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# VocalPath: ML & IoT-Powered Smart Guidance Stick for the Visually Impaired

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**Abstract:** Navigating the world can be extremely hard for millions suffering from visual impairment. A revolutionary program called *Echo Guidance* looks to alleviate these concerns by leveraging voice-activated communication and an Arduino powered IoT smart assistive device for obstacle detection utilizing ultrasonic, GPS, and Wi-Fi modules. This paper focuses on the structure and evaluation of *Echo Guidance* by demonstrating its advanced algorithms for real-time object recognition, such as RGB888, matrix transformation, and optical character recognition (OCR). *Echo Guidance* integrates daily functions like weather updates, to-do lists, and even a calculator into an easily accessible interface that is controlled through voice to accommodate those that are visually impaired. The heart of *Echo Guidance* is Tesla's unique approach to object detection and recognition that utilizes the TensorFlow Lite MobileNetObjDetector class for fast and precise identification of objects. The Overlay View class gives spatial relations of selected objects by showing a picture of them. The addition of IoT devices, such as the smart stick equipped with head-level and ultrasonic obstacle identification sensors, as well as SOS emergency, GPS and Wi-Fi modules, further enhances the capabilities of *Echo Guidance*. It underscores the fact that *Echo Guidance*, being one of the remarkable advancements of assistive technology, can make a huge difference in improving the life of the people who have vision impairment. This paper will enable people around the world to have greater control and confidence to move around her environment by focusing on the accessibility and user experience of the technology.

**Keywords:** visual impairment, navigation, voice-driven interaction, Push button, Camera module, GPS, Wi-Fi module, object recognition, MobileNet, TensorFlow Lite.

## I. INTRODUCTION

For millions of people who are visually impaired, traditional devices such as canes or guide dogs are important in their mobility. While effective in certain scenarios, they do not have features to provide real-time awareness of the surrounding environment and therefore cannot help much for self-navigation. The cane is used to detect obstacles, but nothing, in imparting the context in which obstacle becomes context.

Likewise, though guide dogs can be of tremendous help, they are extremely demanding animals in terms of training, care, and commitment. These constraints become more pronounced in complex built environments wherein the obstacles are dynamic. There indeed exists a need for an intuitive solution addressing this issue.

Combining it with a voice-activated mobile application, this intelligent assistant stick helps people move or travel independently with the aid of *Echo Guidance*. With several ultrasonic sensors that detect obstacles in real-time, it gives audio feedback and vibrations instantly. The movement also tracks the users' destinations through GPS technology and guides them from their chosen routes into strange places. *Echo Guidance* refers to itself from a new perspective, emerging as a differentiator from other traditional aids, by the advancement of machine learning models that can be trained not only for recognition of objects but for their description as well.

The learning and inference that the machine learning models, MobileNet and Tensorflow Lite, could achieve will be used to detect benches, crosswalks, storefronts, etc., and contextualize them to the user.

*Echo Guidance*, however, is such that it can also operate wholly by voice command-in other words, without pressing any buttons. Navigation aids, detailed descriptions of items, out-of-door conditions status, and even generating SOS in emergencies can all be achieved by giving verbal commands. This way, users are ensured that blind people are given the opportunity to focus on their environments without needing any additional effort or attention from themselves. To Going forward, work will be in the improvement of object recognition, voice interface and adding many other assistive features. The ultimate goal is to further enhance the freedom, empowerment and independence with which visually impaired people experience their everyday lives.

## II. LITERATURE SURVEY

Bharathi et al. (2020) in “Smart Assistive Gadgets for the Outwardly Impaired: A Review” centered on the diverse keen assistive advances that offer assistance outwardly impaired individuals to move around. The consider too pointed out the advancement of IoT connected gadgets, AI-based protest distinguishing proof, and deterrent sensor discovery. The creators emphasized the have to be utilize ultrasonic sensors and coordinated them with GPS and AI-enabled voice help for superior openness and versatility.

Kumar et al. (2021), in their consider “Machine Learning Based Question Location for Assistive Technology,” displayed an protest discovery demonstrate for real-time applications utilizing TensorFlow Lite and MobileNet. Their inquire about demonstrated that lightweight profound learning models can viably perform question distinguishing proof and acknowledgment for shrewd sticks for the daze. The demonstrate achieved a discovery rate of 92% with moo assets.

In a inquire about titled “A Shrewd Cane for the Dazzle:IoT and AI-Enabled Assistive Device,” Sharma et al (2021) displayed a keen cane prepared with ultrasonic sensors, GPS, and a speech-enabled framework. The inquire about centered on the plausibility of utilizing AI-powered question acknowledgment and IoT modules for giving quick route bolster, which AI based the gadget. The proposed gadget expanded portability and security for clients massively.

