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Development of Advance Railway Track Crack Detection System using IOT

Prof. Vedashree Rajderkar[1], Prajwal Shende[2], Pratik Ramteke[3], Sahil Humane[4]

[1]*Project Guide, Department of Electrical Engineering, G H Raisoni College of Engineering, Nagpur*
[2, 3, 4]*Students, Department of Electrical Engineering, G H Raisoni College of Engineering, Nagpur*

Abstract: Rail transport in India is at the forefront of providing the transport infrastructure wanted to meet the desires a quickly expanding economy. India today has the world's fourth largest rail network. Although terms of We have far exceeded international norms in terms of reliability and safety. The most difficult aspect of railway analysis is detecting faults in the structure. whether left unmanaged, they can be left astray and lose the proper path. The proposed gadget is suitable for rail transport to discover cracks in the tracks in advance and to prevent accidents. In this paper to use the crack sensor, this will be installed on the train engine. With this, if a certain cracok is found on the tracok the train starts to slow down and stop somewhere automatically and the exact location of the cracokay will be given to the control room. Secondly the following cause of accidents is prevented from two trains facing the same lane the use of the same sensors installed on the engine, while the sensor hears the same signal from another train and automatically applies the brakes and stops the train at a certain distance. A train diversion camakes use of several losses in train accidents.
Keywords: crack detection, railway, IR sensor , IOT module, Arduino Controller etc.

I.   INTRODUCTION

Due to the rapid development of rail structures, excessive-fast trains are being rail and utilised transport increasing every day.The majority of people commute by train. freight and passenger transport from one place to another. The railway line provides services such as excessive speed, low cost, friendly environment. these features can be done during power sessions. however According to the parts, deterioration damage in upper railway building. those deviations and other problems with the rail device such as poor maintenance, current railway monitoring faults from staff. Such flexibility and deterioration are timely and safety measures are more significant to rail system security.

To this problem we present in this project. To provide protection from rail damage due to cracks occurring in the tracokay. The IoT module will specify the exact location to which the message will be sent to the authorities. live feeds and data from the IoT module will be updated on the meant use of the wireless device. through using this technology, we will be able to prevent the loss of valuable existence or property.

II.   PROBLEM STATEMENT

Broken train speaks of Among world's the main source costly Rail is also risky. accidents. Considering the common occurrence, all of which are thought of in our own right, each three days there is more than one major demolition, continuously over 10 years. Accessible interventions in which cross-country fracture conflicts are disrupted do not help enough to understand the political, social and environmental consequences. In the current frame, whilst the tracok is unlocked, the frame is forced to go out and align the tracokay at unusual intervals. Normally, it will send a exclusive flag to the specialisting using the remote control module in case something stands out from the line. Separation is detected via IR sensors and the error flag is transmitted.

Figure 1. Railway Track Crack

A. Train Accident Statistics

Diagram ll shows variety end caused by train misadventure. could be seen in determine death toll increases each year. There is therefore a great need for a technical solution to the problem of train cracks.
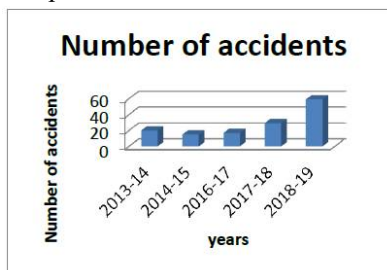

Diagram ll :- No. of accidents

III.   OBJECTIVE

Major objective discover gaps in the railway line and to decide whether there are any accidents on the tracks in order to avoidentity and prevent accidents. This type of model provides an ultrasonic sensor and IR sensor joint that responds to the precise position of the faulty track, as well as transmitting information to the IOT control room, so that abig apple incidents can be closed.

IV.   EXISTING SYSTEM

In the present machine, techniques such as visual inspection, video transmission, and magnetic area techniques can detect cracks in the railroad tracks. Physical examination is one of the first steps in which all the necessary parts will be scanned with the aid of hand. This procedure is commonly used in India, despite producing a very bad result. The camera is used to monitor the tracok while the content is being broadcast. In this process small cracks and a more expensive machine cannot be detected. The current passes through the railway line to detect errors in the current eddy path and the output outcomes are inaccurate. Manew york of these methods require a lot of processing power and a very long time, which makes the robot speed slow and uncomfortable.

