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Plant Disease Identification Using a Novel Convolutional Neural Network

S.Saila, Manish V

Dept of CSE Engineering, Jyothi Institute of Technology, Bangalore, India

Abstract: Early detection of plant diseases avoids the adverse effects on crops. Convolutional neural network, intensive learning, is applied extensively in machine vision and pattern recognition applications. But the deep learning model takes a lot of parameters, and thus, the training time required is longer and hard to execute on small devices. The model proposed has been trained & tested on three plant disease datasets.

Keywords: Plant disease, machine learning, deep learning, depthwise convolution, pointwise convolution.

I. INTRODUCTION

Diseases in crops caused mainly by bacteria and fungi negatively impact the production and quality of crops [1]. The reason behind the CNN-based popularity is the automatic extraction of appropriate features from the dataset. Several popular deep learning-based models, such as AlexNet [10], GoogleNet [11], VGGNet [12], ResNet [13], DenseNet [14], have been developed for the identification of plant diseases. Real-time applications and disease identification using deep learning architectures are gaining more importance in the current scenario. Therefore, there will be issues in applying to small devices having limited resources [15]. Utilizing sophisticated devices with GPUs is not feasible in agriculture as they are costly. Therefore, there is a shortage of demand for applications with fewer parameters, less power consumption, and computation [16]. Based on the above consideration, we have proposed a new, lightweight deep learning model for disease detection in the field. Inception architecture utilizes improved features with multiple convolutions of varying filter sizes. Rather than conventional con-con-convolution, we have employed depth-wise separable convolution, which reduces the size of parameters and computational complexity without affecting performance.

To verify the robustness, the performance of the model is checked on three different plant disease data sets. We have taken three different conditioned images. In the PlantVillage data set, the images were taken on a uniform background and under laboratory setup conditions. The photos in the rice disease dataset were captured in actual field conditions, and in the cassava plant dataset, the photos were taken in the field, and the photos contain several leaves. We have compared the performance of four proposed methods with other state-of-the-art deep learning methods on three different sets. The outcome indicates that our proposed method excels compared to other deep learning methods. The rest of the paper is organized as follows: Section 2 presents existing literature on the detection of plant diseases with deep learning models. Materials and methods are described in Section 3. A lightweight deep learning model to identify the diseases in the plant. The Inception architecture extracts better features using multiple convolutions of different filter sizes. Instead of standard con-con-convolution, we have used depth-wise separable convolution, which reduces the parameter size and the computational complexity without affecting performance. The model has been trained on three different datasets, and the performances are evaluated. The main contribution of the paper is summarized as follows:

- A new CNN architecture is proposed using Inception and Residual connection, which extracts better features and produces higher performance results.
- In this paper, the standard convolution is replaced with depth-wise separable convolution, which reduces the parameter number by a large margin without affecting performance.
- To check the robustness, the model's performance is evaluated on three different plant disease datasets. We have considered three different conditioned images. In the PlantVillage dataset, the images were captured on a uniform background and under laboratory setup conditions. The images in the rice disease dataset were captured in real-time field conditions, and in the cassava plant dataset, the images

II. RELATED WORK

This section reviews recent research on plant disease detection using deep learning models. Mohanty et al. [5] used AlexNet and GoogleNet to classify 26 diseases across 14 plant species, achieving 99.34% accuracy with GoogleNet.

Ferentinos [7] used five pre-trained models like VGG and GoogleNet to classify 58 plant leaf diseases. Geetharamani and Pandian [17] built a nine-layer CNN and achieved 96.46% accuracy. Liu et al. [18] modified AlexNet by adding an inception layer to classify apple leaf diseases with 97.62% accuracy. Ahmad et al. [19] used VGG16, VGG19, ResNet, and InceptionV3 to classify tomato leaf diseases, achieving 99.60% for lab images and 93.70% for field images with InceptionV3. Rangarajan and Purushothaman [20] used VGG16 and multiclass SVM to classify eggplant diseases, achieving 99.4% accuracy with RGB images. To et al. [21] fine-tuned multiple models, with DenseNet reaching 99.75% accuracy. Sethy et al. [1] combined deep CNN features with SVM to detect rice diseases, with ResNet50 achieving an F1-score of 98.38%. Rangarajan Aravind and Raja [22] used six pre-trained models and found VGG16 gave the best result of 90%.

