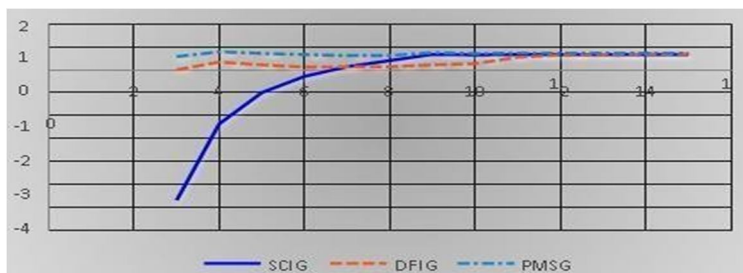


Fig:15-Efficiency of Generators.

The number of particles per unit area in the atmosphere, with  $A$  referring to the entire surface area that is covered by the rotor and  $v$  referring to the speed at which the air is traveling. If we proceed with the evaluation of the generator based on the presumption that the pitch controller will be engaged as soon as  $t = 15$  s, then we will be able to evaluate its performance up to that time. If the actual wind speed reaches a level that is greater than the wind speed that the sail was designed to withstand. The data on efficiency that was collected between  $t = 0$  s and  $t = 3$  s had to be excluded from the research since SCIG experiences a current spike during those times because it is directly coupled to the power grid and does not have a soft starter installed. This meant that the data could not be included in the study. Because of the dynamics of the circumstance, it was imperative that this be done. The SCIG will draw electricity from the grid during the intervals of time ranging from  $t = 3$  s to  $t = 7$  s in order to excite the windings in advance of the beginning of the generator's process of manufacturing energy. This will allow the windings to be excited in preparation for the beginning of the process. This will occur between the periods of  $t = 3$  s and  $t = 7$  s, inclusive. This sheds light on the factors that contribute to the generator's low efficiency rating, which was previously unknown to me.

## VI. CONCLUSION

Up to this moment, effective simulations of the SCIG, DFIG, and PMSG wind turbines' SIMULINK models have been carried out within the limitations of the restrictions imposed by this research project. When contrasted with variable-speed wind turbines that employ DFIG and PMSG, the structure of an SCIG turbine is a great deal simpler and much simpler to grasp. On the other hand, variable-speed generators provide a variety of advantages that fixed-speed generators do not have, including a higher level of reliability and overall efficiency. Even though all of them eventually reach the same level of efficiency, the simulation that was run indicated that PMSG is more efficient than SCIG and DFIG even when the wind speed is low. This was the case even though all of them eventually attain the same level of efficiency. This is the case regardless of whether all of them finally attain the same level of productivity.

The fact that they each finally reach the same degree of efficiency does not alter the fact that this continues to be the case even if it may seem like it should change. In a wind turbine, the kinetic energy of the wind is transformed into the mechanical energy that is required to spin the rotor blades, which are attached to a low-speed shaft. This operation is often carried out using a wind turbine. This is how the wind's kinetic energy is converted into usable electrical energy. After that, the gearbox will be used to transmit the mechanical energy into the high-speed shaft so that it may be converted into electrical energy by the generator [1]. After the preceding stage has been finished, we shall go on to the next one. Wind turbines with a horizontal axis revolve around an axis that is perpendicular to the direction in which the wind is flowing [2, 3]. It will be able to harness the power that is provided by the wind if the rotors are positioned in such a manner that they face in the direction that the wind is blowing. In addition, HAWT often includes towers that are taller, which helps the turbine to better combat a greater wind. This is one of the advantages of using HAWT.

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