

# Traffic Control System using Image Processing

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**Abstract:** The current traffic control system in Indian cities can be improved as it does not take into consideration the randomness in the traffic density. A large amount of time is being wasted at the signal even though there is no traffic because the timings for red and green light are fixed for all the lanes, irrespective of the traffic density. Currently the traffic signals have fixed signal timings which change every 30sec to 120sec. Such timings which are predetermined are inadequate for real time applications of the traffic control system. In order to control the traffic in efficient way we use image processing to analyze the traffic density on a particular lane and accordingly change the signal time.

**Keywords:** MATLAB, Image processing, traffic density, signal timings.

## I. INTRODUCTION

The traffic signal time in the current traffic control system is preset according to the different types of roads in the city. These preset timings remain fixed and do not vary in response to the traffic density on the lanes at that point of time. This may lead to piling up of vehicles on the road at the signal.

Traffic pile up eventually leads to wastage of useful work hours leading to damage of economic growth. According to a study conducted by Boston Consultancy Group(BCG), the economical loss due to traffic congestion in the four major cities namely-Mumbai, Kolkata, Delhi and Bengaluru- is estimated to be 1.47 lakh crore [1]. On an average the commuters in these cities spend 1.5hours more as compared to other Asian cities during peak hours[2].

Adding to this, the improved standard of living has led to people purchasing more private vehicles, further increasing the traffic. The Traffic Monitoring authorities have to identify better methods to solve traffic problem and to develop an efficient traffic control system.

If we are able to calculate the density of traffic on the lanes and give signal times accordingly, the waiting times of vehicles at the signal can be decreased. This can be done by identifying the lane

which lane has the maximum number of vehicles passing through the junction at a particular time .The aim of this project is to acquire and analyze the traffic images to decide signal timings based on traffic density using image processing.

Firstly the images of the lanes will be captured. These captured images will be compared with a reference image i.e. the empty road, to determine the count of vehicles on each of the lanes. According to the count obtained, traffic will be classified into different categories (eg. high, low and medium density traffic). Based on the different categories the green signal time for the lanes will be assigned.

### A. MATLAB

MATLAB is a high performance language used for technical computing, it integrates all the necessary computation, visualization and even programming of the system where the solution's to an system is expressed in a familiar mathematical notations [5]. MATLAB is a standard tool used for computational analysis in the cases of inventory and advanced courses of science and engineering which is the best tool for computational by the researchers. A variety of process approved within MATLAB contains control concerning the matrix, purpose as well as plotting of data, execution regarding algorithms, design of user interface, as well as integrating by means of programs formed within other languages like C, C++, and java. Specifically MATLAB permit intended for matrix estimation as well as thus can be intended for image processing.

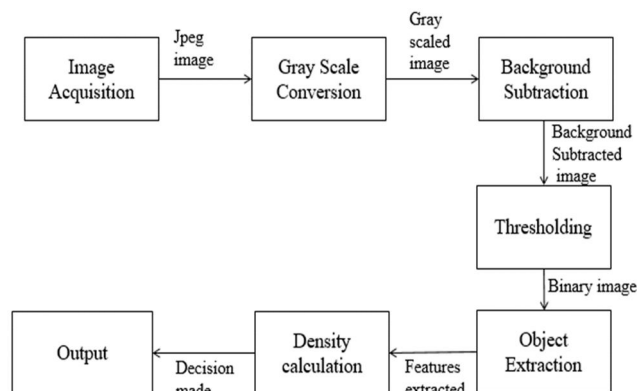
## II. LITERATURE REVIEW

A literature review is both a summary and explanation of the complete and current state of knowledge on a limited topic as found in academic books and journal articles. It gives readers easy access to research on a particular topic by selecting high quality articles or studies that are relevant, meaningful, important and valid and summarizing them into one complete report.

TABLE I . LITERATURE REVIEW

Sr no	Author name	Year	Title	Work done
1	Pallavi Chaudekar, Sayanti Banerjee, M.K.Muju	2011	Implementation of Image Processing in Real Time Traffic Control.	Reduce the traffic congestion and avoids the time being wasted by a green light on an empty road.
2	Shahebgauda Halladamani, Radha R C	2017	Development of Closed Loop Traffic Control System using Image Processing.	Continuously monitoring the traffic and counting no. of vehicles.
3	Pranav Maheshwari, Deepanshu Suneja, Praneet Singh, Yogeshwar Mutneja	2015	Smart Traffic Optimization Using Image Processing.	Dynamic system which uses cameras installed at the red lights and intersections to monitor the traffic dynamically.
4	Md. Munir Hasan, Gobinda Saha, Aminul Hoque, Md. Badruddoja Majumder	2014	Smart Traffic Control System with Application of Image Processing Techniques	Real time monitoring of roads. Sobel edge detection method is used which is simple to implement.

Block Diagram Of Proposed System



### III. METHODOLOGY

- 1) *Image Acquisition:* Generally realtime images are captured using webcam but since it is not feasible to do so, input is given in the form of images from the database.
- 2) *Gray-Scale Conversion:* The RGB image is converted into gray-scale image. Grayscale images are composed of shades of gray, varying from black at the weakest intensity to white at the strongest. Methods for Gray scale conversion:
  - a) *Average Method:*  $Grayscale = (R + G + B) / 3$  .....(1)
  - b) *Weighted Method or Luminosity Method:*  $Grayscale\ image = ((0.3 * R) + (0.59 * G) + (0.11 * B))$  .....(2)
- 3) *Background Subtraction:* The background subtraction is used to remove unwanted objects in the image. This is done to eliminate the background portion in the image and to extract only the vehicles. This process is also known as ROI extraction.
- 4) *Thresholding:* The gray scale image is converted into binary image using mean value as threshold level. Thresholding is classified into two Global Thresholding and Local Thresholding. Global (single) thresholding method is used when the intensity distribution between the objects of foreground and background are very distinct. In local adaptive technique, a threshold is calculated for each pixel, based on some local statistics such as range, variance, or surface-fitting parameters of the neighbourhood pixels.

