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# Fuzzy Logic based Fault Classifier for Protection of Transmission Line using Current Samples and Angular Differences

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**Abstract:** Fault classification technique for transmission line protection is suggested in this paper by Fuzzy logic. Proposed fault classification methodology requires three phase post fault current samples at one end of line post fault current phasor. All possible combination of faults involving three-phases and ground, can be classified, differentiating the faulted phase(s) from the non-faulted phase(s). Different test cases by varying fault resistance, fault distance and inception angle is used to verify adoptability of suggested technique. In MATLAB/ SIMULINK, simulation studies are done using SimPowerSystems and Fuzzy Logic Toolbox.

**Keywords:** Transmission line, Fuzzy logic system (FLS), Fault inception angle (FIA), Fault detection (FD), Discrete Fourier transform (DFT), Fault classification (FC).

## I. INTRODUCTION

The faults are unavoidable and can cause instability and unexpected failures in the transmission line. For protection of transmission line accurate detection and classification as quick as possible is must to achieve the stability again. An effective relaying system is able to respond the irregular condition, if identified, in the transmission line and isolate it from the rest healthy line of the system to prevent fault propagation into healthy part and safeguards the line from transient effects of the fault.

Artificial intelligence (AI) based systems such as artificial neural network (ANN), fuzzy logic, neuro-fuzzy etc. are the recent protection approaches. ANN-based fault location [1]-[4] and distance protection [5]-[7], fuzzy and fuzzy-neural-network [8]-[11] based operations are different fault classification techniques.

The ANN based approaches are precise to evaluate the fault nature, though, it require tedious training tactics to entire fault and operational settings such as fault resistance, fault inception angle, fault location, system pre-fault load, etc. On the other hand, the most important advantage of Fuzzy set is simple "If-Then" technique. Also, the fuzzy logic are simple and fast independent system, in comparison to ANN.

In [8], only LG (line to ground) and LLG (double line to ground) faults are classified, whereas in [1]-[7], [9] & [10] whether LG, LL, LLG or symmetrical fault i.e. nature of the fault is determined. In [11], all possible types of short circuit faults is evaluated with the use of only the magnitude and phase angle of three phase currents. Unluckily, the proposed fuzzy based logic in [11] delivers errors in high distances from relaying point, high system loading level and high fault resistance.

To avoid mentioned limitations an enhanced fuzzy logic-based method capable of high accurate fault classification of transmission line under variation of fault resistance, fault location, and fault inception angle is suggested using only amplitude of current signals from sending end side. Simulation of different fault cases is done to examine the performance of system.

## II. SIMULATION OF POWER SYSTEM NETWORK

A 220 kV, 50Hz transmission line system is used to develop the suggested approach with the use of fuzzy logic. Single-line diagram of the system is shown in Fig. 1. Two sources each of 220 kV located at both ends along with three phase fault simulator is present in the transmission line. Simulink and Sim Power System toolbox of MATLAB is used for the study.