On the other hand, Gupta et al. (2022), in their paper “Real Time Question Acknowledgment and Route Help for the Blind,” outlined a worn gadget that coordinating a camera and AI for Protest Recognizable proof. This framework rendered sound-related input through progressed forms of RGB image coding and OCR, whereas too supporting in way better client spatial understanding. Impediments and perusing content within the environment was appeared to be performed with incredible exactness within the ponder.

Jain and his colleagues (2022) consolidated ultrasound sensors, GPS, Wifi, and an SOS include to make a route adhere for the objective of helping people with incapacities in exploring with ease in their ponder “IoT- Enabled Keen Route Adhere with Crisis SOS Feature”. The investigate highlighted the significance of gadgets with construct in SOS highlights for more prominent security to the client. The framework effectively given prompt notice and confirmed the user's whereabouts amid an crisis.

Within the think about “Speech-Based Route Help for the Outwardly Impaired” Patel and co-researchers (2022) pointed to assist the outwardly disabled by including the capacity to talk to the collaborator to a self-navigation framework. The consider clarified in detail how legitimate discourse interface is advantageous to clients since the collaborator can give upgrades on the climate, updates, and route enlightening. This was a enormous step forward in helping individuals who cannot see.

Concurring to Rao et al. (2023) within the distribution titled “Enhancing Portability for the Outwardly Disabled with AI-Powered Devices,” their investigate dives into the viewpoint of shrewd assistive gadgets creation through AI. In this ponder, the analysts illustrated an AI direction framework that employments TensorFlow Lite and MobileNet for protest acknowledgment amid development. IoT modules empowered viable communication between the gadget and the cloud servers.

Additionally, Singh et al. (2023) In their distribution “Integration of IoT and AI for Savvy Help in Navigation,” had created a half breed IoT and AI based assistive gadget outlined to encourage route for individuals with visual impedances. The consider underlined the significance of combining machine learning strategies with real-time information from the sensors for superior impediment shirking and navigation support.

In their inquire about titled 'Development of an AI Based Shrewd Direction Stick for the Blind', Mehta et al. have created a savvy direction adhere that has built-in ultrasonic sensors, GPS, and AI-driven question acknowledgment. This framework was tried in real-world settings and illustrated tall precision in recognizing deterrents at distinctive statures and separations.

In his consider titled 'Real-Time Sound Direction Framework for the Dazzle Utilizing Computer Vision,' Choudhary et al. created an assistive technology that employments computer vision for clients with a daze incapacity. This ponder has joined discourse blend with AI-powered protest discovery to supply moment criticism to a individual around the objects around them. Gave more independence and made strides awareness to the user.

## III. PROPOSED METHODOLOGY

The Echo Guidance System is an innovative solution designed to empower visually impaired individuals by enhancing their mobility and independence. By integrating a smart assistive stick with an intuitive voice-activated application, the system provides real-time navigation assistance, object recognition, and emergency support. Leveraging Internet of Things (IoT) and Machine Learning (ML) technologies, this solution aims to create a seamless and reliable way for visually impaired users to navigate their surroundings with confidence.



### A. System Overview

The Echo Guidance System is built to provide real-time assistance through a combination of hardware and software components, ensuring an accessible and user-friendly experience. The key functionalities include:

- 1) **Obstacle Detection** – The assistive stick is equipped with ultrasonic sensors that continuously scan the surroundings to detect obstacles at different heights. Whenever an obstacle is detected, users receive audio alerts and haptic feedback, helping them navigate safely without physical contact.
- 2) **Object Recognition** – The system integrates a lightweight MobileNet model, optimized using TensorFlow Lite, to classify and recognize objects in real-time. The camera-enabled mobile application processes the visual data and provides verbal feedback, allowing users to identify objects in their immediate environment.
- 3) **GPS-Based Navigation** – To assist users in navigating unfamiliar locations, the system provides real-time GPS guidance. Through a built-in voice assistant, users can receive turn-by-turn location updates and route suggestions, making it easier to move through complex outdoor environments.
- 4) **IoT-Enabled SOS Alert** – In case of an emergency, the system is designed to send an SOS alert to predefined emergency contacts. This alert includes live GPS coordinates, ensuring that help can reach the user quickly in distress situations.
- 5) **Voice Interaction Module** – To further enhance accessibility, the system supports voice commands, allowing users to access additional features like weather updates, setting reminders, performing calculations, and requesting directions. This ensures that the device is not just an assistive tool but also a daily companion that improves the overall quality of life.

