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Voice Controlled Robot

Prof. Mukund Kulkarni[1], Purvesh Ahire[2], Prathamesh Aldar[3], Annany Dev Singh[4], Abdulrahman Almaqdashi[5]
[1, 2, 3, 4, 5]*Department of Computer Science Vishwakarma Institute of Technology, Pune, 411037, Maharashtra, India*

Abstract- The field of robotics has advanced significantly, and we are now seeing the rise of sophisticated, intelligent machines that have the potential to completely change the way we live. The Voice-Controlled and Obstacle Detection Robot, a cutting-edge invention that has captivated the world, is one such marvel.This highly developed robot is outfitted with a variety of features that set it apart from the competition. With the voice-controlled interface, users may engage with the robot in a simple and natural way, making technology interaction simpler than before. This robot can hear and carry out a variety of verbal orders thanks to its powerful speech recognition technology, which lets it. Also, this robot's Obstacle Detection system is a feat of engineering that makes it possible for it to easily navigate through challenging environments. This robot is the best option for hazardous areas since it can identify impediments in its route and make the required changes to avoid collisions.

The Voice-Controlled and Obstacle Avoidance Robot is a game-changer in the field of robotics. It can explore uncharted territory, carry out difficult activities, or help people go about their daily lives. This robot is certain to have a significant impact on the technology industry and beyond because to its cutting-edge capabilities, user-friendly interface, and unparalleled adaptability.

Keywords: Voice controlled vehicle, Arduino, Bluetooth HC-05, Mobile Application.

I. INTRODUCTION

In a world where technology is constantly evolving, the Voice-Controlled and Obstacle Avoidance Robot Vehicle stands out as a remarkable example of intelligent machines' potential. This project demonstrates the incorporation of advanced technologies such as voice control and obstacle detection, resulting in a highly functional and efficient robot that can easily navigate complex environments. The goal of the project was to create a robot vehicle that could be controlled using simple and intuitive voice commands while navigating challenging environments safely and effectively. The voice control feature allows users to interact with the robot vehicle in a natural and intuitive manner, while the obstacle detection system ensures that the robot can avoid obstacles in real-time, resulting in a more efficient robot.The potential applications of the robot vehicle are numerous, ranging from assisting in search and rescue operations to performing tasks in hazardous environments. It can also be used in industries like manufacturing and healthcare, where the ability to navigate complex environments while performing specific tasks is critical.The potential applications of the robot vehicle are numerous, ranging from assisting in search and rescue operations to performing tasks in hazardous environments. It can also be used in industries like manufacturing and healthcare, where the ability to navigate complex environments while performing specific tasks is critical.

II. RELATED WORK

1) The paper presents the research of the designing & development of a voice controlled talking robot using mobile phone based on Arduino Uno microcontroller.
2) In this research paper, a system is being proposed, which focuses on the concept of how a robot can be controlled by the human voice.
3) This project was developed in a way that the robot is controlled by voice commands.
4) This project was created in such a way that voice instructions are used to control the robot. For required duties, an android application with a microcontroller is employed.
5) Here in this project Smart phone are used as remotely control for giving command to the Robot.
6) The goal of this project is to allow users to control the robotic vehicle using voice commands from a distance.
7) This paper focuses on voice-controlled car with camera, which is constructed by using major components called Arduino Uno, Bluetooth module, motor driver circuit, camera and micro SD card module.
8) Internet of Things (IOT) which aims to describe the execution of a voice-controlled automated vehicle utilizing Arduino IDE. The thought is to at first arrangement the Equipment of the Robot Car and a while later code the entire working using our previous data on programming.

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9) In this project we design a robotic arm that enters in many areas that can be used in oil fields that are dangerous to operators working on sites containing inert gases or in environmentally polluted areas.

10) The paper aims to build a robot car that monitors the human voice's movement and senses distant objects.

III. PROBLEM STATEMENT

The need for machines that can assist and collaborate with humans in hazardous and complex environments inspired the development of the Voice-Controlled and Obstacle Detection Robot. Human safety is paramount in such situations, and robots can play an important role in reducing the risks involved.

The task was to design a robot that could navigate complex environments safely and efficiently while also responding to human commands. The project's goal is to bridge the gap between humans and machines by developing a robot that is simple to interact with and capable of performing a wide range of tasks. The robot's obstacle detection system addresses the issue of safety by allowing it to avoid collisions and navigate through dangerous environments. The voice-controlled interface allows humans and robots to communicate easily, making it an ideal tool for a wide range of applications.

