



iJRASET

International Journal For Research in
Applied Science and Engineering Technology



INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Volume: 3

Issue: XI

Month of publication: November 2015

DOI:

www.ijraset.com

Call: ☎ 08813907089

E-mail ID: ijraset@gmail.com

Vibration Analysis of Spur Gear- FEA Approach

Subodh S. Lande¹, A. M. Pirjade², Pranit M. Patil³

¹P.G. Scholar, Design Engineering (Mechanical), A.D.C.E.T. Ashta (M.S.) India

²Assistant Professor, Department of Mechanical Engineering, A.D.C.E.T. Ashta (M.S.)

³Assistant Professor, Department of Mechanical Engineering, G.I.T, Lavel (M.S.) India

Abstract— Gears are used for a wide range of industrial applications. They have varied application starting from textile to aviation industries. They are the most common means of transmitting power. They change the rate of rotation of machinery shaft and also the axis of rotation. For high speed machinery, such as an automobile transmission, they are the optimal medium for low energy loss and high accuracy. During operation, meshed gears" teeth flanks are submitted to high contact pressures and due to the repeated stresses, damage on the teeth flanks in addition to tooth breakage at the root of the tooth is one of the most frequent causes of gear failure. This fatigue failure of the tooth decides the reliability of the gear. In this paper, spur gear made up of EN9 material is designed and mode shape of respective gear is found out.

Keywords— Modal analysis, FFT analyzer, Finite element analysis.

I. INTRODUCTION

Toothed gears are used to transmit the power with high velocity ratio. During this phase, they encounter high stress at the point of contact. A pair of teeth in action is generally subjected to two types of cyclic stresses: Bending stresses inducing bending fatigue & Contact stress causing contact fatigue. Both these types of stresses may not attain their maximum values at the same point of contact. However, combined action of both of them is the reason of failure of gear tooth leading to fracture at the root of a tooth under bending fatigue and surface failure, due to contact fatigue. When loads are applied to the bodies, their surfaces deform elastically near the point of contact. The highest stresses exist at regions where the lines are bunched closest together. The highest stress occurs at two locations: At contact point where the force F acts & At the fillet region near the base of the tooth. Given the fact that most gear systems in real engineering environment are multi-mesh with more than one pair of gears, some researchers have shifted their research effort from single-mesh gear trains to multi-mesh ones including gear trains with two meshes and planetary gear trains. Al-shyyab and Kahraman [1,2] systematically investigated the response of a double mesh system which is a common configuration in many applications with multi-term harmonic balance method. Based on the assumption that tooth separation takes only small fraction of the mesh period, Liu and Parker [3] formulated the nonlinearity of clearance with a smooth function and approached the problem with the method of multiple scales. Comparison was also made between the results obtained through multiple scales method and that of harmonic balance method. Tobe, Sato and Takatsu [5,6] are believed to be pioneers in studying gear systems with random vibration theory. They measured the transmission error of a gear pair and confirmed the existence of random components in it. Following that a combination of statistic linearization technique and moment equations was employed in the theoretical work [6]. Kumar, Osman and Sankar [7] investigated the dynamic response of a gear pair with direct integration method, which is much easier to be applied and understood. However, details on how to handle the clearance-type nonlinearity were not explained fully. Wang and Zhang [8] also studied a gear pair, but modeled the random excitation as a speed dependent noise. More recently, Naess, Kolnes and Mo [9] and Mo and Naess [10] approached a similar system with path integration method. The random excitation was modeled as a white noise and the probability density of the response was given in the result. In this paper, spur gear made up of EN9 material is tested analytically and experimentally. Mode shapes of both the materials are compared for suitable natural frequency

II. DESIGN METHODOLOGY

Nomenclature		
m- mass	k- stiffness	w- fundamental frequency
\ddot{x} - acceleration	\dot{x} - velocity	x- displacement
f- natural frequency	J- polar moment of inertia	G- Rigidity Modulus
I – moment of inertia	E – modulus of elasticity	

In order to design the spur gear the CATIA V5 as modeling software has been used. Gear and Pinion are designed by following

International Journal for Research in Applied Science & Engineering Technology (IJRASET)

dimensional parameters.