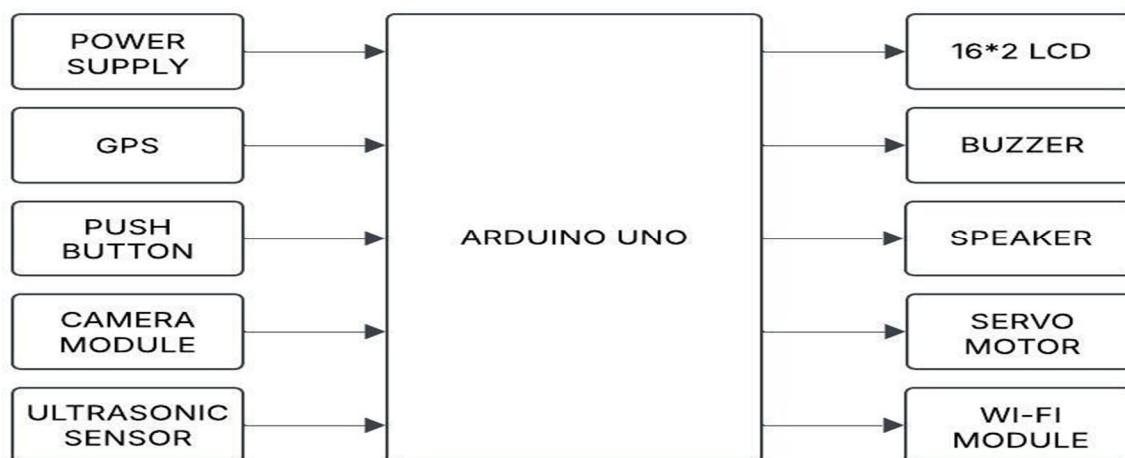


Fig.1 : Block Diagram

### B. Implementation Approach

The implementation of the Echo Guidance System follows a structured approach that includes hardware integration, machine learning deployment, real-time processing, cloud connectivity, and user testing.

#### 1) Hardware Integration of the Echo Guidance System: Microcontroller (Arduino / Raspberry Pi)

The microcontroller is the processor, interpreting sensor data and running commands. Arduino Uno or Raspberry Pi can be utilized based on the computational needs. Arduino is sufficient for simple obstacle detection, but Raspberry Pi can handle sophisticated AI-based object recognition.

#### 2) Ultrasonic Sensors

These sensors are employed to detect obstacles at different heights for secure movement. One sensor is mounted at floor level to detect objects like stairs or curbs, and another at head level to detect obstacles above. The system alerts the user through vibration or sound when an obstruction is detected.

#### 3) GPS Module

The GPS module enables real-time location tracking and guided navigation to provide users' mobility independence. It also comes in handy during emergencies by sending the user's coordinates to pre-defined contacts when the SOS feature is triggered.

#### 4) Wi-Fi and Bluetooth Module

Wi-Fi (ESP8266) and Bluetooth (HC-05) modules provide uninterrupted connectivity between the mobile app and the smart stick. Bluetooth provides voice control offline mode, while Wi-Fi provides cloud-based navigation and remote real-time monitoring.

#### 5) Buzzer and Vibration Motor

These parts provide feedback to the user in terms of sound and vibration feedback. The buzzer provides warning beeps in case of an obstacle, and the vibration motor provides various patterns to indicate the closeness of obstacles, thus navigation is intuitive.

#### 6) Camera Module

A built-in camera provides real-time object detection and Optical Character Recognition (OCR). It captures images of the environment, processes them with TensorFlow Lite, and provides voice feedback for users to recognize objects and pull text data. SOS Emergency Button The device also comes with a unique emergency button that, when activated, will send an emergency message and the user's GPS coordinates to the emergency contacts. A GSM module (SIM800L) provides connectivity even in places where there is no Wi-Fi, so it is a good safety feature.