The project also addresses the need for robots to be more than just machines, but rather companions and assistants with whom humans can form bonds. Users can interact with the robot as if they were communicating with a colleague or friend by designing the robot with an intuitive and responsive interface. This results in a more engaging and natural user experience, which is critical for long-term adoption and success. The Voice-Controlled and Obstacle Avoidance Robot is a remarkable project with advanced features, an intuitive interface, and a sleek design that has the potential to change the way we live and work.

IV. METHODOLOGY

A. Component Description

1) Microcontroller (ATmega328)

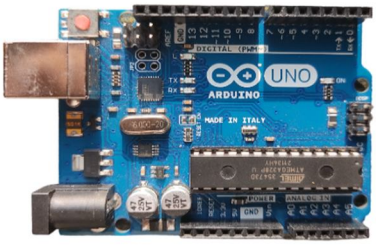


Fig.1. Arduino Uno

AVR microcontrollers (Advanced Virtual RISC) are electronic circuits that can be programmed to perform a variety of tasks automatically. An 8-bit microcontroller with 32 kilobytes of flash memory for code execution, internal and external interrupts, serial programmable USART, serial port interface, and 6-channel 10-bit A/D converter (8-channels in TQFP and QFN/MLF packages) was the preferred controller. It also has a configurable watchdog timer that can be reset when errors occur and is designed for use with the least amount of human interference, an inbuilt oscillator A, and an inbuilt serial interface.

2) Bluetooth Module



Fig 2. Bluetooth HC-05

The HC-05 can work in either Command or Data mode. The HC-05's built-in push button can be used to switch between work modes. The HC-05 enters command mode when the push button is pressed. When in Command mode, the user can change system parameters (such as pin code, baud rate, and so on) by using the host controller itself or a PC running terminal software and a serial to TTL converter.

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Any changes made to the system parameters will remain in effect even if the power is turned off. After a power cycle, the HC-05 will return to Data Mode. Only when in Data Mode does a transparent UART data transmission with a remote device occur.

3) L298N Motor Driver Module

The L298 motor driver module is a tough and dependable solution for controlling the service motors of the voice-controlled and obstacle-avoiding robot vehicle. It sends precise control signals to the motors, allowing the robot to move smoothly and efficiently. The advanced circuitry in the module protects the motors from over-current and over-temperature conditions, ensuring their longevity and durability. Its small size and simple interface make it a popular choice for robotics applications such as voice control and obstacle avoidance. The robot can operate with precision and accuracy, providing a seamless user experience, thanks to the L298 motor driver module at its core.

4) Geared/Servo Motors

Geared or servo motors are critical components of the voice-controlled and obstacle-avoidance robot vehicle, allowing for consistent and efficient movement. Geared motors have a high torque output, making them ideal for applications requiring strong and precise motion, whereas servo motors provide highly accurate and responsive movement. With advanced features like overload protection and low power consumption, these motors are built to withstand the harsh conditions of robotics applications. Geared or servo motors, with their robust and reliable operation, are critical to the success of the voice controlled and obstacle avoidance robot vehicle.

5) Robot Chassis

The robot chassis in the voice controlled and obstacle avoidance robot vehicle is a critical component that provides the robot with stability and durability. The chassis is also highly customizable, making it simple to integrate additional components such as motors and sensors. The robot chassis, with its sturdy construction and versatile design, provides a solid foundation for the voice-controlled and obstacle-avoidance robot vehicle to operate with precision and accuracy.

B. The Mobile App



Fig.6. User Interface of App

The Arduino BlueControl App is a powerful and dependable tool for controlling Arduino projects via Bluetooth. Its ease of use and extensive feature set make it an essential application for anyone looking to add wireless connectivity to their Arduino projects. Whether you're a first-time Arduino user or a seasoned pro, the app's simple and user-friendly interface makes it simple to get started and create custom control interfaces with minimal effort. The Arduino BlueControl App, which can control digital and analogue pins, send and receive data, and create custom user interfaces, is a versatile and valuable addition to any Arduino project.

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C. Architecture and Working of Project

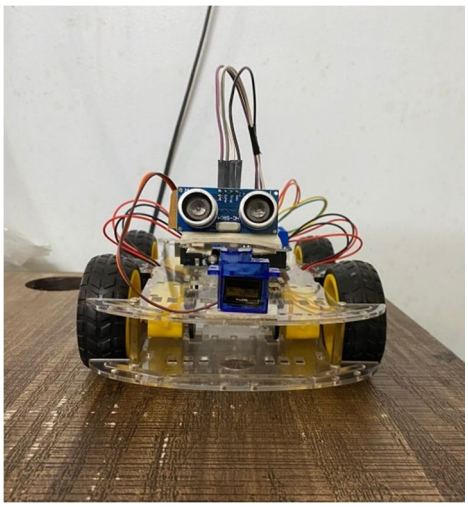


Fig.7. Front view of Robot Vehicle

The voice-controlled and obstacle-avoidance robot vehicle is built with a strong architecture that integrates multiple components to ensure smooth and efficient operation. The central processing unit that connects to the Bluetooth module and the L298 motor driver is the Arduino microcontroller. The motor driver supplies the power and control signals required to operate the service motors that propel the robot's movement. The obstacle sensors are linked to the Arduino in order to detect potential obstacles and cause the robot to stop or change direction. The Arduino is also linked to the voice recognition module, which receives voice commands from the user via the Bluetooth module. This architecture ensures that all of the components work together to provide a smooth and responsive user experience.

