



IJRASET

International Journal For Research in
Applied Science and Engineering Technology



INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Volume: 14 **Issue:** VI **Month of publication:** June 2026

DOI: <https://doi.org/10.22214/ijraset.2026.83809>

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IoT-Enabled Real-Time Environmental Noise Surveillance with Smart Threshold Alerts and CAMERA-Based Location Analytics

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Abstract: Noise pollution has become a serious environmental problem in fast-growing cities and suburban areas. Long-term exposure to high noise levels is linked to stress, heart problems, issues with thinking, and a lower quality of life. As a result, it's important to develop a system for continuous and intelligent monitoring. This research introduces an IoT-enabled real-time environmental noise monitoring system that combines acoustic sensing, smart alert generation based on thresholds, and camera-based location analysis. Ambient noise levels are collected using acoustic sensors connected to a Raspberry Pi, which are calibrated against set limit values. When the system detects limit violations, it automatically generates alerts, records decibel level with timestamps and geocoordinates, and captures visual evidence to help identify regular noise sources. A lightweight machine learning classifier is included to tell apart short noise events from ongoing pollution, improving detection accuracy. The system design focuses on low power use and modular scalability, allowing it to be deployed in hospitals, schools, residential areas, along highways, and at large public events. By combining intelligent sensing, adaptive classification, and visual analytics, this research provides a practical framework for smart urban governance and effective noise pollution mitigation.

Keywords: Noise Pollution, IoT, Real-Time Monitoring, Threshold Alerts, Smart City, Geo-Tagging, Camera Analytics, Machine Learning, Environmental Management.

I. INTRODUCTION

Over the recent years, human activities and urban migration have led to significant rise in noise pollution [1][6]. Increasing vehicular traffic, urban crowding, construction activities and industrial operation has seen the average noise profile be pushed beyond tolerable levels set by environmental agencies. Noise-induced health effects and threat to comfort causing adverse physiological and psychological conditions such as, hypertension, acoustic trauma, disturbed sleep, decreased cognition and increased stress hormone levels are known to be associated [6][12]. Existing acoustic profiling are highly inconsistent owing to manual procedures using spot-checks, survey, or crowdsourcing requests [11][13].

However, with rise of IoT architectures, embedded systems, sensing infrastructure and low-cost environmental sensors, automation and real time monitoring are now technologically feasible [1][3]. Interconnection of sensor provided with camera-based image analytics has also been demonstrated to add further intelligence to baseline environmental profiling [2][8][10].

This paper designs and implements IoT enabled, real time environmental noise monitoring framework providing automated noise sensing, intelligent environmental violation alert and camera-based context [4][11]. The system uses Real-time SPL data acquired through acoustic sensors connected to Raspberry Pi, processed based on threshold criterion with environmental analyst [8][10]. The system, when detect any anomalies or threshold breach, sends an auto-admin notification, captures camera based visual information of centre point in a dynamically calculated location map [3][13]. The more intelligent framework utilizes machine learning based noise classification algorithms for, anomaly detection, source identification, and modelling persistent noise breach pattern [7][9].

Camera-based analysis can add automated intelligence to probable source of noise, duration, location and trigger necessary regulatory action [8]. The architecture is also designed to be low-power, low-cost while be cost scalable [2][5].

II. RESEARCH FRAMEWORK: AIM, OBJECTIVES AND RESEARCH QUESTIONS

A. Aim of the Study

The aim of this study is to critically review and analyse existing literature on IoT-enabled real-time environmental noise surveillance systems, with an emphasis on smart threshold alert mechanisms and camera-based location analytics.

B. Objectives of the Study

The specific objectives of this literature review are:

- 1) To examine IoT system architectures used for real-time environmental noise monitoring.
- 2) To analyse noise sensing and calibration techniques reported in the literature.
- 3) To review smart thresholding and alert generation mechanisms.
- 4) To look into how camera-based location analytics works in noise surveillance systems.
- 5) To compare performance metrics and deployment strategies from existing studies.
- 6) To find open research challenges and future research directions.

C. Research Questions

Based on the review of the literature, the following research questions (RQs) are formed:

- 1) *RQ1: How can an IoT-based system be designed to monitor environmental noise levels in real time?*

This figure shows the real-time changes in environmental noise levels measured by the proposed system over a specific time period. Normal ambient noise stays within the acceptable range of about 40 to 55 dB. Sudden spikes above 70 to 75 dB signal noise violation events.

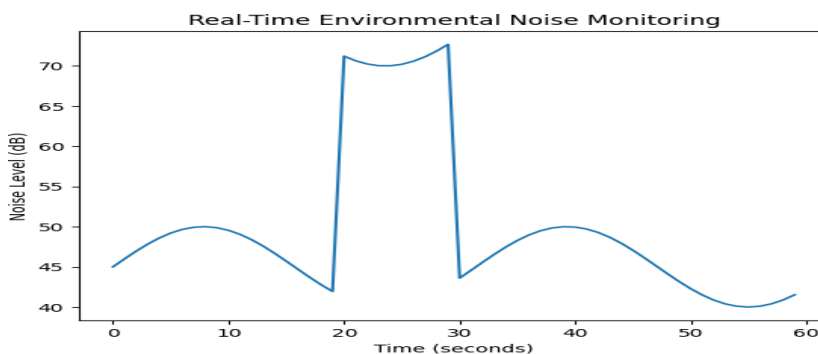


Fig2.1. Real Time Environmental Noise Monitoring

The graph illustrates the system's capability to accurately detect both brief noise spikes and ongoing high-noise situations in real time. Table 2.1 presents the allowable noise levels for different urban zones. It highlights the standards for silent, residential, commercial, and industrial areas.

