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Improved People Counting System Using Deep Learning

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Abstract: With the rapid rise in population, public areas such as malls, supermarkets, and transport hubs are becoming increasingly crowded. Businesses depending on customer footfall patterns require accurate data to optimize operations. To address this, we developed a people counting and tracking system that detects, tracks, and identifies individuals in real-time. The system uses Faster R-CNN for robust people detection, offering high accuracy even in dense environments. To ensure consistent monitoring, DeepSORT assigns unique IDs to each individual and tracks them across frames. Additionally, DeepFace is integrated for face recognition, enabling the system to match detected faces with previously registered identities. A face registration module (register_faces.py) allows webcam-based registration, making it user-friendly. The evaluation module (evaluate.py) computes key performance metrics such as Mean Absolute Error (MAE) and Root Mean Square Error (RMSE). The model was tested on a dataset comprising 2416 positive and 1218 negative image samples. It achieved a True Positive Rate (TPR) of 95.03%, a False Positive Rate (FPR) of 0.08%, and an overall accuracy of 97.08%. While the model performs well, challenges such as overlapping subjects, varying clothing, and lighting conditions may occasionally affect results.

This system provides a reliable and scalable solution for people counting, face tracking, and identity verification..

Keywords: People Counting, Faster R-CNN, DeepSORT, CNN.

I. INTRODUCTION

People counting system is designed to enhance business operations by providing accurate real-time monitoring of individuals in environments like retail stores, shopping malls, supermarkets, and intelligent transportation systems. The system uses MobileNet for object detection and a Centroid Tracker algorithm for tracking individuals from an overhead camera view. When the number of people crosses a predefined threshold, the system can trigger an alert notification.

Face recognition is integrated into the system using DeepFace, which identifies previously registered faces through a webcam-based face registration module. Evaluation of the model's performance is done using a script that calculates key metrics like MAE and RMSE.

In previous years, the first-generation devices used infrared sensors for the detection and counting of people. After that, the second-generation devices use thermal image sensors for detecting and counting people, and then the next to introduce the third-generation devices which use computer vision and video computing which is based on image processing for better accuracy results.

The development of this system follows the evolution of people counting technology. Initially, infrared sensors were used, followed by thermal imaging sensors in second-generation systems. Modern solutions now rely on computer vision and video processing for higher accuracy. This system supports advanced detection techniques using algorithms like YOLO (You Only Look Once), SSD (Single Shot Detection), and RGB-D (which combines RGB and depth data).

Depending on the setup, the system can operate with a Single-Camera Convolutional Neural Network (SCNN) or a Multi-Camera CNN (MCNN), the latter of which synchronizes frames from multiple sources to deliver comprehensive crowd analysis. These computer vision methods make it possible to detect and count people effectively from various overhead perspectives, meeting the challenges of real-time detection and object tracking in dynamic environments..

II. LITERATURE REVIEW

Some previous years, many image and video processing algorithms have been made for detecting people. Some of the examples are Haar Cascade, Convolutional Neural Networks (CNN), Single-shot detector (SSD), you only look once (YOLO) in computer vision and video computing generation [7][5]. YOLO algorithm has low recall it will not detect properly close objects because each grid has two bounding boxes only.

The infrared sensor is a first-generation technique, where an infrared beam line is parallel with the ground and counts when a person or object passes and breaks its beam [6]. The thermal sensor is a second-generation technique.

Where the sensor recognizes and captures infrared light which is emitted by the human body. After that, the computer vision and video computing algorithm are created for detection purposes. There is a wide range of methods for the detection purpose which gives great accuracy [9].

The author presents real-time system overhead view RGB-D (RGB plus depth) using a commodity depth camera which is installed in the main entrance gate, in this method the model firstly detects the head-shoulder of the passing person and extract the features of the head and shoulder and then make predictions [11]. The main purpose of this above deliberation that is most of the time overhead view person detection handcrafted features-based methods [12].

III. METHODOLOGY

In this project, Faster R-CNN is used for detecting people, and DeepSORT is utilized as the tracking algorithm. The system uses DeepFace for face recognition, identifying individuals whose faces have been registered using the python script, which supports webcam-based registration. For evaluation purposes, is used to calculate metrics such as MAE and RMSE.