Ramacharan et al. [23,24] applied InceptionV3 and MobileNet for cassava disease detection, achieving better accuracy with single leaf images (80.6% for images and 70.4% for video files). Oyewola et al. [25] showed that deep residual networks outperform basic CNNs for cassava disease detection. Picon et al. [26] used a 50-layer ResNet for wheat diseases, achieving 96% accuracy. Durmus et al. [27] used SqueezeNet to detect tomato diseases with a much smaller model size. Hu et al. [28] improved a CIFAR10 CNN with depthwise separable convolution to detect tea diseases, reaching 92.5% accuracy. Atila et al. [29] used EfficientNetB4 for crop disease detection, achieving 99.97% accuracy with fewer parameters. Chen et al. [6] built INC-VGGNet for rice and corn disease classification, achieving 92% and 80.38% accuracy, respectively. Li et al. [30] used a shallow VGG16-based CNN with PCA and achieved an F1-score of 94% using SVM and RF classifiers. Finally, Zeng and Li [31] employed a self-attention CNN to focus on important regions for better crop disease detection. Table 1 summarizes these studies and their results.

III. MATERIAL AND METHODS

A. Convolutional Neural Network

Convolutional Neural Network (CNN) is a Neural network that is highly efficient in many computer vision applications like pattern recognition and classification. CNN has the benefit of learning and extracting the features automatically from the training images, while in the conventional method, manual feature extraction from the images is required. CNN comprises various layers: a convolutional layer, a pooling layer, and a fully connected layer. The convolutional layer is the most central and important one among CNN's layers, which detects features of the input image. Convolution layers comprise a tiny array of figures known as kernels spread across the input, which creates an output named feature maps. Various convolutional kernels are used for detecting varying kinds of features. There are many convolutional layers, depending on the input image size. Following the convolutional layer, pooling is done, which is used to decrease the dimension of the convolutional feature map. The feature maps of the convolution and pooling layer are converted into a one-dimensional vector where each input is associated with each output by weight. There can be multiple fully connected layers, and the last fully connected layer contains the same number of outputs as the number of classes.

B. Residual Network

The convolutional neural network can have high performance on classification problems. As the network depth increases, the accuracy of performance gets saturated and deteriorates sharply.

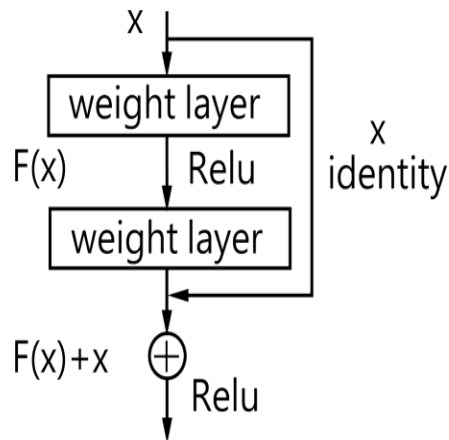


Figure 1. basic block diagram of residual network.

To address this issue in 2015, He et al. [13] introduced a deep residual learning network known as ResNet. In deep learning, using the residual connection in the network, we can train a large network and solve the vanishing gradient problem, which usually occurs due to the increase in network depth. Figure 1 shows the basic block diagram of the ResNet model. ResNet introduced a skip connection known as “identity mapping” which combines the previous layer’s output with the forthcoming layer. To perform identity mapping, it doesn’t generate any parameters. Therefore, the ResNet can train a deep network with lower complexity than other networks, such as VGG.

C. Depthwise Separable Convolution

Depthwise separable convolution, introduced by Chollet in the Xception model and later adopted in MobileNet by Howard et al., breaks down standard convolution into two operations: depthwise convolution and 1×1 pointwise convolution. This significantly reduces computational cost compared to traditional convolutions. The cost for depthwise separable convolution is much lower, as shown by the formula where DFD_FDF is the input size, DKD_KDK is kernel size, MM is input channels, and NN is the number of filters. In this paper, a lightweight CNN model is proposed using Inception and Residual connections, drawing from the Inception-V3 architecture by Szegedy et al. The original Inception blocks perform multi-scale convolutions in parallel and concatenate the outputs. In our model, computationally expensive convolutions in Inception-A and Inception-B blocks are replaced with depthwise separable convolutions. For instance, 3×3 and 5×5 convolutions in Inception-A are replaced with 3×3 depthwise separable convolutions, while 7×7 convolutions in Inception-B are replaced similarly. These modifications reduce parameters while maintaining high performance.