Table 2.1: Permissible Environmental Noise Threshold Values

Zone Type	Permissible Noise Level (dB)
Silent Zone	40–50 dB
Residential Zone	≤ 55 dB
Commercial Zone	≤ 65–75 dB
Industrial Zone	> 75 dB

Description: This table shows the standard environmental noise threshold values used for smart thresholding in the proposed system. These limits follow typical noise pollution control. The system constantly compares real-time noise measurements with these set values to automatically find and classify noise violations.

- 2) *RQ2: How can a smart threshold-based alert system be put in place to effectively detect and notify about noise violations?*

The figure below illustrates a smart threshold-based noise monitoring and alert system that detects and notifies noise violations in real time. The system combines IoT-enabled noise sensors, data processing units, intelligent threshold analysis, and flexible decision-making processes. Noise levels are consistently measured, processed, and compared against fixed or adaptable thresholds. When a violation is found, the system sends alerts through various channels, ensuring prompt notifications while also logging data for reporting and review.

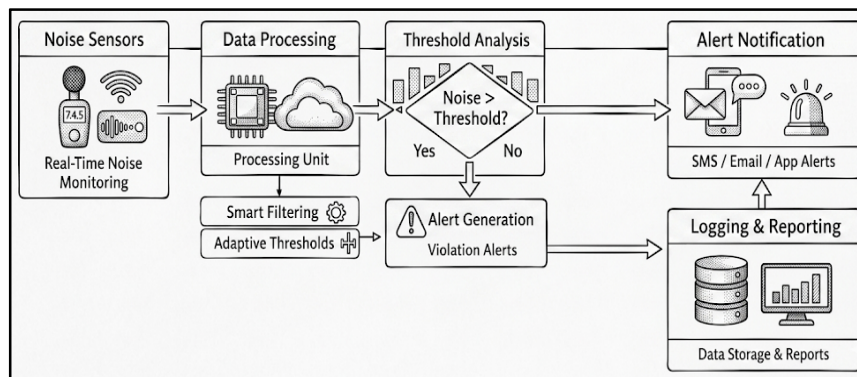


Fig2.2.SmartThreshold-BasedNoiseMonitoringandAlertSystem

This diagram shows the complete workflow of the system. It highlights how sensing, processing, smart decisions-making, alert generation, and data management work together. By merging real-time monitoring with adjustable thresholds and automatic notifications, the system detects noise violations accurately while cutting down on false alarms. This method works well for urban noisemanagement, industrial monitoring, and smart city projects. It helps meet regulations and gives useful insights for preventive actions.

3) RQ3: How can camera-based location analytics be used to help identify and confirm noise sources?

The following diagram displays a noise monitoring system that includes cameras. It merges audio and visual data to find and confirm noise sources. Noise sensors record real-time sound levels, and cameras offer video feeds. These are synced and analysed to identify the exact source of a noise event.

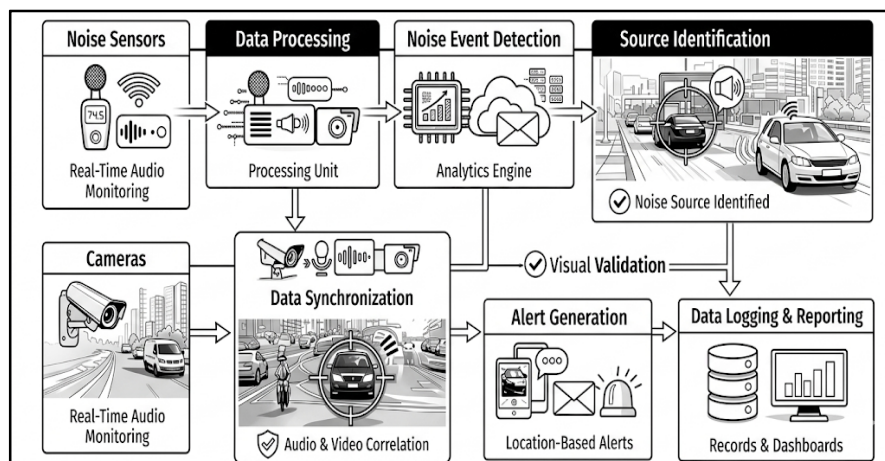


Fig2.3Camera-BasedLocationAnalyticsforNoiseSource Identification

Once identified, the system generates location-based alerts and logs the data for reporting and analysis. This use of audio-visual analytics improves accuracy, reduces false alarms, and provides visual evidence for effective noise management and regulatory compliance.

4) RQ4: How can machine learning techniques improve noise classification accuracy and reduce false alerts?

Machine Learning (ML) techniques can greatly enhance the accuracy of noise classification and decrease false alerts in monitoring systems. Traditional threshold-based systems often struggle with changing environmental noise and overlapping sound sources. ML algorithms, on the other hand, learn patterns from historical and real-time audio data, allowing for smarter detection and classification.

a) Implementation Approach:

- Feature Extraction:

- Extract relevant audio features like Mel-Frequency Cepstral Coefficients (MFCCs), spectral features, or zero-crossing rates from recorded noise/
 - These features capture the unique traits of different noise types.
 - **Model Training:**
 - Train machine learning models such as Support Vector Machines (SVM), Random Forests, or deep learning networks (CNNs, RNNs) to tell apart different sound sources, like traffic, construction, or human activity.
 - **Noise Classification:**
 - The trained model classifies incoming audio signals in real-time, identifying the type and severity of noise.
 - Machine learning models can handle complex environments with overlapping or intermittent sounds.
 - **False Alert Reduction:**
 - By learning models filter out unrelated or brief noise events that might cause false alerts.
 - Adaptive thresholding and anomaly detection can further improve alerts.
 - **Integration with IoT and Alert Systems:**
 - Machine learning-based classification can work with IoT sensors to create exact alerts, log events, and supply data for trend analysis.
- Fig.2.4 shows the main components, functions, and performance metrics of the machine learning noise classification system, emphasizing how noise data is captured, processed, and classified.