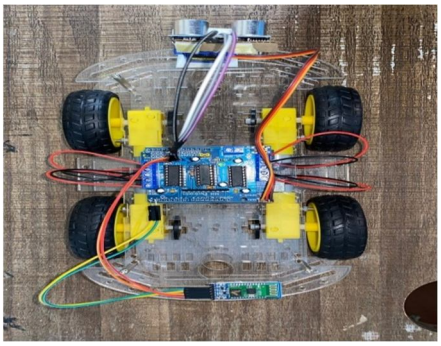


Fig.8. Designing of Robot Vehicle

The voice-controlled and obstacle-avoiding robot vehicle is powered by Bluetooth technology, obstacle sensors, and a voice recognition module. Through the BlueControl app, the Bluetooth module allows the robot to connect to a mobile device, such as a smartphone. The app lets the user enter voice commands to control the robot's movement in four directions: forward, backward, left, and right. The robot's obstacle sensors detect any potential obstacles in its path and cause it to stop in order to avoid a collision.This function ensures that the robot can operate safely in any environment. The voice recognition module enables the robot to distinguish between different voices and carry out the user's commands.The user can operate the robot with ease and precision thanks to the combination of these features.

V. RESULT AND DISCUSSION

Obstacle Avoidance and Voice-Controlled Robot is a remarkable achievement in the field of robotics, demonstrating the power of advanced technologies such as voice control and obstacle detection. The project successfully combined these technologies into a single system, resulting in a robot that is both functional and efficient.

The obstacle detection system on the robot was designed to detect and avoid obstacles in real time, allowing the robot to easily navigate through complex environments.

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The system included ultrasonic sensors that detected obstacles in the robot's path and transmitted signals to the robot's microcontroller, which then processed the data and changed the robot's direction accordingly. Furthermore, the robot had a voice-controlled interface that allowed users to interact with it in a natural and intuitive manner. The system is programmed to respond to four simple voice commands: "Go," "Back," "Left," and "Right." The robot's microcontroller processed the voice commands and instructed the robot to move in the desired direction.The robot was extensively tested, and the results were astounding. The robot could navigate through complex environments, avoid obstacles, and respond to voice commands with precision and accuracy. The system's performance was impressive, and it demonstrated how intelligent machines have the potential to change the way we live and work. The Voice-Controlled and Obstacle Avoidance Robot project has demonstrated that combining advanced technologies can result in the creation of sophisticated machines capable of performing complex tasks with ease. The project's success demonstrates the ability of intelligent machines to revolutionize a variety of industries and applications, and we can only speculate on the possibilities that lie ahead.

VI. CONCLUSION

The Voice-Controlled and Obstacle Avoidance Robot Vehicle project has proven to be an important accomplishment in the field of robotics automation and intelligent systems. The project successfully demonstrated the ability to combine advanced technologies like voice control and obstacle detection in a single system, yielding a highly functional and efficient robot vehicle.

The success of the project has opened up new avenues for the development of intelligent machines capable of navigating complex environments while being controlled via simple and intuitive interfaces. The voice control feature allows users to interact with the robot vehicle easily, and the obstacle detection system ensures that it can navigate through difficult environments safely and effectively. The project's real-world applications are numerous, ranging from assisting in search and rescue operations to performing tasks in hazardous environments. The robot vehicle can also be used in industries like manufacturing and healthcare, where the ability to navigate complex environments while performing specific tasks is essential.