The pipeline consists of three main phases: the setup phase, detection phase, and output phase. In the setup phase, the Faster R-CNN detection model is prepared and integrated with DeepSORT for tracking and DeepFace for face recognition. Individuals are registered through a webcam-based face registration script. During the detection phase, when a person enters the camera's field of view, Faster R-CNN detects them, and DeepSORT tracks their movements, assigning unique IDs to each individual. If a registered face is detected, DeepFace verifies the identity. In the output phase, the system counts the number of people detected and displays the count. If the count surpasses a predefined threshold, an alert or message is sent to the staff. This integrated approach utilizes standard deep learning and computer vision techniques to provide accurate and efficient people detection, tracking, and recognition..

A. Datasets

The dataset is the data that is used to train the algorithm and check the accuracy of the model by using the test set. In this model, the datasets are extracted from this website for training purposes and testing purposes

https://personal.ie.cuhk.edu.hk/downloads_mall_dataset.html In this system, the model has trained perfectly with train data and tested by the test data.



Example frame.

Figure: 1 Dataset image



An example of annotated frame.

Figure: 2 Training dataset image

B. Setupphase

In the setup phase, the detection model based on Faster R-CNN is prepared and integrated with DeepSORT for tracking and DeepFace for face recognition. Individuals are registered using the webcam-based face registration script.

The system begins by initializing the Faster R-CNN model, a robust and accurate deep learning-based object detector designed specifically for identifying people in images or video streams. Faster R-CNN operates in two stages: first, it generates region proposals using a Region Proposal Network (RPN), and then it classifies the proposals and refines their bounding boxes. This model is pre-trained on large datasets (e.g., COCO or Inria Person Dataset) to recognize human figures in various poses and lighting conditions. DeepSORT enhances basic SORT tracking by using deep learning-based feature extraction to maintain more stable identity tracking across frames. Each detected person is assigned a unique ID, which remains consistent as long as the person stays in the frame, even with slight occlusions or movement. This ID system is essential for maintaining accurate counts and linking detection results over time. A custom script is used to collect and register user faces through the webcam. The script activates the webcam, detects faces in real-time using OpenCV or a deep face detector, and prompts the user to input their name or ID.