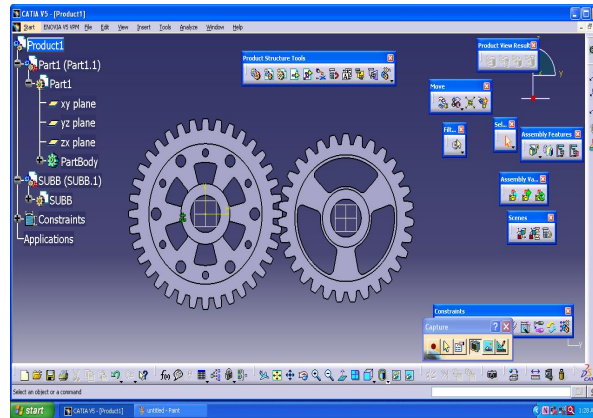


Fig 1 Previous Design of Gear and Pinion using CATIA as design software

A. Material IEN9

Table 1: Chemical Composition of EN9 material

C	Si	Mn	S	P
0.50 – 0.60 %	0.10 – 0.40 %	0.50 – 0.90	0.050 max %	0.050 max %

III. MODAL ANALYSIS OF GEAR

FEA consists of a computer model of a material or design that is stressed and analyzed for specific results. It is used in new product design, and existing product refinement. A company is able to verify a proposed design will be able to perform to the client's specifications prior to manufacturing or construction. Modifying an existing product or structure is utilized to qualify the product or structure for a new service condition. In case of structural failure, Finite element analysis may be used to help determine the design modifications to meet the new condition

A. Modal Analysis

In many engineering applications, the natural frequencies of vibration are of interest. This is probably the most common type of dynamic analysis and is referred to as an 'Eigen value analysis'. In addition to the frequencies, the mode shapes of vibration which arise at the natural frequencies are also of interest. These are the un damped free vibration response of the structure caused by an initial disturbance from the static equilibrium position. This solution derives from the general equation by zeroing the damping and applied force terms. Thereafter, it is assumed that each node is subjected to sinusoidal functions of the peak amplitude for that node. The mode shapes are also of interest to the engineer. These are normalized to the maximum displacement of the structure. The input conditions which initiate the vibration control the amplitudes of vibration in any problem.

B. Mode Shapes And Frequencies Of Gearmaterial En 9(Existing Material)

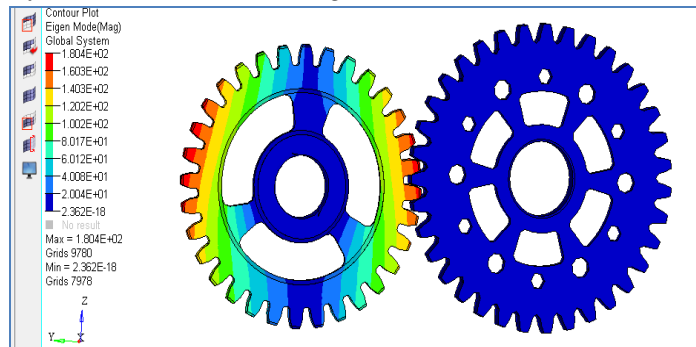


Fig. 2 Mode shape 1 in modal analysis at frequency (23611HZ)

International Journal for Research in Applied Science & Engineering Technology (IJRASET)

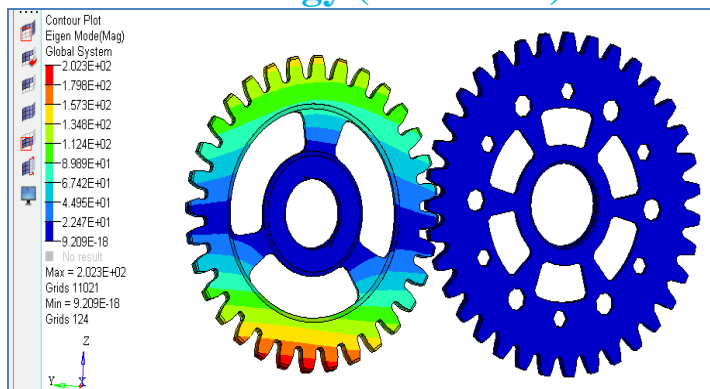


Fig. 3 Mode shape 2 in modal analysis at frequency(23664HZ)