Figure 3. Manual crack detection by human
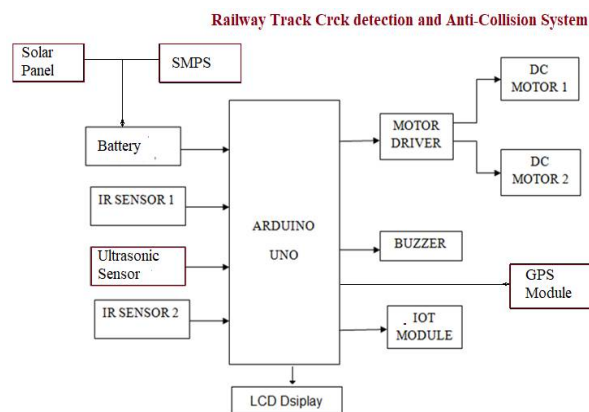
V.   PROPOSED METHODOLOGY
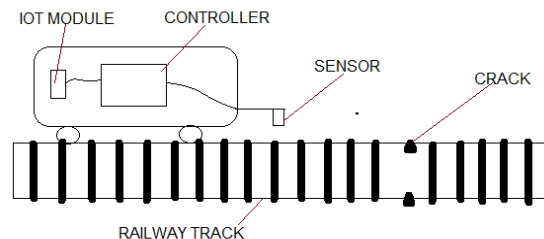
A. Figure

Diagram 4.

Diagram V. Structural Diagram

B. Working

In our task, there are sets of IR sensors mounted on both facets of the vehicle. This unit is used to show on / off the GSM transmitter unit within the event of a crack .

1) *At Normal Condition:* An IR transmitter sensor transmits infrared radiation with the help of a 555 IC timer circuit. those infrared radiation is detected via an IR receiver sensor. Transistors are used as a part of the amplifier. beneath normal circumstances the Transistor isn't OFF. At that point the transmission is CLOSED, in order that the car can move continuously.

2) *At Crack Condition:* In instances of break up transmission Infrared resistance for all opportunity because of continuously Infrared radiation . consequently. At factor the transfer start role. At factor, engine electricity deliver is disconnected and transformed to IoT unit. The IoT module is centered on the nearest station manager, in order that the alarm sign is given to the station supervisor.

3) *Anti-Collision System:* In recent years rail accidents occurred continuously. while railway move through matching lines meet, railway misadventure happen with other train and object. except them be traveling in the process of particular preservation due to extraordinary circumstances , those kind like incidents unable-to usually averted since Railway operator and certainty officers There isn't sufficient hours for act. This misadventure source straight or accidental harm persons or conditions, mostly while them require railway transfer fear, persons and risky and contamination material . This updation project is based on avoiding train collisions through android system integrated with ultrasonic inbuilt in the train.

C. Main Components and Description

1) *IR Sensor:* In our project the IR transmitter and receiver circuit are used to discover the crack of the train tune. couple alike sensors are utilised. Detector l :- single aspect as to educate tune. Detector ll:- the opposite facet the educate song Detector l or a pair of sensors are used to hit upon cracks inside the train tune and to provide control signal to the GSM transmission unit.

2) *Arduino:* Arduino is an open source computer and software organization, assignment and community of users who design and convey single-board microcontrollers and a microcontroller kit to construct a digital device and interactive talents that can make sense and manage gadgets in the digital international.

3) *IOT Module:* The internet of factors (IoT) is making changes and enhancing the manner we work and live. however, it's miles best possible with complete IoT solutions built on flexible wi-fi connectivity and longevity. Crack statistics is sent to a licensed man or woman the use of IoT.

4) *Motor Driver:* Drivers function a visual hyperlink among engines and manage circuits. Motor calls for a excessive modern-day fee even as the manage location operates at low modern signals. it's miles therefore the task of motorists to take a low present day manage signal and convert it right into a high cutting-edge signal that can drive the engine.

5) *D.C. Motor:* In our mission a permanent DC motor is used. Electricity powered machine be gadget that Electric conversion strength Mechanically inclined electricity. Its action is primarily based on the precept that after the incumbent driver is now positioned in a magnetic field, he receives a magnetic area whose route is given via Fleming's left hand rule.

6) *Ultrasonic sensor (HC-SR04):* A UT detector be gadget particularly operate UT detector signal for calculate gap on a thing. That protects against anti-collision collisions..

7) *GPS Modules (NEO-6M):* GPS modules have small CPUS or receiver which collect details straight through space station along particular broadcast station.

8) *Solar Panel (10w):* A solar-energy an assemblage as to solar panel arranged with structure as install. photovoltaic cell cause DC electric utilize daylight for origin power.

9) *Frame:* The frame is made p with MS steel materials. The visible device includes a battery, a automobile tire device.
10) *Railway Track:* The railway line is made of M.S.metallic material. The middle of the wheel is V-grooved, so that the car can circulate in a straight line.
11) *Battery*
substances: Lead-Acid Output Battery: 12 V
Output energy: 2 Ampere-Hour.

VI.   CALCULATION

A. *Selection of Electric Motor*
1) SPEED = 30 RPM D motor
2) VLT = 12 VLT RPM VOLTGE
3) WTT = 18 WATTS

B. *The motor's torq.*
1) (P X 60) / Torq. = 2 x (3.14) x N
2) Torq. = (18 x 60) ÷ (2 x 3.14 x 30)
3) Torq. = 5.72 NM Torq. = (5.72 x 10³) N-m
4) shafft made of ms or it acceptable shear stress = 42 Mpa
5) 5.72 x 103 = 3.14 x 42 x d 3 / 16 D = 8.85 mm Torq. = 3.14 x fs x d 3 / 16 D = 8.85 mm.
6) near standard. calculation is d = 9 mm.