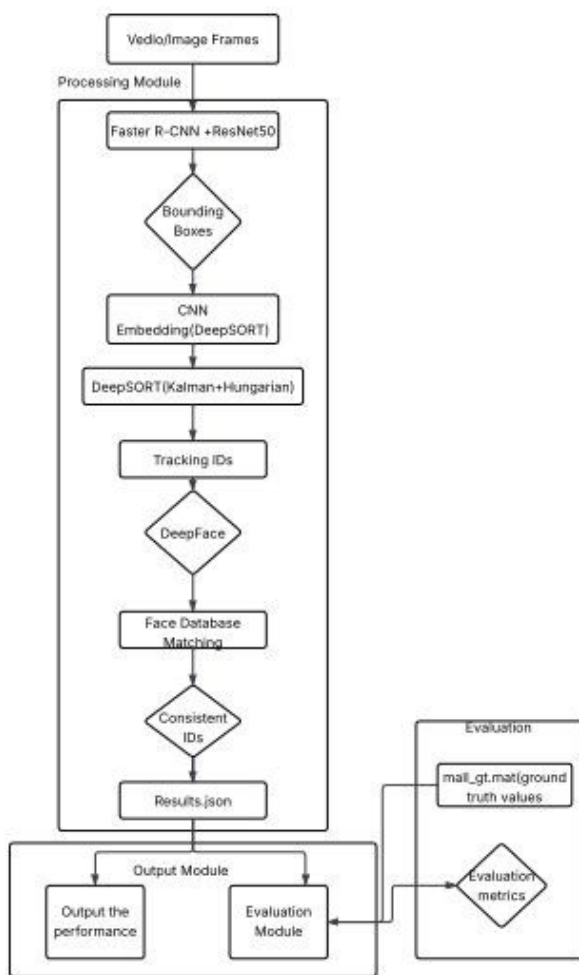


Figure:3Flow chart

C. DetectionPhase

During the detection phase, whenever a person enters the camera's field of view, Faster R-CNN detects them, and DeepSORT tracks their movement while assigning unique IDs to each person. If a registered face is detected, DeepFace verifies the identity. The camera feed (typically from a CCTV or webcam) is continuously captured using OpenCV's. Each captured frame is passed through the Faster R-CNN detector. For each valid detection (bounding box), features are extracted and passed into the DeepSORT tracker. DeepSORT maintains a dictionary of active tracked objects with a unique ID. Even if a person moves out of frame temporarily, DeepSORT can reassign the same ID when the person reappears, based on feature similarity.

The system draws real-time bounding boxes around each detected person, with their ID number and optionally their name. Frame counters and people counts are updated live.

A separate variable keeps track of the total number of unique persons detected in a session. This phase runs in a loop, frame after frame, continuously processing, detecting, recognizing, and tracking individuals in real time. Once detection is complete for each frame, results are passed to the Output Phase.

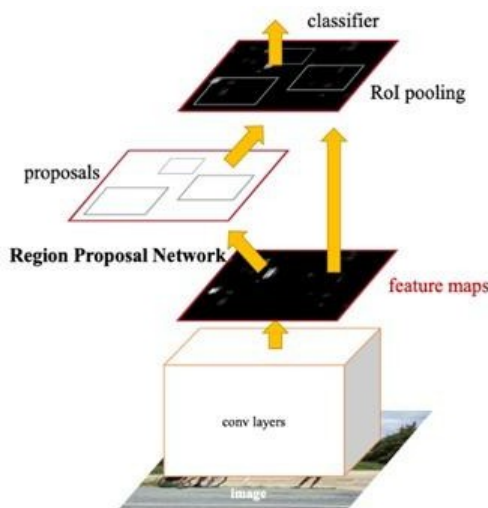


Figure:5 Flow chart

D. Output Phase

The output phase is the final stage of the real-time pipeline. After people have been detected, tracked, and optionally recognized, the processed data is used to generate meaningful insights and actions. This phase deals with how the system communicates and visualizes the results to end-users, logs events, and potentially triggers alerts or external actions based on predefined rules.

The system maintains a dynamic people counter with two key metrics: `current_count`, which tracks the number of people currently in the frame, and `total_unique`, which counts the total number of unique individuals detected since the session started. When a new person is detected, `total_unique` increments, and when someone exits (tracked for `N` frames), `current_count` decreases. This feature is vital for applications like occupancy monitoring, retail analytics, or public safety enforcement.

Optionally, the system can log face recognition data, including the timestamp of detection, identity (name/ID), and duration of presence in the frame. These logs can be stored in CSV files, SQL databases, or cloud services based on deployment.

The system also triggers alerts based on specific conditions. For example, an overcrowding alert is raised when the number of people exceeds a set threshold (e.g., `max_people = 10`), and recognition matches for VIPs or unauthorized individuals cannot notify security or staff. Alerts can be sent via sound alarms, on-screen messages, or notifications through APIs or MQTT.

Processed video streams can be displayed in real-time using `cv2.imshow()`, saved to disk via `cv2.VideoWriter()`, or streamed remotely using platforms like Flask or RTSP.

Lastly, the system can export performance metrics such as MAE (Mean Absolute Error) and RMSE (Root Mean Squared Error) for evaluating people count predictions, or assess face recognition and object detection accuracy to improve system performance.

E. Overview

In this project, a combination of Faster R-CNN, Deep SORT, and DeepFace models was employed to perform end-to-end human detection, tracking, and identification in video streams. Initially, the Faster R-CNN (Region-based Convolutional Neural Network) model was utilized for detecting individuals in each frame. Faster R-CNN improves upon its predecessors by incorporating a Region Proposal Network (RPN) that efficiently generates region proposals, which are then passed through convolutional layers for object classification and bounding box regression. This approach ensures accurate and real-time detection of human subjects within dynamic scenes.