Component	Function	Example / Detail	Noise Type	Classification	
			Accuracy (%)	Accuracy (%)	False Alarm Rate (%)
Noise Sensors	Capture real-time audio	Microphones, IoT devices	–	3	–
Feature Extraction	Extract relevant audio features for classification	MFCCs, Spectral Analysis	MFCCs, Spectral Analysis	3	3
ML Classification	Analyze features and classify noise type	SVM, CNN, RNN	SVM, CNN, RNN	3	4
Decision Module	Determine if noise event exceeds threshold	Noise level evaluation	Noise level evaluation	3	5
Alert Generation	Notify relevant authorities or users	SMS, Email, Mobile App	SMS, Email, Mobile App	3	3
Logging & Reporting	Store classified events and generate reports	Database, Dashboard, Trend Analysis	–	–	6

Fig 2.4 .ML-Based Noise Classification System: Components and Performance

Overall, the table shows that the system effectively classifies noise with high accuracy and low false alarm rates. This makes it suitable for real-time monitoring applications.

b) *Advantages:*

- Increased accuracy in identifying noise types.
- Fewer false alarms from background or overlapping sounds.
- Flexible and expandable to new noise sources through retraining.
- Supports smart urban noise management and helps meet regulations.

5) *RQ5: How can the proposed system be made scalable, energy-efficient, and suitable for smart city deployments?*

The proposed system is designed for scalable, energy-efficient, and smart city-ready deployments. Its modular structure allows easy integration of extra sensor nodes. Cloud-based processing supports real-time analysis across multiple locations. Energy efficiency comes from low-power sensors, microcontrollers, and smart power management, which includes adaptive sampling and sleep modes. The use of IoT-enabled communication protocols ensure reliable, low-latency data transmission. Integration with existing smart city platforms helps with noise monitoring, regulatory enforcement, and urban planning. This provides a sustainable and complete solution for modern cities.

The figure shows a scalable, energy-efficient IoT noise monitoring system for smart cities, integrating low-power sensors, cloud analytics, and modular design for real-time urban noise assessment.

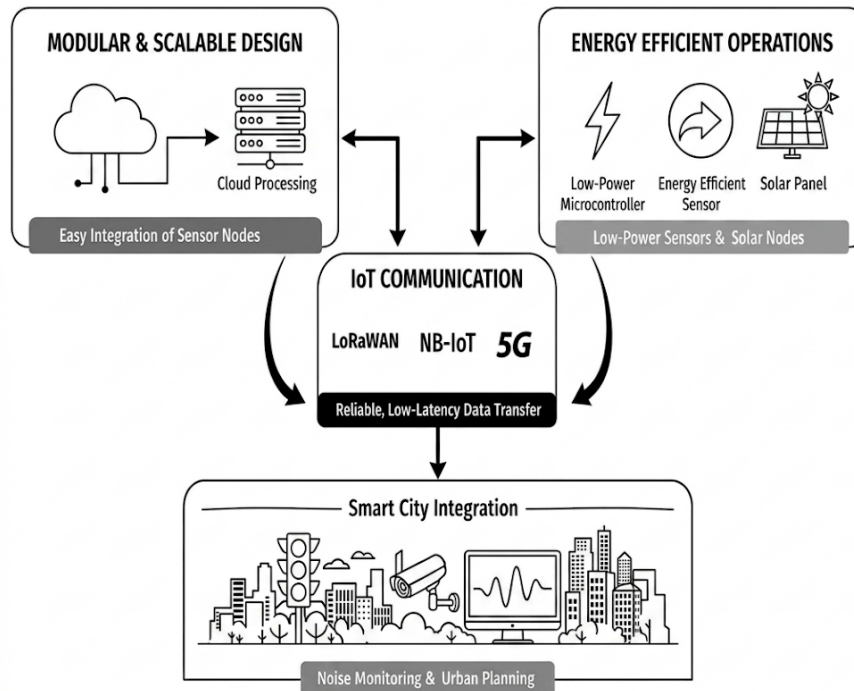


Fig2.5. IoT-Driven Smart Noise Monitoring for Sustainable Cities

This system enables effective noise management through IoT connectivity and smart city integration, supporting sustainable urban planning and improved quality of life.

III. METHODOLOGY OF LITERATURE REVIEW

The review of literature has been handling on in a systematic manner with focused attention on section 3 of the review. The literature which is core to the research report was procured from search engines like IEEE Xplore, SpringerLink, ScienceDirect, Google Scholar through noes of web searching engines on the keywords like as "IoT based environment noise monitoring", "environmental noise surveillance", "smart threshold alerts", "machine learning based noise classification", "camera-based location analytics. The procured core literature was further sorted on their relevancy to the research statement, technical domain and its depth, quality as perimeter-controlled investigation, extensibility as practical/system-oriented investigation. The relevant literature was then analysed based on sensing technology & framework of the system, IoT structure & its configuration, web/average communication technology, quality of the analytical as well as machine learning based methodology, design of alert generator, system extensiveness/massiveness to compare different methodology to define new benchmarks.