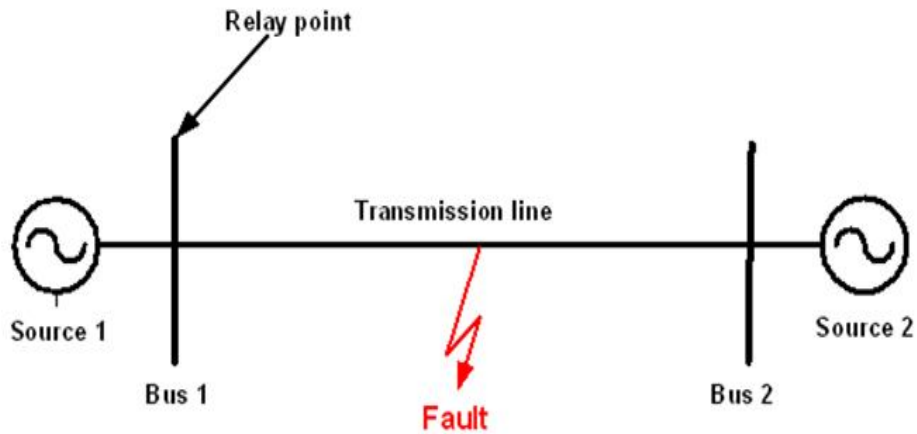


Fig.1 Single line diagram of simulated power system network

### III. FAULT CLASSIFICATION SCHEME

By extensive simulation studies carried out on the power system model shown in Fig. 1 using MATLAB, fault classification technique is developed. Post-fault samples of three phase currents are considered where magnitudes of each fundamental current signals recorded at the relay location. With the use of Discrete Fourier Transform (DFT) magnitudes of current signals are calculated as characteristic features and given as input for FLS. The fault classification algorithm based on fundamental magnitudes of phase currents and angular differences among the sequence components of the fundamental fault current.

The characteristic features are calculated in terms of  $\Delta 1$ ,  $\Delta 2$ ,  $\Delta 3$  and  $\Delta 4$  from the fundamental current magnitudes of the phase currents and the characteristic features are calculated in terms of  $\text{ang\_A}$ ,  $\text{ang\_B}$ , and  $\text{ang\_C}$  which are angular difference among the sequence components of the fundamental fault currents. These characteristics features are calculated as described below.

#### A. Characteristics Features Calculations using Current Magnitudes

From three First of all, from the post-fault current samples the ratios R1, R2 and R3 are calculated as follows:

$$R1 = \max \{ \text{abs} (Ia) \} / \max \{ \text{abs} (Ib) \}$$

$$R2 = \max \{ \text{abs} (Ib) \} / \max \{ \text{abs} (Ic) \}$$

$$R3 = \max \{ \text{abs} (Ic) \} / \max \{ \text{abs} (Ia) \}$$

Where Ia, Ib, Ic are the post-fault samples of the three phase currents. Next, the normalized values of R1, R2 and R3 are found out as follows:

$$R1n = R1 / \max (R1, R2, R3)$$

$$R2n = R2 / \max (R1, R2, R3)$$

$$R3n = R3 / \max (R1, R2, R3)$$

Finally, the differences of these normalized values are found out as follows.

$$\Delta 1 = R1n - R2n$$

$$\Delta 2 = R2n - R3n$$

$$\Delta 3 = R3n - R1n$$

To indicate the presence of ground in the fault the ratio of zero sequence current and positive sequence current is calculated as:

$$\Delta 4 = \text{abs} (Io) / \text{abs} (I1)$$

When  $\Delta 4$  exceeds the threshold value, it indicates that a fault involving ground has occurred otherwise a line-to-line fault not involving ground has occurred. The characteristic features of different types of fault are determined in of  $\Delta 1$ ,  $\Delta 2$ ,  $\Delta 3$  and  $\Delta 4$ .

#### B. Characteristics Features Calculations using Sequence Currents

For an example, when a phase-a-to-ground bolted fault occurs in an unloaded system, the phasor diagram of sequence components of fault currents is shown in Fig. 2.

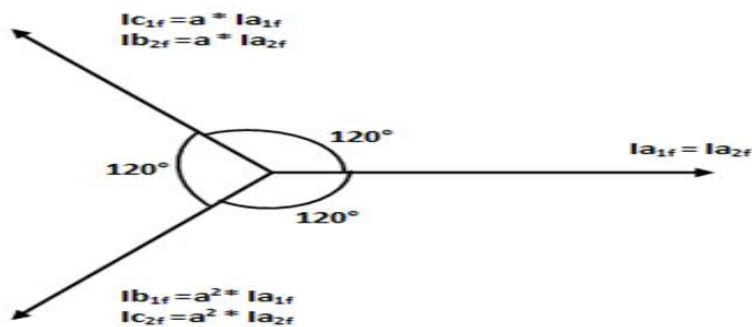


Fig. 2 Phasor diagram for a-g fault

In figure 2, the post fault currents relative to phase “a” are denoted as  $I_{a1f}$  for positive and  $I_{a2f}$  for negative sequence respectively. Similarly, the sequence components for phases “b” and “c” are denoted as  $I_{b1f}$ ,  $I_{b2f}$  and  $I_{c1f}$  and  $I_{c2f}$  respectively. The symbol “a” is a complex operator whose value is  $\alpha = 1 \angle 120^\circ$