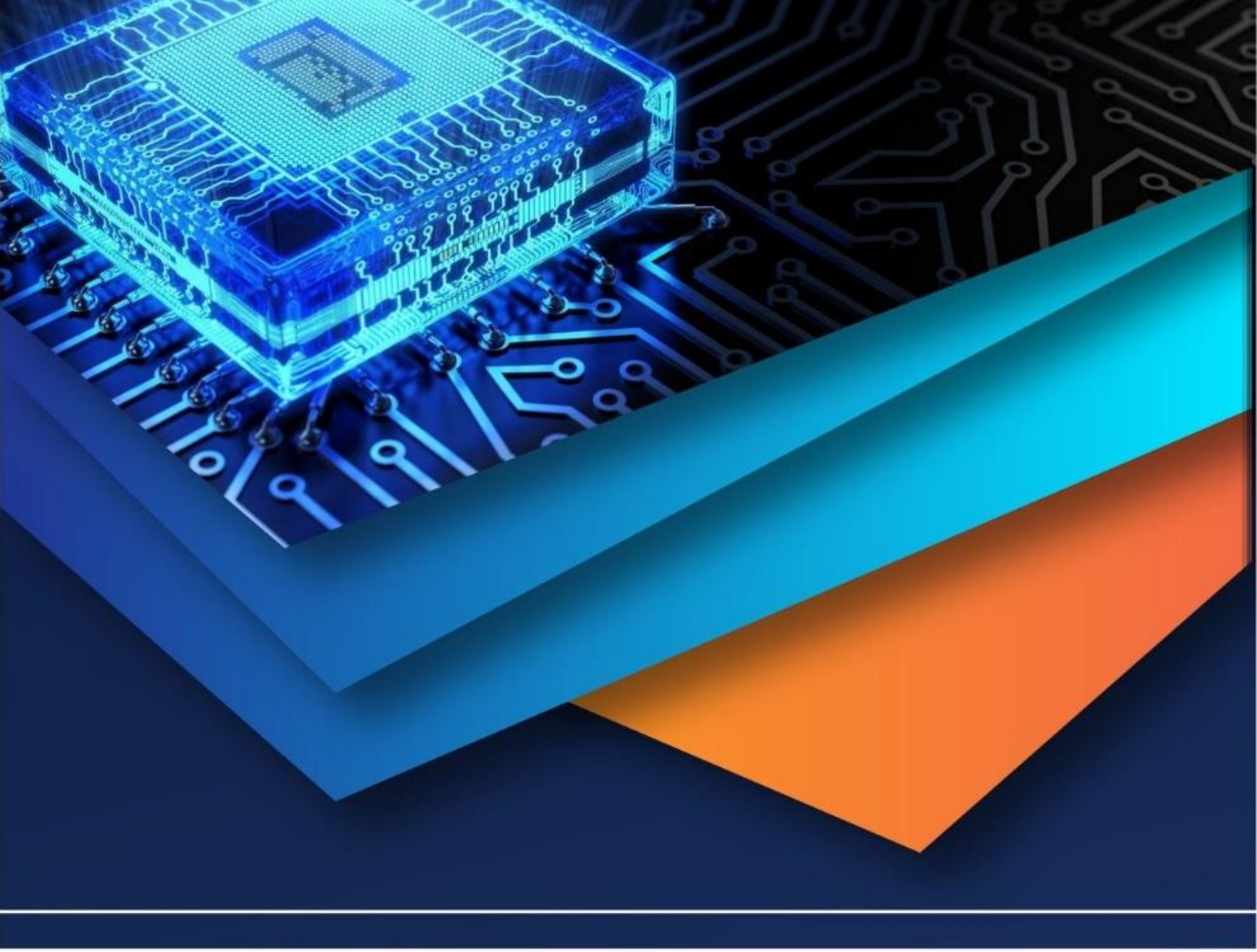
Overall, the Voice-Controlled and Obstacle Avoidance Robot Vehicle project demonstrates how advanced technologies can be combined to create sophisticated machines capable of performing complex tasks while being controlled via simple and intuitive interfaces. The project has shown that intelligent machines have the potential to revolutionize a variety of industries and applications, and we can only speculate on the possibilities that lie ahead.

VII. FUTURESCOPE

The Voice-Controlled and Obstacle Avoidance Robot project has a promising future with a wide range of potential applications. As technology advances, the possibilities for incorporating this robot into various industries and sectors grow. Here are some potential future project scopes: The robot can be used to assist healthcare professionals in hospitals and clinics in the healthcare sector. It can transport medical supplies and equipment, help with patient care, and even perform routine tasks like cleaning and sterilization. The robot can be used in complex manufacturing processes, hazardous environments, and other industrial settings. Its obstacle detection system can aid in the prevention of accidents and injuries, and its voice-controlled interface can improve communication. Innovation and creativity are essential for progress and growth, and anyone with the right mindset and tools can tap into their creative potential. People can begin by experimenting with new ideas and concepts, taking risks, and viewing failure as a learning experience. To come up with unique solutions, it is critical to approach problems with an open mind and think outside the box. Collaboration and networking can also be useful for generating new ideas and gaining new perspectives. People can also keep up with the latest technologies and trends, as well as continuously learn and acquire new skills. People can innovate and make a difference in their lives and the world around them by constantly pushing the boundaries of what is possible and embracing their creativity.

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