D. Proposed Novel CNN Approach For Plant Disease Identification

In this paper, we have proposed a novel light-weight CNN based on Inception and Residual connections with fewer parameters compared to Inception V3, ResNet50, as well as other deep learning approaches. The reduction A 3×3 convolution layer was substituted with a 1×1 convolution layer and a 3×3 depthwise separable convolution. In block reduction B, we substituted the 3×3 and 7×7 convolution with a 1×1 convolution layer and a 3×3 depthwise separable convolution layer. Table 2 and 3 illustrate the parameter comparison of the original inception-A block with the modified inception-A block having depthwise separable convolution. From Table 3, one can observe that the parameter utilized in the modified inception-A block is significantly smaller than compared of the original inception-A blocks. Figure 5 illustrates the proposed CNN architecture employed to detect diseases in plants. The implemented model proposed comprises a convolution layer, a batch normalization and activation layer, a depthwise separable convolution layer, inception blocks, a pooling layer, and a fully connected layer. In this structure, we have substituted the standard convolution with depthwise separable convolution. We have employed one standard convolution, three depthwise separable convolutions, two max-pooling, and one global average pooling operation, three modified inception A blocks with residual connection, followed by modified reduction A blocks, three modified inception B blocks with residual connection, followed by modified reduction B blocks. Following each of the convolution layers, we have applied Batch Normalization and activation. We applied ReLU as the activation function. Batch Normalization and activation function enhance the performance and accelerate the process. Following global average pooling, we have applied dropout, which decreases the likelihood of overfitting the model. The number of parameters required in our proposed model is 428,100, whereas the parameters utilized in the conventional inception V3 model are 23,851,784, which is even greater than the proposed model. It is seen that the proposed model employs 770% fewer parameters compared to the Inception V3 architecture.

TABLE 1.

table 1. summary of related works on identification of plant diseases.

Author	Deep learning model	Dataset	Results
Mohanthy et al.(2016) [5]			99.35%(Training acc.)
Sladojevic et al.(2016) [32]			96.3%(Precision)
Puentes et al.(2017) [33]	Faster R-CNN	Own	83%(Testing acc.)
Ferentinos et al.(2018) [7]	Multiple CNN	PlantVillage	99.53%(Training acc.)
Geetharamani et al.(2019) [17]	Nine Layer CNN	PlantVillage	96.46%(Testing acc.) 97.87%(Validation acc.)
Too et al. (2019) [21]	Multiple CNN		99.75%(Testing acc.)
Sethy et al.(2020) [11]	Multiple CNN with SVM		98.38%(F1-score)
		MK-D2 AES-CD9214	95.33%(Testing acc.) 98%(Testing acc.)

Zeng et al.(2020) [31]	Self Attention CNN		
			97.57%(Training acc.) 91.83%(Validation acc.)
J.Chen et al.(2020) [6]	INC-VGGN	PlantVillage	
			94%(Precision) 94%(Recall) 94%(F1-score)
Yan Li et al.(2020) [30]	Shallow CNN	PlantVillage	
Oyewola et al.(2021) [25]	Deep residual CNN	Cassava	96.75%(Testing acc.)

IV. RESULTS AND DISCUSSION

A. Dataset

To evaluate the proposed model, three plant disease datasets were used:

- PlantVillage Dataset: Contains corn, potato, and tomato disease images, captured under controlled, uniform background conditions.
- RiceDiseaseDataset: Includes 5,932 field images divided into four classes — bacterial blight, blast, brown spot, and tungro.
- Cassava Disease Dataset: Consists of 5,656 field images with complex backgrounds and multiple leaves; five classes including healthy and various diseased leaves.

All images were resized to 256×256 pixels and datasets were split into 80% training and 20% testing.