From Fig. 2, the angles between the positive and negative sequence components of phase a, b, and c are given below.

$$\begin{aligned} \text{ang\_A} &= |\text{ang}(I_{a1f}) - \text{ang}(I_{a2f})| = 0^\circ \\ \text{ang\_B} &= |\text{ang}(I_{b1f}) - \text{ang}(I_{b2f})| = 120^\circ \\ \text{ang\_C} &= |\text{ang}(I_{c1f}) - \text{ang}(I_{c2f})| = 120^\circ \end{aligned}$$

Similar these relationships can also be written for other type of asymmetrical faults (i.e., b-g, c-g, a-b, b-c, c-a, a-b-g, b-c-g, and c-a-g) and these relations are given in Table 1.

For symmetrical faults, the zero and negative sequence currents do not present in the system. Hence, the angles  $\text{Ang\_A}$ ,  $\text{Ang\_B}$  and  $\text{Ang\_C}$  are not defined for this case. Now it is to be noted that the relationships given in Table 1 are only valid for solid faults in an unloaded system. On considering present pre-fault power level, fault location, fault inception angle and fault resistance, values of  $\text{Ang\_A}$ ,  $\text{Ang\_B}$  and  $\text{Ang\_C}$  will get varied from their ideal values (as given in Table 1). A large number of fault studies is carried out under varying combinations of fault location, fault resistance and fault inception angle and the values have been computed for each of these faults. From these data, the mean values of each of these three quantities have been calculated for each specific type of fault and subsequently, these mean values have been rounded to their nearest whole number.

For an example, the mean value of the variable has been found to be 26.75, which has been rounded to its nearest whole number (i.e., 30). Similar exercises have been carried out for the other variables also. Now, for subsequent reference, these rounded, nearest whole numbers would be termed as “approximate mean value.” These mean values are given in Table 2.

TABLE I  
FUNDAMENTAL RELATIONS FOR  
VALUES OF

Type of Fault	Ang_A	Ang_B	Ang_C
a-g	0°	120°	120°
b-g	120°	0°	120°
c-g	120°	120°	0°
a-b-g	60°	60°	180°
b-c-g	180°	60°	60°
c-a-g	60°	180°	60°
a-b	60°	60°	180°
b-c	180°	60°	60°
c-a	60°	180°	60°
Symmetrical	-	-	-

DIFFERENT QUANTITIES

TABLE II  
APPROXIMATE MEAN  
ASYMMETRICAL FAULTS

Type of Fault	Ang_A	Ang_B	Ang_C
a-g	30°	150°	90°
b-g	90°	30°	150°
c-g	150°	90°	30°
a-b-g	30°	90°	150°
b-c-g	150°	30°	90°
c-a-g	90°	150°	30°
a-b	30°	90°	150°
b-c	150°	30°	90°
c-a	90°	150°	30°
Symmetrical	-	-	-

**IV. DEVELOPMENT OF FUZZY LOGIC BASED FAULT CLASSIFIER**

A Fuzzy logic system (FLS) uses a collection of fuzzy membership functions and rules, instead of Boolean logic, to reason about data. Basically, a Fuzzy knowledge based system comprises of three parts, namely, Fuzzification, inference rules and Defuzzification which are described in the following sections.