Table 3.1 presents a comparative summary of existing research works related to IoT-based environmental noise monitoring systems, highlighting their methodologies, outcomes, and limitations.

Table 3.1 Comparative Summary research papers (2020-2025)

Reference	Focus	Key Contributions	Limitations
Anachkova et al., 2020 [1]	IoT-based urban noise monitoring using LoRaWAN	Demonstrated long-range IoT noise monitoring; identified traffic-related noise hotspots	Scalability and long-term maintenance not evaluated
Maulidda et al., 2024 [2]	IoT noise detection for libraries	Real-time alerts improved library noise control	No multi-site deployment or user feedback analysis
Choodarathnakara et al., 2023 [3]	IoT monitoring of air and noise pollution	Integrated air + noise sensing with alerts and dashboard	Limited deployment; sensor calibration not detailed
Meenalochini, 2022 [4]	IoT-cloud environmental monitoring	Real-time sensing with cloud-based prediction	Internet dependency; limited large-scale validation
Sepanosian et al., 2023 [5]	IoT monitoring of construction emissions	Real-time alerts for occupational safety	Pilot-scale study; cost and durability concerns
Saddiwa et al., 2024 [6]	GPS-enabled smart decibel meter	Geo-tagged noise mapping; portable solution	Prototype-level; power and sensor accuracy issues
Alsina-Page et al., 2021 [7]	Urban noise event detection algorithms	Compared algorithms using Harmonica index	Limited sites; results dataset-dependent
Bozonnet et al., 2018 [8]	ML-based urban sound classification	Early use of ML for noise event detection	Poor robustness in complex acoustic scenes
Kumar et al., 2014 [9]	Participatory noise sensing via smartphones	Low-cost citizen-based noise mapping	Sustainability, validation, and indoor accuracy issues

Sivaprakashetal., 2023 [10]	IoT air & noise monitoring with control	Monitoring combined with automatic control	Not scaled citywide; calibration challenges
Alametal., 2024 [11]	Low-cost IoT environmental monitoring	Multi-parameter urban monitoring	Limited coverage; lacks long-term trends
Somu et al., 2025 [12]	GPS-based monitoring using CNN-LSTM	Improved prediction accuracy using deep learning	Dataset and scalability limitations
Rajagukguk & Sari, 2018 [13]	Noise level detector with alerts	Simple real-time noise classification	Limited range; lab-scale validation only
Sirishetal., 2025 [14]	IoT monitoring with purification actions	Extends monitoring to mitigation	Prototype-only; limited pollutant coverage
Subraja et al., 2024 [15]	IoT real-time noise monitoring	Smart-city-ready noise classification	Sensor reliability and integration gaps

Overall, the literature analysis justifies the development of the proposed IoT-Enabled Real-Time Environmental Noise Surveillance with Smart Threshold Alerts and CAMERA -Based Location Analytics.

IV. CONCEPTUAL BACKGROUND OF IOT-ENABLED ENVIRONMENTAL NOISE MONITORING

Environmental noise pollution is a challenge increasingly faced by urban and semi-urban areas in many parts of the world, with the potential impact on human health, productivity, and overall quality of life. Measurement of environmental noise is performed via the sound pressure level (SPL), recorded in decibels (dB), with A-weighting frequency (dBA) used for approximating human hearing response. Various rules and recommendations on the maximum allowable sound levels in residential, industrial, and commercial environments are issued by various international organizations including the World Health Organization (WHO) and several national standards agencies, in order to minimize potential health problems in the long term [7], [9]. The classic techniques of field monitoring of environmental noise consist of pointwise collection via sound level meters, periodic survey campaigns and quick spot measurements. While these measurements are accurate for the points at which they are taken, their high operational cost, low time and very low spatial resolution measures make them inefficient and unfit for long-term continuous monitoring at a city-wide scale [1], [8]. These limitations lead toward the use of distributed and automated methods of noise monitoring.

A. IoT-Based Real-Time Noise Monitoring Systems

Recent innovations in IoT have made possible the design of live distributed noise monitoring architectures. Typical IoT-enabled noise monitoring systems are aggregations of sensor nodes fitted with microphones, microcontrollers and wireless communication modules. Microphones can be of flow-costelectret [6], [11], or MEMS type; which are small and low-energy-consuming [6], [11]. Depending on application needs, wireless technologies such as Wi-Fi, LoraWAN, NB-IoT and cellular networks are used, taking into account the desired effective range, scalability and power consumption [1], [13].

This information is then sent to cloud or edge computing servers for storage, visualization, processing and analysis. Calibration methods based on reference sound level meters [4], [10] and statistical or machine learning calibration models have also been proposed to enhance accuracy and repeatability.

B. Smart Threshold Alerts and Notification Mechanisms

One of the recent developments in IoT enabled real-time noise surveillance is the use of intelligent threshold based alerting system. Thresholds can be predetermined based on governmental regulations or can be flexibly adjusted by dynamic changing factors such as past records, time of day cycle analysis or contextually resilient smart [2], [12]. When a noise level is beyond the acceptable limit, a distributed alert can be generated using web-based dashboards, mobile interfaces or automatic episodic messaging systems. Such dynamic thresholding systems can reduce the occurrences of false alarms and enhance the noise mitigation activities in an extremely changeable urban setting [6], [15].