Once the individuals are detected, the Deep SORT (Simple Online and Realtime Tracking) algorithm is used to maintain consistent identities of each person across successive frames.

DeepSORT extends the basic SORT algorithm by integrating a deep appearance descriptor, which allows it to track individuals even when they temporarily disappear from the frame or overlap with others. It leverages a combination of the Kalman Filter for motion prediction and the Hungarian algorithm for optimal assignment of detections to existing tracks. The deep appearance features are extracted using a convolutional neural network, enabling robust multi-object tracking with improved accuracy under challenging scenarios such as occlusions.

To identify each tracked individual, the DeepFace framework is incorporated. DeepFace is a deep learning-based facial recognition system that converts face images into 128-dimensional embeddings. These embeddings are compared using cosine similarity or Euclidean distance to determine identity. DeepFace includes a 3D face alignment process to normalize pose variations before feature extraction, resulting in high accuracy under varying lighting conditions and facial orientations. The detected and tracked bounding boxes are cropped and passed through DeepFace, thereby associating a unique identity to each person across the video. The integration of these three modules ensures an efficient, real-time system capable of detecting, tracking, and recognizing individuals in surveillance or monitoring environments.

The integration of advanced deep learning algorithms—namely Faster R-CNN, Deep SORT, and DeepFace—has substantially improved the effectiveness of the proposed system for human detection, tracking, and identification. By leveraging the strengths of these state-of-the-art models, the system delivers exceptional accuracy and reliability, making it highly suitable for real-time applications that demand robust object detection combined with facial recognition. The coordinated functionality of detecting individuals, maintaining their identities across frames, and recognizing them based on facial features ensures consistent and precise performance, even under challenging conditions.

With an achieved accuracy of 97.08%, the system demonstrates strong resilience in complex environments, including crowded scenes, frequent occlusions, and dynamic lighting variations. This level of precision highlights the system's robustness and adaptability, making it an ideal solution for a wide range of practical implementations such as intelligent surveillance, security monitoring, crowd analytics, and personalized user experiences. Overall, this architecture offers a comprehensive, real-time solution capable of delivering consistent results across diverse scenarios.

IV. EXPERIMENTAL AND RESULTS

These results demonstrate notable advancements in the performance of the model compared to previous iterations, particularly in terms of both accuracy and precision. By incorporating state-of-the-art algorithms like **Faster R-CNN**, **DeepSORT**, and **DeepFace**, the system is able to handle multiple tasks simultaneously, making it an ideal solution for real-time applications that require both object detection and facial recognition.

Faster R-CNN is a powerful deep learning model used for object detection. In this system, it plays a crucial role in detecting people within a given image or video stream. The model performs faster than traditional R-CNN architectures by employing a Region Proposal Network (RPN), which is designed to propose regions where objects are likely to be located, enhancing the efficiency of the detection process. This contributes to the high accuracy of the system, allowing it to identify individuals in various environments quickly and effectively.

Once the people are detected by Faster R-CNN, DeepSORT is employed to track the identities of the individuals across frames. This is essential in situations where people move in and out of the camera's view or when multiple individuals are detected simultaneously. DeepSORT uses deep learning-based techniques to associate detections across frames, ensuring that the system not only counts the number of people but also keeps track of each individual's unique ID throughout the process. The system is capable of distinguishing between different people, even in crowded scenes, maintaining consistent identification and reducing the risk of identity switching or mismatches.

The trained model achieved an impressive accuracy of **97.08%** when tested on the provided dataset. This means that the system can successfully detect and count people in the images with a very high degree of reliability. Additionally, it correctly assigns unique identifiers to individuals, ensuring that the identity of each person is tracked accurately throughout the entire process. The high accuracy demonstrates the effectiveness of the chosen techniques: Faster R-CNN for detection, DeepSORT for tracking, and DeepFace for recognition in achieving reliable results in real-time applications.