*A. Fuzzification*

FLS has input variables  $\Delta 1, \Delta 2, \Delta 3, \Delta 4, \text{Ang\_A}, \text{Ang\_B}$  and  $\text{Ang\_C}$ . The output variables for FLS are Trip1, Trip2 which are expressed by  $u1$ , and  $u2$  respectively. The linguistic input variables contain two fuzzy subsets: 1) high (H); 2) low (L). The linguistic output variables contain two fuzzy subsets: 1) Trip high (TH); 2) Trip low (TL). Fuzzy ratings for input and output linguistic terms are shown in Table 3, 4, 5 and 6 respectively. Triangular-shaped membership functions are used for input and output variables as shown in Fig.3. The membership functions are selected on a hit and trial basis with the aim of improving the classification accuracy.

Table III  
fuzzy ratings for input  
Linguistic terms  $\Delta 1, \Delta 2, \Delta 3$

Linguistic terms	Fuzzy numbers
low	[-1 -0.5 0 ]
medium	[-0.1 0.1 0.3 ]
high	[ 0.12 0.55 1 ]

Table Iv  
fuzzy ratings for input  
linguistic terms  $\Delta 4$

Linguistic terms	Fuzzy numbers
low	[0 .015 0.03 ]
high	[0.03 0.55 1 ]

TABLE V  
FUZZY RATINGS FOR INPUT LINGUISTIC  
FOR OUTPUT  
TERMS  $\text{Ang\_A}, \text{Ang\_B}$  and  $\text{Ang\_C}$

Linguistic terms	Fuzzy numbers
Ang_A	[0 30 60 ]
Ang_B	[60 90 120 ]
Ang_C	[120 150 180 ]

TABLE VI  
FUZZY RATINGS

LINGUISTIC TERMS	
Linguistic terms	Fuzzy numbers
AG	[4.5 5 5.5]
BG	[9.5 10 10.5]
CG	[14.5 15 15.5]
ABG	[19.5 20 20.5]
BCG	[24.5 25 25.5]
CAG	[29.5 30 30.5]
AB	[34.5 35 35.5]
BC	[39.5 40 40.5]
CA	[44.5 45 45.5]
ABC	[49.5 50 50.5]

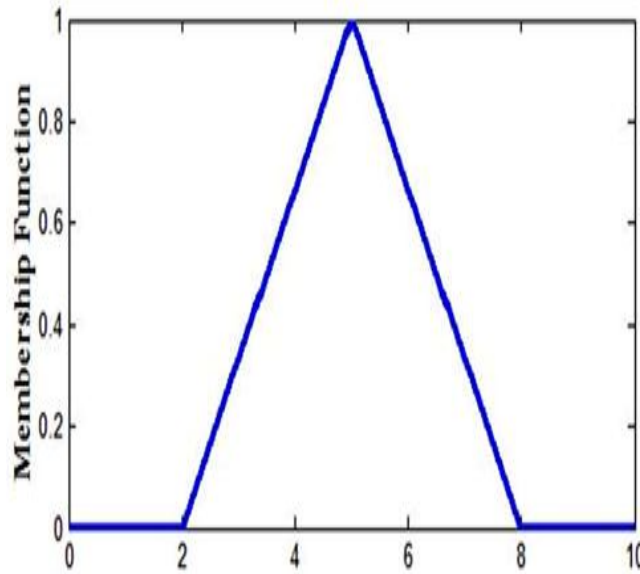


Fig. 3 Triangular membership functions for outputs of phase fault

### B. Fuzzy Inference Rules

To ensure the change trends of output variables, based on a set of extensive simulation, the rules of fuzzy knowledge based systems are given below. The output membership function of each rule is calculated by the MAX-MIN method proposed in the relative.