B. Experimental Results

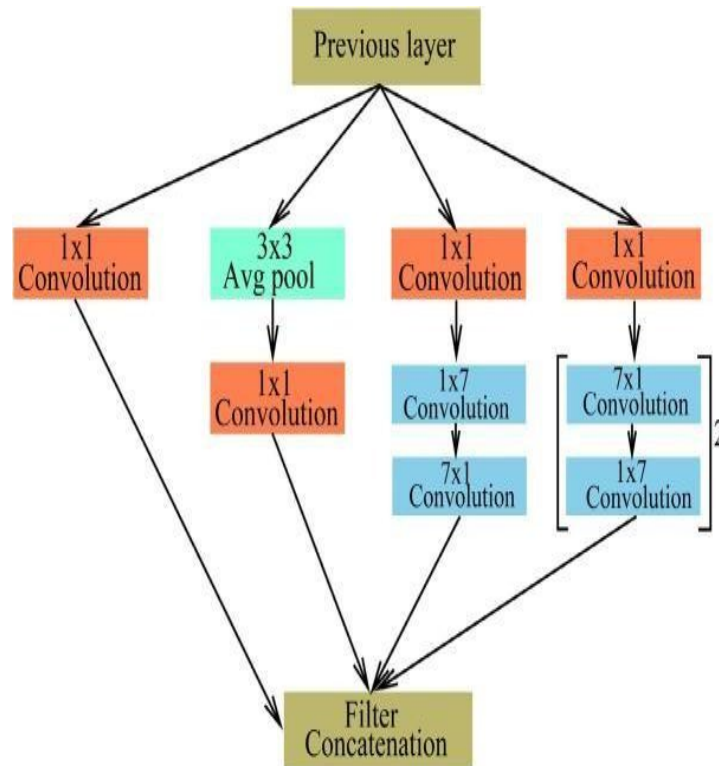
The model was evaluated using accuracy, precision, recall, and F1-score:

Key results after 50 epochs:

- PlantVillage Dataset: Training accuracy of 99.81%, validation accuracy of 99.39%.
- Rice Dataset: Training accuracy of 99.94%, validation accuracy of 99.66%.
- Cassava Dataset: Training accuracy of 98.17%, validation accuracy of 76.59%.

Due to complex backgrounds and class imbalance, the Cassava dataset showed comparatively lower performance. However, overall the model demonstrated high accuracy with fewer parameters.

Figures 7–9 depict the training and validation accuracy and loss trends for the datasets, showing fast convergence and stability.



(a)

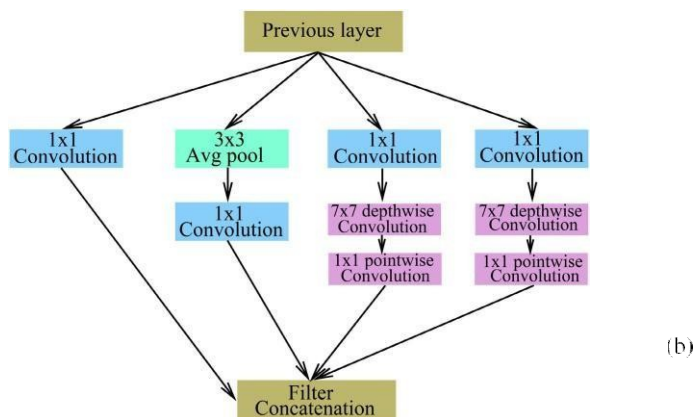


Figure2:Inceptionarchitectureof(A)Originalinception-Bblock(B) Modifiedinception-Bblock

C. Model Robustness

To test robustness, 5-fold cross-validation was performed:

- PlantVillage:Accuracybetween99.29%and99.37%.
- Rice:Accuracybetween99.33%and99.66%.
- Cassava: Accuracy between 76.42% and 76.58%.

Minimalvariationacrossfoldsindicatesconsistentmodel performance across different splits.