C. *Equ. of Electric PWR*
1) PWR = I × v Where V = 12 W = 18 and I = 18/12=1.5
2) H.P. = .02414

D. *Calculating the Battery*
1) BH/I = 8 ah/420ma = 19 hours
2) determine curr. W = 18 w
3) V = 12v Curr. = ?
p = V x I 18 = 12 x I I = 18÷ 12 = 1.5
4) Use of an AMS batt. with 1.5 MS BH /I 8/1.5 = 5.3 hours

VII. CAD DESIGN

Figure. 6. Cad design

VIII. RESULTS AND DISCUSSION

The project "robot that detects teach track cracks" was designed in any such way that it designed the set up device with out using an IoT module. The project unveiled the vehicle area straight away after the discovery of a crack in the railway line and in the course of the discovery of boundaries. The device permits localization of acquisition the use of a base station network through Io module alerts and transfers vicinity to a small controller the controller assumes the area switch feature the usage of Io module resources.

1) The controller video display units the situations supplied and acts according with the code.
2) The controller enables the driver to operate and the engines to move at the music.
3) Then IoT is activated and sends the message to close by stations.
4) Sensors are activated and could always locate cracks or obstacles.
5) If a crack is detected, the robotic displays the message "cracked".
6) After the message is displayed the robot stops walking on the track.

The subsequent parent suggests the Crack Detected or impediment found on the Arduino show display screen,

Figure.8. i) Crack Detected   ii) Obstacle Detected

The following figure shows that SMS received on cellular telephones are inside the latitudinal and longitudinal areas where a crack or impediment is located.

7:40 PM

RAILWAY CRACK DETECTION ON LEFT WHEEL
BUZZER IS ON

7: 40 PM

RAILWAY CRACK DETECTION ON RIGHT WHEEL
BUZZER IS ON

7.41 PM
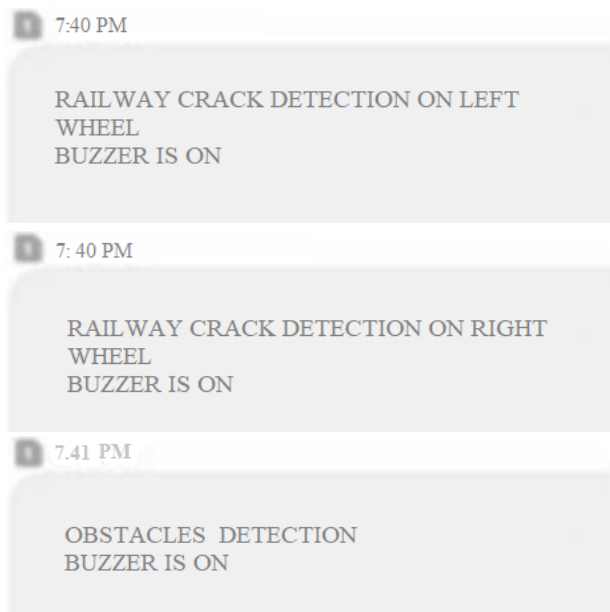
OBSTACLES DETECTION
BUZZER IS ON

Figure.9. Information Received in the mobile Phone

The proposed device introduces IoT-primarily based era, to prevent train injuries. An IoT module with a sensor tool hooked up at every quit of the train. whilst the teach starts off the tune, the signal breaks and a notification is given to the engine driving force and an emergency brake is applied.

IX. ADVANTAGE

1) Very green and friendly layout for the individual.
2) Espy to use.
3) Short capacity loss.
4) The situation auto may decided the usage of GPS.
5) Stumbling cracks use of IR impediment sensors
6) GPS tracking information based on GPS and GSM to send SMS
7) Keep away from the risks of single music.
8) A hit shape.
9) Works worldwide (GSM availability).

X. APPLICATION

It is miles which might be used in railway offerings to reduce accidents.

XI. CONCLUSION

The proposed Arduino-based totally detecting machine is primarily able to come across cracks in rails, in addition to small cracks without human intervention. The proposed system has many more blessings than conventional visible techniques. benefits include quicker availability and reporting facilities, decrease fees, lower electricity intake and plenty less testing time. similarly, the clean availability of additives and simplicity of vision makes the proposed system lots better to use on a large scale with little or no initial aid. As a result, it may draw efficiently and successfully underneath running situations. With this proposed version, we will avoid accidents due to road cracks, which helps us to keep extra lives. On this venture, we've designed a low-powered board and excessive-efficiency board that permits for excessive levels of rail safety to keep the teach from harm. and railway obstacles. The prototype looking model of the teach can without problems find cracks and obstacles in track. through the use of these functions in actual-time software, we have been capable of save you crashes in approximately 70%.

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