- 1) If  $\Delta 1$  is high &  $\Delta 2$  is medium &  $\Delta 3$  is low &  $\Delta 4$  is high &  $\text{Ang\_A}$  is  $\text{aprx}30^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}150^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}90^\circ$  then fault type is “a-g”.
- 2) If  $\Delta 1$  is low &  $\Delta 2$  is high &  $\Delta 3$  is medium &  $\Delta 4$  is high &  $\text{Ang\_A}$  is  $\text{aprx}90^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}30^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}150^\circ$  then fault type is “b-g”.
- 3) If  $\Delta 1$  is medium &  $\Delta 2$  is low &  $\Delta 3$  is high &  $\Delta 4$  is high &  $\text{Ang\_A}$  is  $\text{aprx}150^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}90^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}30^\circ$  then fault type is “c-g”.
- 4) If  $\Delta 1$  is low &  $\Delta 2$  is high &  $\Delta 3$  is low &  $\Delta 4$  is high &  $\text{Ang\_A}$  is  $\text{aprx}30^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}90^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}150^\circ$  then fault type is “a-b-g”.
- 5) If  $\Delta 1$  is low &  $\Delta 2$  is low &  $\Delta 3$  is high &  $\Delta 4$  is high &  $\text{Ang\_A}$  is  $\text{aprx}150^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}30^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}90^\circ$  then fault type is “b-c-g”.
- 6) If  $\Delta 1$  is high &  $\Delta 2$  is low &  $\Delta 3$  is low &  $\Delta 4$  is high &  $\text{Ang\_A}$  is  $\text{aprx}90^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}150^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}30^\circ$  then fault type is “c-a-g”.
- 7) If  $\Delta 1$  is low &  $\Delta 2$  is high &  $\Delta 3$  is low &  $\Delta 4$  is low &  $\text{Ang\_A}$  is  $\text{aprx}30^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}90^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}150^\circ$  then fault type is “a-b”.
- 8) If  $\Delta 1$  is low &  $\Delta 2$  is low &  $\Delta 3$  is high &  $\Delta 4$  is low &  $\text{Ang\_A}$  is  $\text{aprx}150^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}30^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}90^\circ$  then fault type is “b-c”.
- 9) If  $\Delta 1$  is high &  $\Delta 2$  is low &  $\Delta 3$  is low &  $\Delta 4$  is low &  $\text{Ang\_A}$  is  $\text{aprx}90^\circ$  &  $\text{Ang\_B}$  is  $\text{aprx}150^\circ$  &  $\text{Ang\_C}$  is  $\text{aprx}30^\circ$  then fault type is “c-a”.
- 10) If  $\Delta 1$  is medium &  $\Delta 2$  is medium &  $\Delta 3$  is low &  $\Delta 4$  is low &  $\text{Ang\_A}$  is none &  $\text{Ang\_B}$  is none &  $\text{Ang\_C}$  is none then fault type is “a-b-c”.
- 11) If  $\Delta 1$  is medium &  $\Delta 2$  is low &  $\Delta 3$  is medium &  $\Delta 4$  is low &  $\text{Ang\_A}$  is none &  $\text{Ang\_B}$  is none &  $\text{Ang\_C}$  is none then fault type is “a-b-c”.
- 12) If  $\Delta 1$  is low &  $\Delta 2$  is medium &  $\Delta 3$  is medium &  $\Delta 4$  is low &  $\text{Ang\_A}$  is none &  $\text{Ang\_B}$  is none &  $\text{Ang\_C}$  is none then fault type is “a-b-c”. A “Mamdani” type of Fuzzy Inference System (FIS) was utilized for taking the crisp output of the fault type. To implement the fuzzy inference system, the “min” and “max” operators were used for “and”, “implication” and “aggregation” methods, respectively. The “centroid” defuzzification method was used to defuzzify the output of the fuzzy inference system [15].

**V. RESULTS OF FUZZY LOGIC BASED FAULT CLASSIFIER**

Simulation of three phase transmission line model has been done at different fault location, fault resistance and fault inception angle for all phase to phase and phase to ground faults to verify the performance of the fuzzy logic based fault classifier. The simulation test result of all possible types of shunt faults (LG, LLG, LL and LLL) are given in Table 7, 8, 9 and 10.