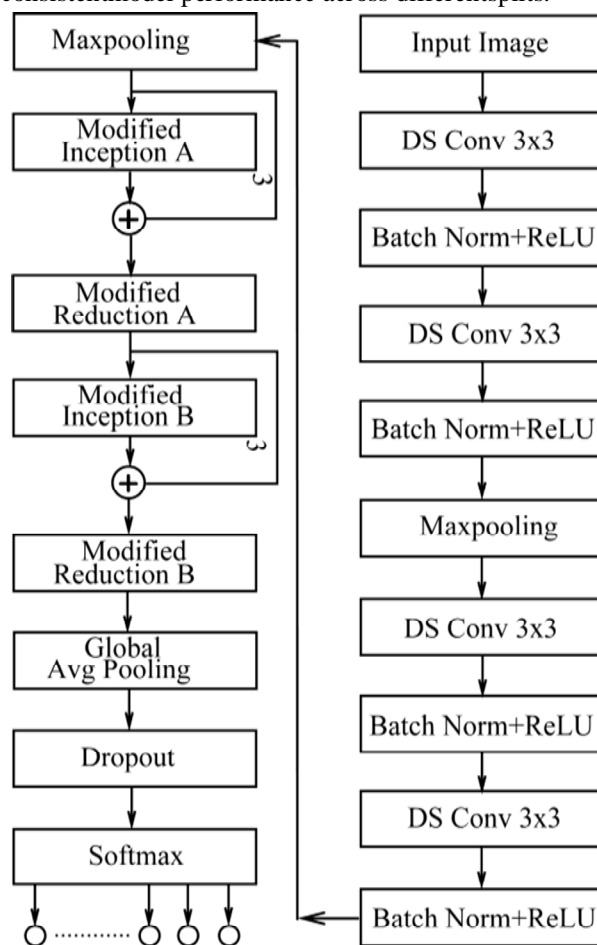


figure 3: Proposed CNN approach in identification of plantdiseases.

FIGURE 5.



Figure4:Sampleimagesof Plantvillagedataset,riceandcassavaplant dataset.

D. Performance Comparison with pre- Trained Networks

We compared the proposed model with VGG16, VGG19, Inception V3, ResNet50, and DenseNet201:

- Our model achieved higher accuracy (upto 99.66% on Rice) with significantly fewer parameters (428,100).
- Pre-trained models showed lower accuracy because they used weights trained on the ImageNet dataset, which is not specialized for plant diseases.
- The proposed model benefited from using Inception layers, residual connections, batch normalization, and depth-wise separable convolutions, leading to better feature extraction, reduced vanishing gradients, and faster training.

Training time was significantly less for the proposed model compared to DenseNet201 and others due to its lightweight structure.

table2. data description of cassava dataset.

Class	Plant Name	Disease Name	Disease Scientific Name	Type of Disease	No of Image
C1	Cassava	-	-	-	316
C2	Cassava	Bacterial blight	Xanthomonas axonopodis pv. manihotis	Bacterial	466
C3	Cassava	Brown streak	Cassava brown streak viruses	Bacterial	1443
C4	Cassava	Green mite	Mononychellus tajajon	Pest	773
C5	Cassava	Mosaic disease	Cassava mosaic disease	Viral	2658

table3. Summary of deep learning based implemented methods.

	30 epochs		50 epochs				Training time (sec/epoch)	Testing accuracy (%)		
	Training acc	Training loss	Val acc	Val loss	Training acc	Training loss			Val acc	Val loss
PlantVillage	0.9981	0.0273	0.9891	0.0864	0.9973	0.0015	0.9939	0.0549	883	0.9939
Rice	0.9970	0.0085	0.9823	0.0452	0.9994	0.0030	1.00	0.0041	227	0.9966
Cassava	0.9545	0.1201	0.6793	0.6732	0.9817	0.0508	0.7659	0.4465	221	0.7659

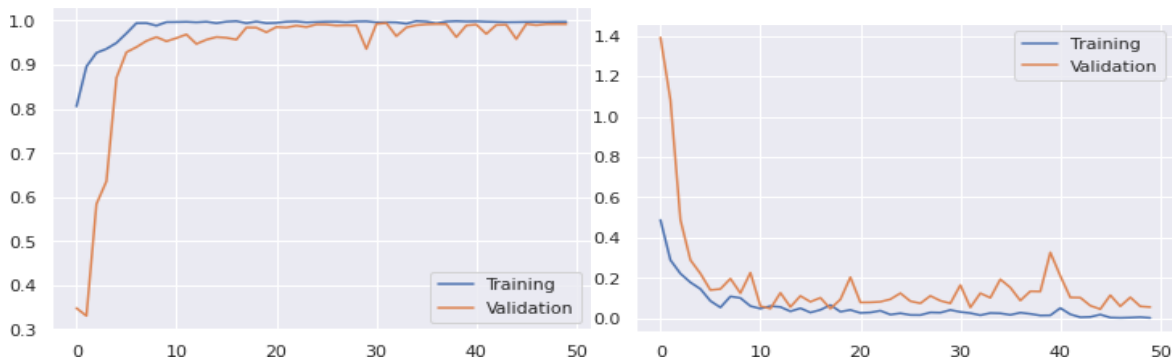


Figure5.(a)training&validationaccuracy(b)training&validationlossonplantvillagedataset.