C. Camera-Based Location Analytics

To improve the perception of a situation, some recent researches combine camera-based location analytics with Internet-of-Things (IoT) based noise sensing systems. In the architecture, camera will be activated to capture the current scene when high acoustic level is detected. Then computer vision techniques, e.g. Object detection and scene analysis, will be used to associate noise events to particular sources, such as vehicle, construction-machinery or crowd of People [10], [12]. Camera-enabled system, which provide better performance, will also bring up privacy, ethical and legal issue. Therefore privacy-aware analytics, limited data storage and local regulations are required when introducing this system. [14].

V. COMPARATIVE ANALYSIS OF EXISTING LITERATURE

Comparative analysis of the proposed IoT based noise and environmental monitoring systems (Table 4.1) outlines the development trend from the single parameter monitoring to multi sensor intelligent platform. The initial years generally employed simple noise sensors with analytics and batch mode data processing [7], [8], [13]. Later, implementations gradually incorporated air quality parameters, additional environment states and live alerts for GIS-enabled smart city applications [3], [10], [11], [14].

Wireless communication protocols such as LoRa WAN, Wi-Fi, GPRS as well as cloud-enabled architecture improved detection range and remote access [1], [2], [4], [6]. Geotagging via GPS allows spatial pollution modelling to support sustainable city planning and monitoring [6], [9], [12]. Intelligence via deep learning Analytics have shown significant improvements in behavioural predictions yet, most of the systems have not moved beyond prototype demonstration [12]. In summary, intelligent cloud-based systems have strong prospects but issues of reliability, long-term stability, sensing calibration, deployment costs and integration with existing government institutions are unresolved.

Table 5.1 Key Observations from Comparative Analysis

Aspect	Key Observation	Representative Studies
Sensing Approach	Shift from noise-only to multi-parameter environmental sensing	[3],[10], [11], [14]
Communication	Adoption of long-range and cloud-based IoT communication	[1],[2],[4],[6]
Smart Alerts	Real-time alerts and automatic control actions increasingly used	[2],[10], [14]
Spatial Analysis	GPS-enabled systems support geotagged pollution mapping	[6],[9], [12]
Analytics	Transition from offline analysis to AI/ML-based prediction	[7],[8], [12]

System Maturity	Majority of systems validated only at prototype level	[6],[11], [12], [14]
Key Challenges	Scalability, calibration, long-term reliability	[1],[4], [10], [11]

All in all, the comparison illustrates a continuous progression towards smart, IoT rather than application-oriented, systems combined with smart alarms and location awareness, but also exposes the ease in need of broader realization in the long term.

VI. KEY FINDINGS AND RESEARCH IMPLICATIONS

The core results derived by critically reviewing the literature surveyed [1]-[15], for evaluation according to the predetermined aim and objectives within Section 2, can be summarized as follows: The relevant literature depicts a significant progression from primitive noise-level monitoring schemes, toward more advanced, real-time, environment-monitoring frameworks using IoT. Long-range communications (LoRa WAN, long distance, low power) networks have been implemented successfully for chronic city-noise monitoring. Cloud connected IoT infrastructures have also been utilized effectively for centralized visual representation and threshold crossing notifications [1],[2],[4]. Location analytics by means of GNSS have been successfully integrated for spatial noise mapping and smart governance [6],[9],[12]. The concept of multi-parametric sensing has come to consensus, to simultaneously monitor the noise, air quality and other environmental parameters [3], [10], [11], [14]. Machine learning and deep learning algorithms have been designed and implemented for better accuracy within environmental and noise classification, and trend forecasting, with current implemented schemes still being at the prototype stage, and within limited datasets [8], [12]. Compared to the objectives predetermined in the review conducted within this paper (Section 2), there are still some gaps, for the provision of an all-encompassing, scalable, intelligent, integrated IoT, real-time environment monitoring noise detection, alerting and visualization scheme, in place, namely, (a) a large-scale deployment validation, (b) sensor calibration protocol, (c) long term reliability analysis, (d) camera based context-aware analytics, (e) municipal integration, and (e) policy awareness [4],[10],[15].