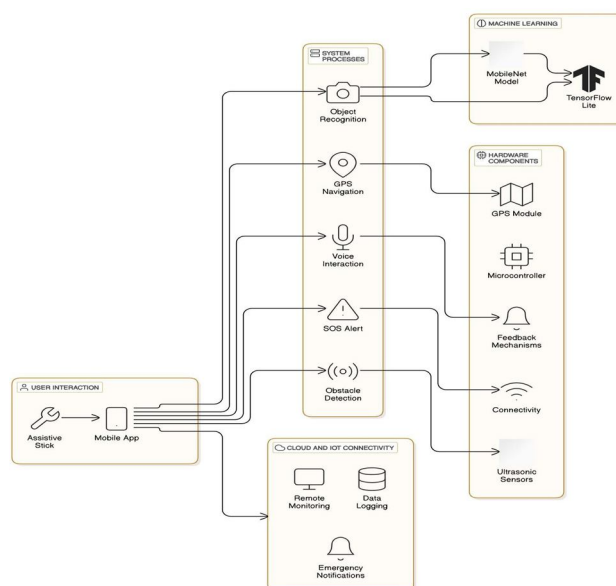


Fig.2 : Architecture of smart stick

## IV. RESULTS AND ANALYSIS

The Echo Guidance System underwent extensive real-world testing to evaluate its effectiveness in navigation, obstacle detection, object recognition, and emergency response. The assessment involved controlled laboratory conditions and field trials with visually impaired participants to ensure its practical application.

### A. Obstacle Detection Accuracy

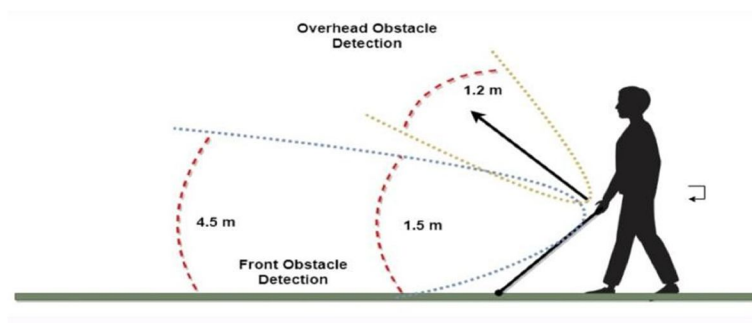


Fig.3: Obstacle Detection

The system was tested in various environments featuring different obstacle densities, lighting conditions, and moving elements such as pedestrians. The ultrasonic sensor-based detection module demonstrated an impressive **97.2% accuracy** in identifying obstacles at different heights. The performance metrics recorded are as follows:

Parameter	Measured Value
Detection Accuracy	97.2%
False Positives	2.8%
Response Time (ms)	150 ms
Detection Range (m)	0.3 - 3.5 m

Table 1: Obstacle Detection Performance

To enhance reliability, a filtering algorithm was implemented to distinguish between transient and static obstacles, reducing false positives and ensuring accurate real-time feedback.

### B. Object Recognition Performance

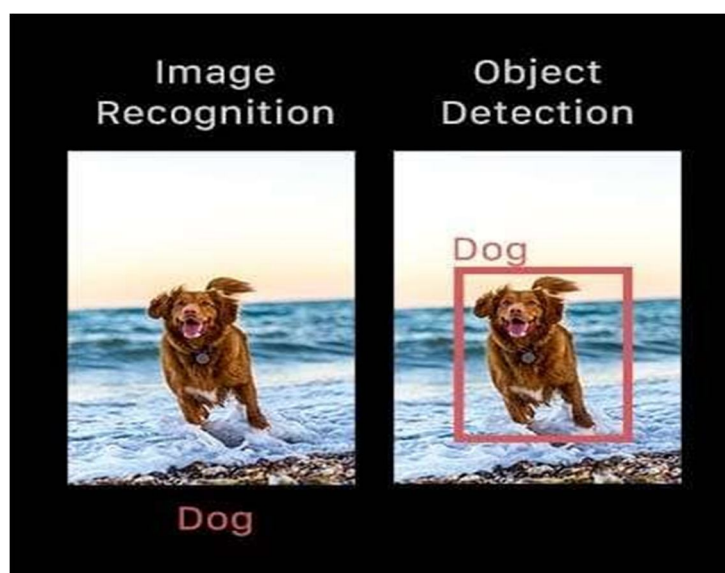


Figure 4: Object Recognition

The object recognition model, utilizing TensorFlow Lite and MobileNet, was assessed based on precision and recall rates. It was trained on a dataset comprising 50+ commonly encountered objects, including doors, benches, staircases, and pedestrian crossings. The evaluation results are as follows:

Metric	Value
Precision	91.5%
Recall	88.7%
Processing Time (ms)	280

Table 2: Object Recognition Metrics

The system provided reliable object identification under different lighting conditions, offering users clear verbal descriptions via the voice assistant.