- 5) *Object Extraction:* In this stage object/features will be extracted from input image to count the exact number of vehicles on a lane.
- 6) *Density Calculation:* Each vehicle is considered as one object. After object extraction stage, the objects at each lane will be displayed. We need to count the number of objects using object counting method. Based on the vehicle count of each lane, the lanes will be classified into various categories of traffic density (eg. low, high and medium). The green light will be given for more time to the lane with higher density of vehicles and comparatively less time will be given to the lanes with lower density of vehicles.
- 7) *Output:* According to the density calculated, timer for each lane will be displayed.

#### IV. RESULTS

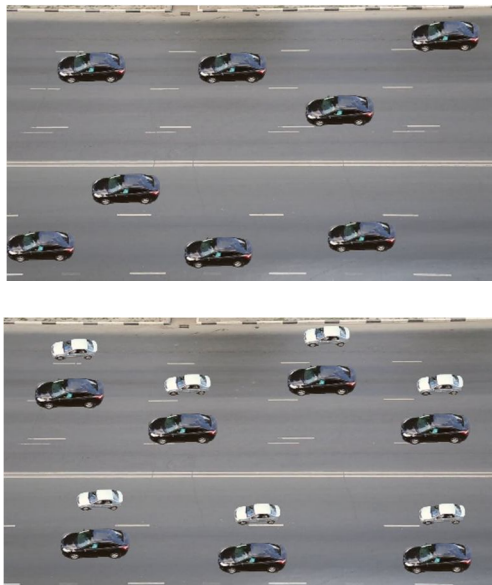


Fig 1: Input images of lane1 and lane2

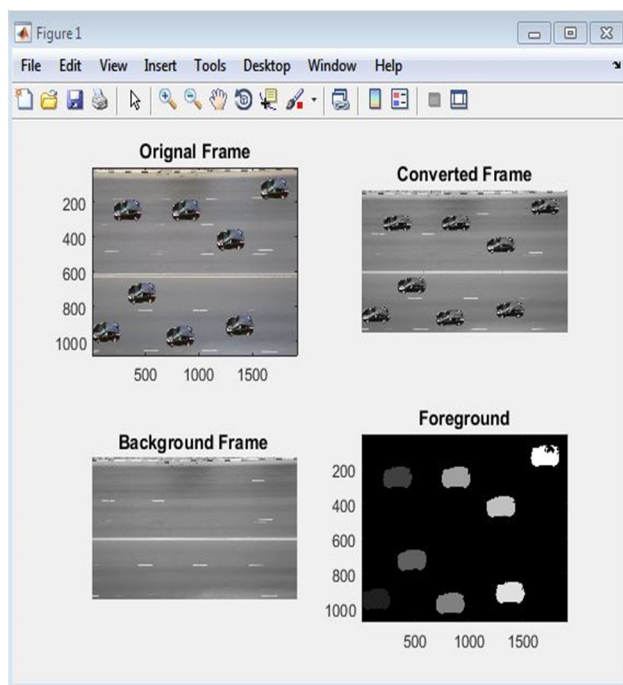


Fig 2: Lane 1 vehicles detected

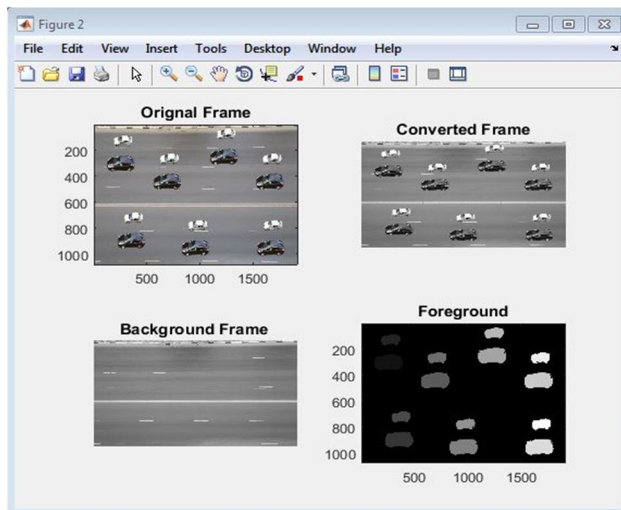


Fig 3: Lane 2 vehicles detected

```

Command Window

ans =

    45

cc =

    Connectivity: 8
    ImageSize: [1080 1920]
    NumObjects: 8
    PixelIdxList: {1x8 cell}

    8

    3.8580e-06

ans =

    45

cc =

    Connectivity: 8
    ImageSize: [1080 1920]
    NumObjects: 14
    PixelIdxList: {1x14 cell}

    14

    6.7515e-06
    
```

Fig 4: No of vehicles detected

```

Command Window

x =

    14

ans =

The highly densed lane has count of 14 cars

ans =

lane2 gets green signal for 30 sec
lane1 gets green signal for 20 sec
    
```

Fig 5: MATLAB command window output.

## V. CONCLUSION

The aim of this project is to implement “traffic control system using image processing” by evaluating the traffic on each lane. This system overcomes the limitations of the earlier systems for controlling traffic. The current traffic control system has a drawback of using fixed timers which leads to wastage of time on empty lanes. Major advantage of this proposed system is the variation in signal time by calculating traffic density using image processing and adjusting the signal time according to the density.

## VI. FUTURE ENHANCEMENT

In future, this system can be modified to identify the vehicles as they pass by, giving preference to emergency vehicles and assisting in surveillance on a large scale.

## REFERENCES

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