**TABLE VII**  
SIMULATION RESULT OF FUZZY LOGIC BASED

**FAULT CLASSIFIER FOR LG FAULTS**

Fault Type	Fault Conditions			Output Variables	
	R <sub>f</sub> (ohm)	Φ <sub>i</sub> (deg)	L <sub>f</sub> (km)	Desired Output	Actual Output
A-G	1	30	1	5	4.95
	120	150	50		4.95
	200	270	75		4.95
	300	360	99.5		4.95
B-G	1	30	1	10	10.17
	120	150	50		10.04
	200	270	75		10.16
	300	360	99.5		10.18
C-G	1	30	1	15	15.13
	120	150	50		15.08
	200	270	75		15.13
	300	360	99.5		15.12

**TABLE VIII**  
SIMULATION RESULT OF FUZZY LOGIC

**FAULT CLASSIFIER FOR LLG FAULTS**

Fault Type	Fault Conditions			Output Variables	
	R <sub>f</sub> (ohm)	Φ <sub>i</sub> (deg)	L <sub>f</sub> (km)	Desired Output	Actual Output
AB-G	1	30	1	20	20.07
	120	150	50		20.08
	200	270	75		20.07
	300	360	99.5		20.08
BC-G	1	30	1	25	25.02
	120	150	50		25.03
	200	270	75		25.02
	300	360	99.5		25.02
AC-G	1	30	1	30	29.88
	120	150	50		29.98
	200	270	75		29.98
	300	360	99.5		29.97

**TABLE IX**  
SIMULATION RESULT OF FUZZY LOGIC BASED

**FAULT CLASSIFIER FOR LL FAULTS**

**FAULT CLASSIFIER FOR LLL FAULTS**

Fault Type	Fault Conditions			Output Variables	
	R <sub>f</sub> (ohm)	Φ <sub>i</sub> (deg)	L <sub>f</sub> (km)	Desired Output	Actual Output
AB	0.01	30	1	35	34.93
	0.01	150	50		34.92
	0.01	270	75		34.93
	0.01	360	99.5		34.92
BC	0.01	30	1	40	39.88
	0.01	150	50		39.88
	0.01	270	75		39.88
	0.01	360	99.5		39.88
AC	0.01	30	1	45	44.82
	0.01	150	50		44.82
	0.01	270	75		44.82
	0.01	360	99.5		44.83

**TABLE X**  
SIMULATION RESULT OF FUZZY

Fault Type	Fault Conditions			Output Variables	
	R <sub>f</sub> (ohm)	Φ <sub>i</sub> (deg)	L <sub>f</sub> (km)	Desired Output	Actual Output
ABC	0.01	30	1	50	50.05
	0.01	150	50		50.05
	0.01	270	75		50.05
	0.01	360	99.5		50.05

From the test results given in Table 7-10, it is clear that the Fuzzy Logic based Fault Classifier is able to classify the fault accurately. Thus, even the extreme fault case of high impedance fault near the far end of the line is classified correctly by the developed Fuzzy Logic based Fault Classifier.

### VI. CONCLUSIONS

For the digital protection of transmission line, proposed methodology can be implemented with only requirement of three phase post fault current samples at one end of line. The magnitudes of fundamental phase current and angular differences between sequence components of the fundamental fault current are considered for fault classification algorithm. Faults with ground and without involvement of ground is developed All the characteristics features participate in fuzzy logic system (FLS) and suitable rule base is designated for detection and classification of fault under varying fault resistance, fault inception angle and fault location. Obtained results confirm the adoptability of the proposed scheme hence applicable to enhance the present protection technology.

### VII. ACKNOWLEDGMENT

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### APPENDIX

Components	Parameters		
Three phase source	Voltage (kV)	220	
	Frequency(Hz)	50	
	Short circuit capacity (GVA)	1.25	
	X/R ratio	10	
Transmission line	Line length (km)	100	
	Line voltage (kV)	220	
	Sequence impedance( $\Omega$ /km)	Positive	0.0275 + j0.422
		Zero	0.275 + j1.169
	Sequence capacitance(nF/km)	Positive	9.483
		Zero	6.711

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