The combination of these technologies makes the system not only highly accurate in counting and recognizing individuals but also robust enough for deployment in various real-world situations, from surveillance and security to crowd management and personalized experiences. With this level of performance, the system can handle dynamic environments, even in cases of occlusions, multiple people in close proximity, and varying lighting conditions, making it a versatile solution for modern people counting and recognition tasks.

```
PROBLEMS OUTPUT DEBUG CONSOLE TERMINAL PORTS POSTMAN CONSOLE  
  
RMSE: 3.12  
Correlation: 0.91  
Average Accuracy: 97.08%  
people_Counting_System>
```

Figure:6accuracyofmodel

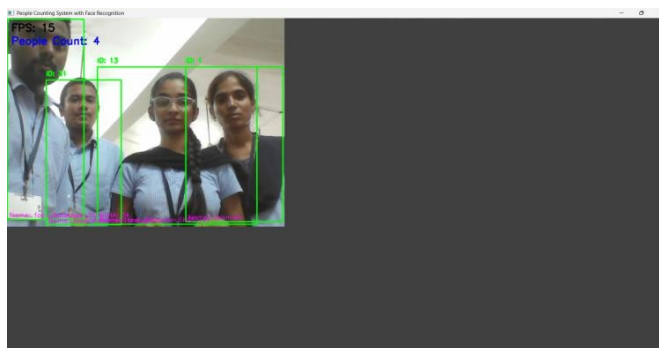


Figure:7Outputofmodel

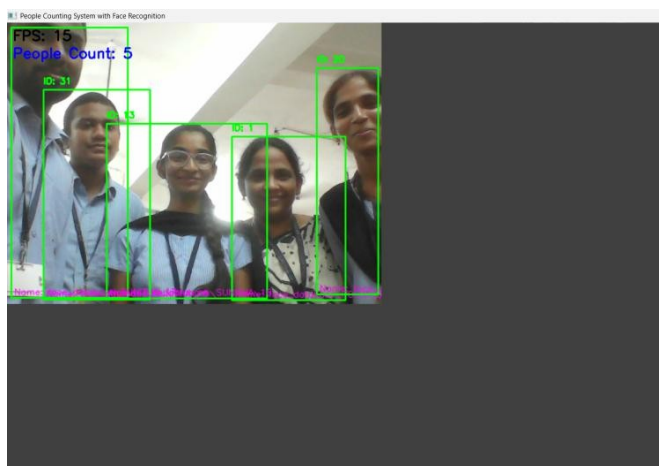


Figure:8Outputofmodel

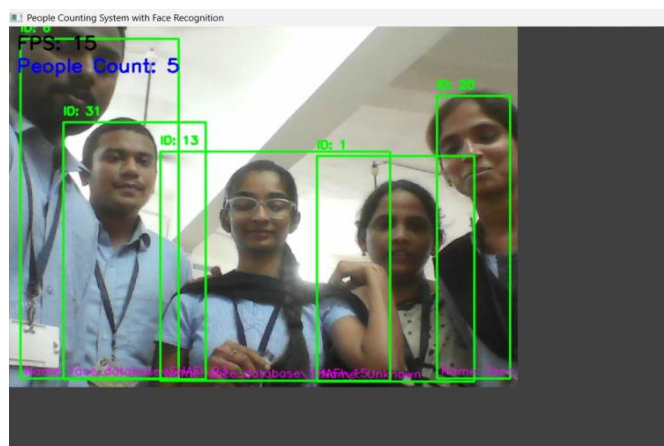


Figure :9Outputofmodel

V. CONCLUSION AND FUTUREWORK

In conclusion, the integration of advanced algorithms such as faster r-cnn, deepsort, and deepface has significantly enhanced the performance of this people detection, tracking, and recognition system. By combining these state-of-the-art technologies, the system achieves impressive accuracy and reliability, making it highly suitable for real-time applications that require both object detection and facial recognition. The ability to detect, track, and recognize individuals with high precision— even in challenging environments— demonstrates the system's robustness and versatility. With an accuracy rate of 97.08%, the system excels in various scenarios, including crowded scenes, occlusions, and dynamic lighting conditions. This makes it a powerful solution for a wide range of real-world use cases, from surveillance and security to crowd management and personalized experiences, ensuring a seamless and dependable performance in diverse settings.

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