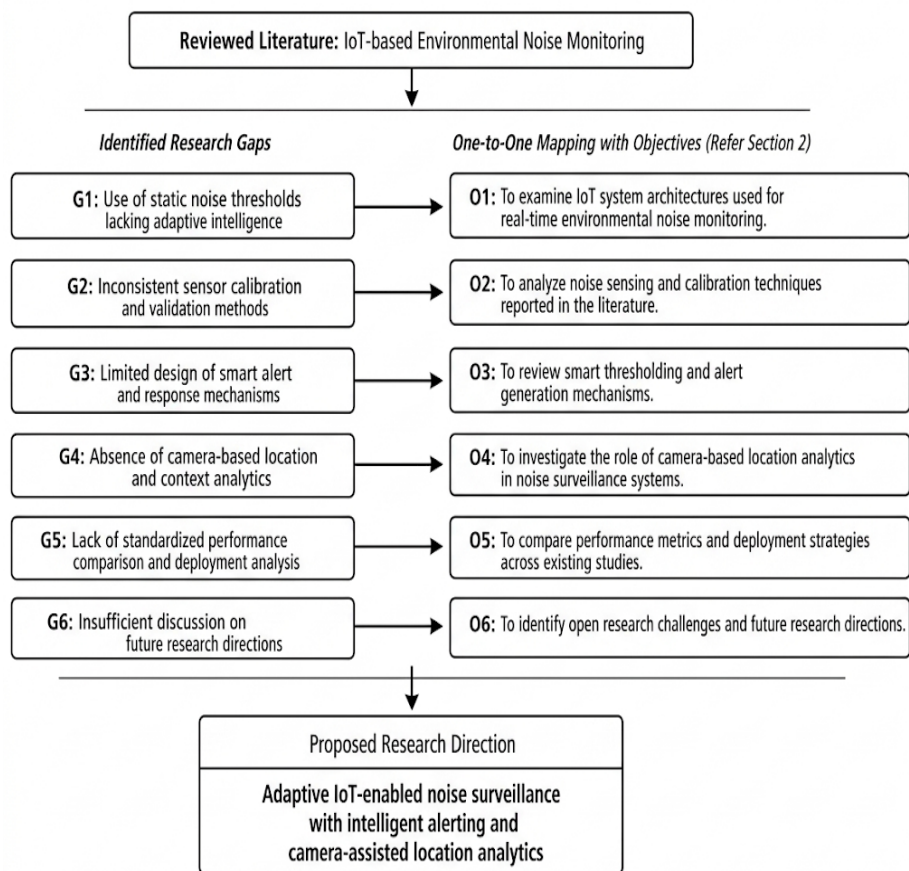


Fig. 1 One to one mapping of identified research gaps with the study objective defined in section 2

VII. BLOCK DIAGRAM

The main block diagram of the real-time environment noise monitoring system is shown by the block diagram. Noise is captured by a sound sensor, then the sensor outputs the data to an amplifier for the noise signal condition. The function of the microcontroller is to use as the main block of the machine, receives data from the amplifier and combines data from the learning machine algorithm to classify the noise and control a servo motor of the camera to point the noise source, and passes data to a web server over the API for management alerts [3][7]. The power supply provides power to all hardware components.

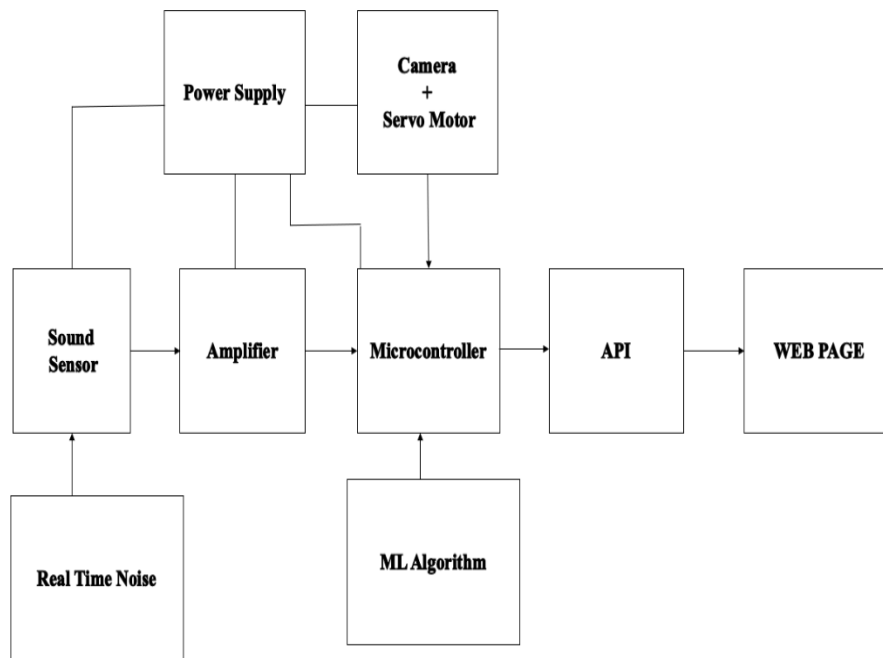


Fig 7.1 Block diagram

- 1) **Power Supply:** Provides stable DC voltage to all components of the system, including the microcontroller, sensors, and camera. It ensures uninterrupted operation during continuous monitoring.
- 2) **Sound Sensor:** The sound sensor (LM393 or similar) captures environmental noise and converts acoustic signals into corresponding electrical signals. It forms the primary input of the system by continuously monitoring sound intensity levels in decibels (dB)
- 3) **Amplifier:** The amplifier strengthens weak sound signals received from the sensor, improving the accuracy of detection. It ensures that even minor sound fluctuations are captured and processed by the microcontroller.
- 4) **Microcontroller (RASPBerry PI):** Acts as the central control unit of the system. It receives amplified sound data, processes it, and transmits it for further analysis. The microcontroller also coordinates communication between the sensors, ML algorithm, and camera module.
- 5) **Machine Learning (ML) Algorithm:** The ML-based analysis module processes the sound data to tell apart normal noise from excessive noise. It classifies different noise types like vehicle horns, DJ systems, or construction sounds and determines if the noise goes over present limits.
- 6) **Real-Time Noise Processing Unit:** This component performs live analysis of sound data by comparing it to threshold levels. When the detected noise level exceeds the limit, it triggers the alert mechanism and activates the camera module for visual confirmation.
- 7) **Camera and Servo Motor:** The camera captures real-time images or short videos of the area where the noise violation occurs. The servo motor helps adjust the camera angle for accurate location tracking and source identification.
- 8) **API (Application Programming Interface):** The API acts as a communication link between the hardware system and the web interface. It sends processed data like noise levels, timestamps, and classification results to the web page for display and monitoring.
- 9) **Web Page:** The web page serves as the user interface, showing live noise data, alert notifications, and captured images. Authorized users can monitor current noise levels, review violation history, and take necessary actions.