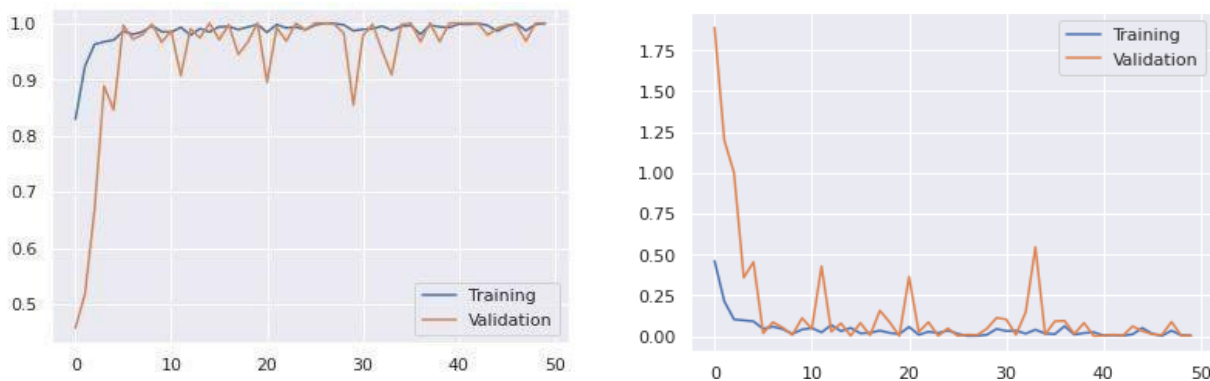
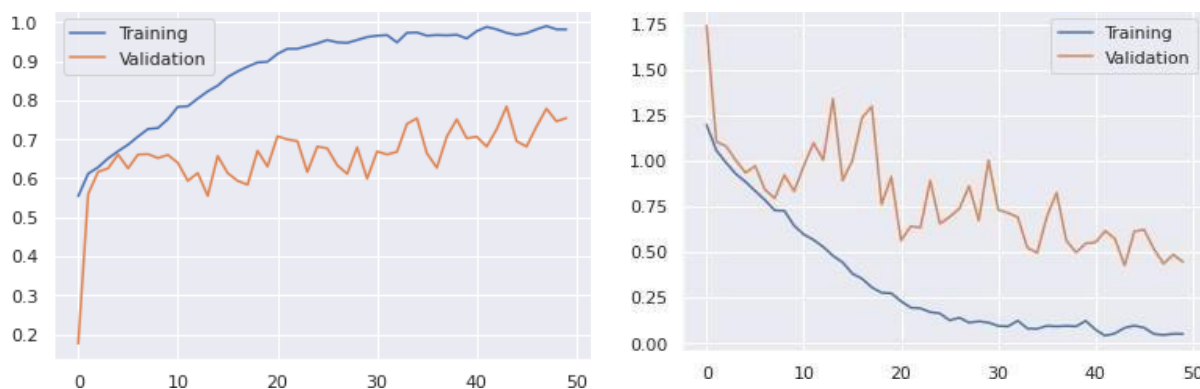


Figure6.(a)training&validationaccuracy(b)training&validationlossonrice dataset.



(a) (b)
Figure7.(a)training&validationaccuracy(b)training&validationlossoncassavaplantdataset.

TABLE 8.

Table4.Performancemetricoftheproposedmodelontestingimages.

Dataset	Accuracy	Recall	Precision	F1-score
Rice Dataset	99.66	99.67	99.66	99.67
PlantVillage	99.39	99.19	99.17	99.18
Cassava	76.59	72.63	62.03	66.91