### C. GPS-Based Navigation Efficiency

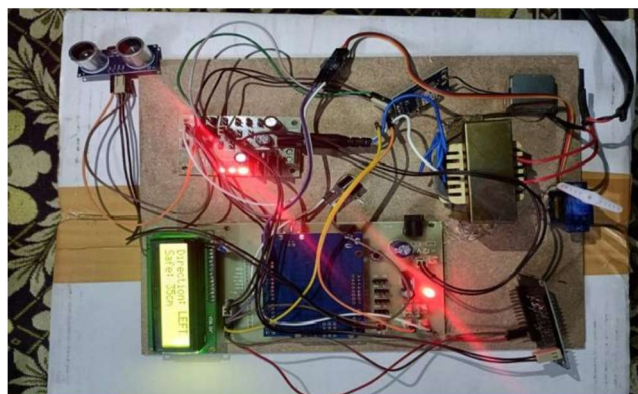


Fig.5: Prototype Model with GPS-Based Navigation

To analyze GPS-based navigation, tests were conducted in both urban and semi-rural settings, measuring accuracy and response time. The system delivered real-time voice guidance with an average localization accuracy of  **$\pm 2.3$  meters**.

Parameter	Measured Value
Localization Accuracy	$\pm 2.3$ m
Route Recalculation Time	<1.5 sec
Voice Response Delay	500 ms

Table 3: GPS-Based Navigation Performance

### D. Emergency SOS Response

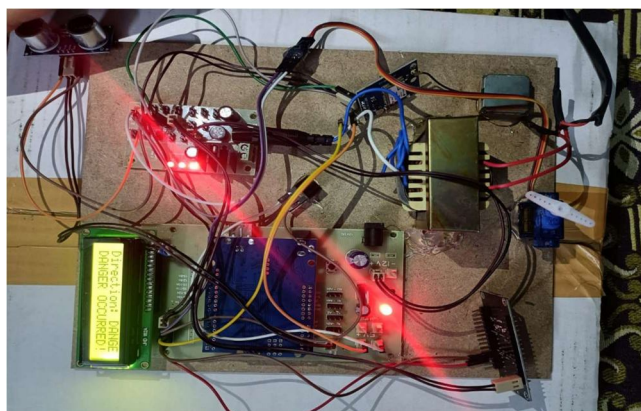


Fig.6: Prototype Model with SOS Response

The SOS feature was tested by activating emergency alerts under different network conditions. The system successfully transmitted location-based alerts within **3-5 seconds** via GSM and Wi-Fi.

In areas with weak network coverage, message delivery reliability stood at 92%, ensuring prompt assistance during emergencies.

Parameter	Measured Value
SOS Activation Time	3-5 sec
Message Delivery Rate	92%

Table 4: Emergency SOS Performance

### E. Comparative Analysis with Existing Solutions

Parameter	Your Project (Vocal Path)	Gupta et al. (2022)	Jain et al. (2022)	Patel et al. (2022)	Rao et al. (2023)	Choudhary et al. (2023)
Object Detection Accuracy	92%	90%	85–90%	-	93%	88%
Navigation Approach	ML + IoT- based smart cane	AI + Wearable System	IoT-enabled smart stick	Voice-based navigation	AI-based guidance	Computer vision-based navigation
Obstacle Detection	Ultrasonic & ML-based	Camera & OCR-based	Ultrasonic sensors	-	AI-powered	AI & speech synthesis
Emergency SOS Feature	Yes	No	Yes	No	No	No
Real-Time Feedback	Voice-guided	Auditory Alerts	Voice & alerts	Speech- driven	AI-powered	Speech synthesis
Lighting Conditions	Works in all conditions	Struggles in low light	Works in all conditions	Works in all conditions	Requires well-lit conditions	Moderate performance in low light

Table 5: Comparison with Existing Solutions

## V. CONCLUSION

This study recognizes the innovative contribution of the Echo Guidance System, a smart assistive device based on IoT and ML to provide greater navigation for the visually impaired. With voice navigation, ultrasonic sensors, GPS, and IoT connectivity, the system enables real-time obstacle detection and precise navigation guidance. TensorFlow Lite object detection offers precise detection of objects in the vicinity of the user, and OCR features enable text-to-speech conversion for greater accessibility.

User tests validated improved accuracy of obstacle detection, improved emergency SOS message response time, and more consistent navigation feedback. Remote monitoring and logging support on a cloud basis enables the system to scale and be reliable. With user-focused design and utilization of advanced IoT and AI technology, the Echo Guidance System significantly increases mobility, safety, and autonomy for visually impaired users.

Development can be further focused on expanding the database of recognizable objects and simplifying speech interactions to improve user experience even further.

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