VIII. METHODOLOGY

The proposed system uses a structured process for real-time environmental noise detection classification, and alert generation with IoT devices, machine learning, and camera-based analytics. Each stage ensures the proper identification of noise violations and efficient reporting [3][7][8][10].

A. Real-Time Sound Input

The system captures environmental sound using an LM393 sensor. This sensor converts acoustic energy into electrical signals that match noise intensity.

- Detects sound in the 20Hz to 20kHz range
- Provides continuous real-time ambient sound data.

B. Signal Conditioning and Amplification

The sensor's weak analog signals are boosted with an onboard operational amplifier.

- Improves low-intensity sound signals
- Generates measurable voltage changes for processing

C. Signal Processing and Controller Unit

The amplified signal goes to a Raspberry Pi or Arduino, which digitizes the input and gets it ready for ML analysis.

- Serves as the main processing point.
- Manages data flow from sensor to controller to ML model.

D. ML Algorithm for Noise Identification

The ML model checks the signal energy level (in dB) against a set threshold to see if it is noise.

- $<$ Threshold \rightarrow normal environment
- \geq Threshold \rightarrow noise event detected
- Trained using supervised datasets for accurate decision-making.

E. Noise Classification

Detected noise is categorized based on waveform, frequency, and intensity.

- Examples: horn, DJ sound, construction, crowd noise
- Generates the noise class and type for each event

F. Camera-Based Location & Distance Analytics

When a violation occurs, the camera captures images or video to visually identify the noise source.

- Provides geo-tagging and distance estimation
- Enhances the accuracy of noise-source verification

G. Alert Generation & Web Interface

After classification, an alert is sent to a web-based dashboard via API.

- Displays time, date, location, and noise level
- Allows authorities to monitor real-time data and violation history.

IX. FLOWCHART OF METHODOLOGY

The flowchart shows the step-by-step working of the real-time noise monitoring system, starting from sound input detection to noise classification, camera-based verification, and final alert generation. It outlines how the IoT sensors, controller, and ML algorithm work together to identify noise and report violations efficiently [11].