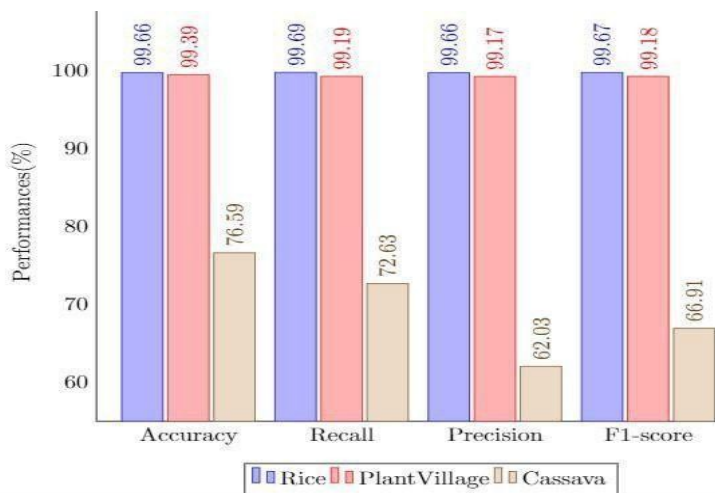


FIGURE 10 Figure8.Performancemetricofproposedmodelondifferentdataset.

E. Comparison With existing literature

Finally, the proposed CNN model was compared against existing deep learning models reported in the literature:

- The model achieved higher accuracy, lower parameter count, and faster training time.
- Unlike many previous works focusing only on controlled datasets like PlantVillage, our model was tested on real-world field images (Rice and Cassava datasets), demonstrating robustness under practical conditions.

Thus, the proposed lightweight CNN shows advantages in terms of efficiency, accuracy, and practical usability in plant disease detection.

TABLE 9.

table5.Result of proposed CNN based on k-fold cross validation.

No of Fold	Accuracy		
	PlantVillage	Rice Dataset	Cassava
1-fold	0.9931	0.9966	0.7649
2-fold	0.9929	0.9954	0.7645
3-fold	0.9937	0.9951	0.7642
4-fold	0.9934	0.9933	0.7658
5-fold	0.9931	0.9959	0.7652

Table6.Performance comparison with pre-trained network.

Models	VGG16	VGG19	InceptionV3	ResNet50	DenseNet201	Proposed
Parameter	138,357,544	143,667,240	23,851,784	25,636,712	20,242,984	428,100
Accuracy (PlantVillage)	0.9565	0.9887	0.9727	0.9798	0.9975	0.9939
Training Time (sec/epoch) (PlantVillage)	2135	2463	2742	5475	9626	883
Accuracy (Rice)	0.7931	0.7888	0.7931	0.7888	0.7991	0.9966
Training Time (sec/epoch) (Rice)	490	608	697	1434	2582	227
Accuracy (Cassava)	0.6355	0.6813	0.7143	0.7439	0.7567	0.7659
Training Time (sec/epoch) (Cassava)	477	598	673	1412	2556	221
Average	0.9932		0.9952		0.7649	

TABLE 11.

table7.Performance comparison with different deep learning models.

Deep learning model	Dataset used	Parameter required	Training acc	Testing acc	Testing loss	Epoch	Training time (sec/epoch)
VGG [7]	PlantVillage	138 million	-	98.87	0.0542	49	4208
AlexNet [5]	PlantVillage	60 million	99.35	93.88	-	30	-
INC-VGGN [6]	PlantVillage	more than 138 million	97.57	91.83	0.2409	30	-
GoogleNet	PlantVillage	7 million	-	97.3	-	20	-
ResNet50+SVM [11]	Rice	23 million	-	98.38	-	-	69.04
Nine layer CNN [17]	PlantVillage	-	97.87	96.46	-	3000	-
Shallow CNN+ RF [30]	PlantVillage	0.26 million	-	94	-	-	-
Deep Residual CNN [25]	Cassava	-	-	58.39	-	80	-
Proposed CNN	PlantVillage	0.42 million	99.73	99.39	0.0549	50	883
Proposed CNN	Rice	0.42 million	99.94	99.66	0.0041	50	227
Proposed CNN	Cassava	0.42 million	98.17	76.59	0.4465	50	221

V. CONCLUSION

Deep learning is also proven to be a good approach to finding plant diseases. In this research work, we proposed a lightweight CNN model with Inception modules, Residual connections, and depthwise separable convolutions that reduced parameters by 70% and accelerated the training process. The developed model recorded astounding test accuracies of 99.39% on PlantVillage, 99.66% on Rice, and 76.59% on the imbalanced Cassava dataset compared to the traditional models such as CNN and ResNet. The model performs with higher accuracy and efficiency compared to past research. Our future work will involve its application for the detection of weeds and pests and the assessment of performance on various datasets and location.

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