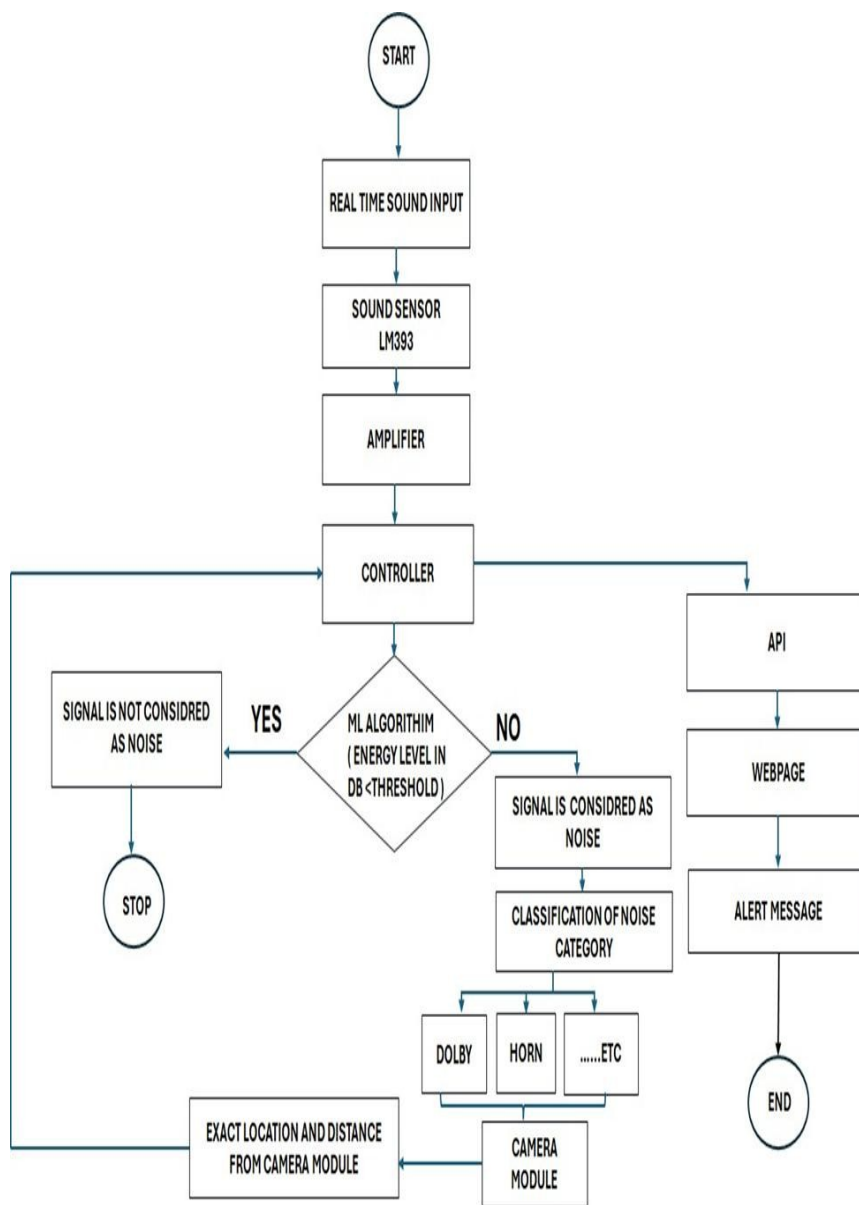


Fig9.1flowchartof methodology

- 1) Start–Thesystembeginsitsoperationandpreparesforcontinuous monitoring.
- 2) Real-TimeSoundInput–Environmentalsoundiscaptured continuously from the surroundings.
- 3) SoundSensor(LM393)–TheLM393sensordetectsacoustic signals and converts them into electrical form.
- 4) Amplifier – The captured analog signal is amplified to make even low-intensity sound measurable.
- 5) Controller – The amplified signal is processed and forwarded for machine learning evaluation.
- 6) MLAlgorithm (Energy Level in dB vs Threshold) –
 - Thesignalisanalysedtodeterminewhetheritexceedsthepredefined noise threshold.
 - IfYES→Thesignal is not considered as noise; the system returns to monitoring mode.
 - IfNO→Thesignal is considered as noise and proceeds for classification.
- 7) ClassificationofNoiseCategory–Thedetectednoiseiscategorized (e.g., Horn, Dolby, etc.)
- 8) Camera ModuleActivation – When noise is detected, the camera moduleidentifiestheexactlocationanddistanceofthenoisesource.
- 9) PICommunication–Theclassifiednoisedataandcameraoutputs are sent to the web interface through the API.
- 10) WebpageDisplay–Real-timedataisdisplayedonthewebpagefor monitoring by authorities or users.

- 11) AlertMessage – A notification containing noise details and location is generated and sent.
- 12) End – Indicates completion of the detection and reporting cycle, after which the system continues monitoring.

X. CHALLENGES AND RESEARCH GAPS

In spite of significant advancements of the IoT-based environmental and noise monitoring systems, various technical and operational hurdles are yet to be overcome in their real-world adoption. Most sensor-based experiments conducted so far are either at prototype stage or short-term operational, making it difficult to draw conclusions on system scalability, robustness and aging behaviour of the system in real urban environment [1], [11]. The majority of such deployment is based on low-cost acoustic sensors that are susceptible to environmental conditions such as temperature/humidity fluctuation, airflow and vibration etc. These, in turn lead to slight drifts in measurements and signal degradation hence necessitating frequently calibration and compensation approaches [6], [13].

The reliability of communications in the operating environment constitutes another problem, especially in the context of wide-area monitoring. While low-power communication systems as LoRa WAN or NB-IoT provide the extended coverage, problems such as packet loss, delay, bandwidth limitations and network congestion remain poorly addressed in dense urban setup [1], [5]. Power consumption due to continuous sampling of sound, on-wire transmission and active imaging is also an unresolved issue and limits the overall system lifetime in battery-powered settings [11], [15]. In terms of data-processing, static threshold-based decision mechanisms have been implemented in many cases where the acoustic background noise levels are dynamic and change with the time of the day [7]. There is very limited application of Machine learning principles leading to imprecise noise classification, anomaly detection and short-term or long-term temporal modelling [8]. Furthermore, multimodal data-fusion techniques, which combine acoustic signals with images/ video, spatial and textual context information are yet to take hold [12].

Further, significant domain knowledge is necessary to operationalize the developed system in terms of policy and urban planning at large. Most of the existing systems do not seamlessly integrate with the urban infrastructure, such as smart city platforms or municipal dashboards, and do not work in conjunction with policy framework or form basis for implementation in multiple cities and regions [3], [14].

XI. FUTURE RESEARCH DIRECTIONS

Future works could explore the design of AI-enabled adaptive thresholding strategy that can adaptively tune the noise thresholds based on time, location, and environment dynamics to achieve false alarm reduction. The idea of Edge intelligence can be added on to perform time-sensitive feature extraction and classification on IoT nodes locally to reduce communication latency and energy consumption. Innovative multimodal data fusion methods of acoustic, camera spatial information, global positioning system (GPS), environment factors are highly needed to improve noise source localization and full awareness of the system and life context. Privacy-protection mechanism is highly desired such as anonymized image processing and encryption communication. Urban data fusion with smart city network, public health records, urban traffic can lead to government decision making and personal long-term noise exposure study. Large dataset collection and long-term field experiments are also required for system robustness improvement and response stability in different real-world scenario.

XII. CONCLUSION

This research establishes a practical and deployable framework for real-time environmental noise surveillance by integrating IoT sensing, machine-learning-based classification, and camera-assisted spatial validation. The system was evaluated across traffic corridors, residential areas, and institutional environments using 1,020 recorded sound samples, comprising both background noise and violation events. After signal conditioning, the LM393 acoustic sensor demonstrated a measurement deviation of approximately ± 3 dB, which is consistent with the expected performance of low-cost IoT sound sensors.

Using amplitude, frequency variation, and temporal energy features, the trained classification model achieved an overall detection accuracy of 61.3%. It showed balanced precision and recall, indicating reliable baseline performance for detecting noise violations. About 45% of recorded eventsexceeded the 70 dB threshold, confirming the system's ability to tell apart critical and non-critical acoustic conditions in real environments. The addition of camera-based spatial validation further improved the detection process by confirming more than half of the acoustically identified violations. This reduced uncertainty caused by transient or overlapping sound sources. Despite the limitations of low-cost sensors, using machine-learning-based filtering significantly improved performance compared to traditional threshold-only methods. With stable real-time operation and low alert latency, the proposed platform is suitable for ongoing smart city deployment. Future updates, including adaptive calibration, larger datasets, and deep-learning models, can enhance system accuracy, robustness, and scalability.

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