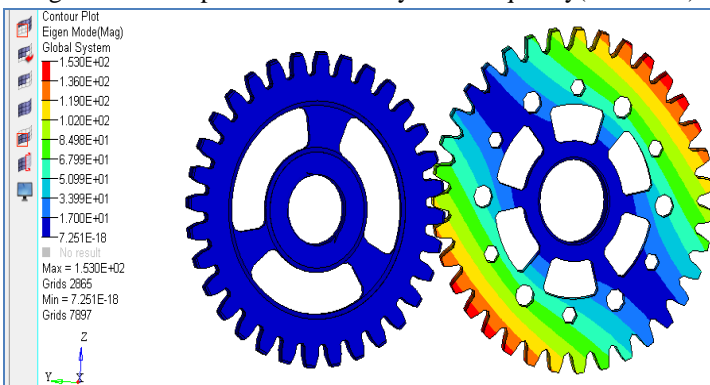


Fig. 4 Mode shape 3 in modal analysis at frequency(25682HZ)

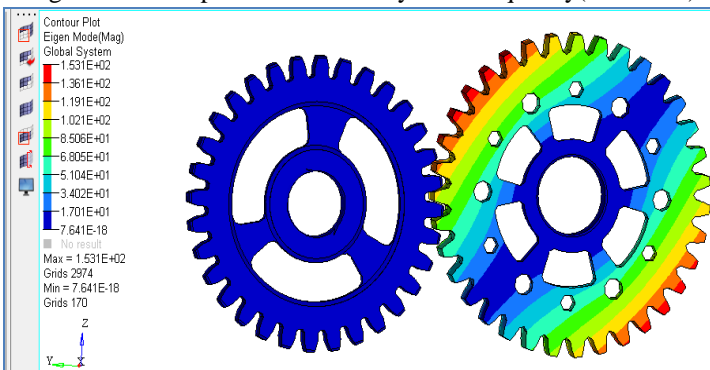


Fig. 5 Mode shape 4 in modal analysis at frequency(27518HZ)

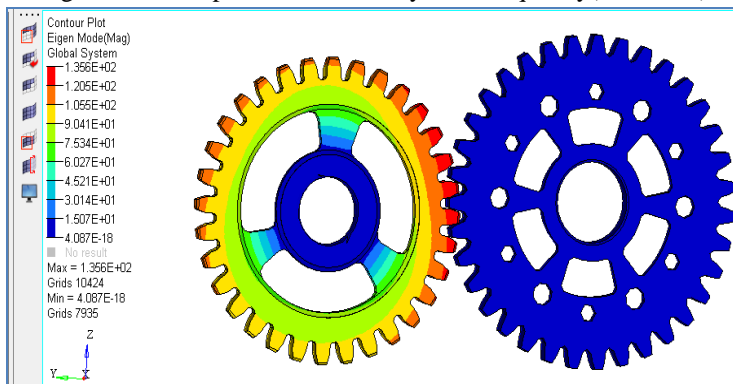


Fig. 6 Mode shape 5 in modal analysis at frequency(30430HZ)

International Journal for Research in Applied Science & Engineering Technology (IJRASET)

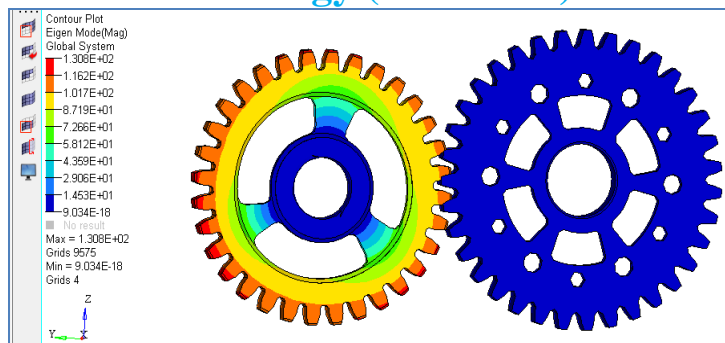


Fig. 7 Mode shape 6 in modal analysis at frequency(33706HZ)

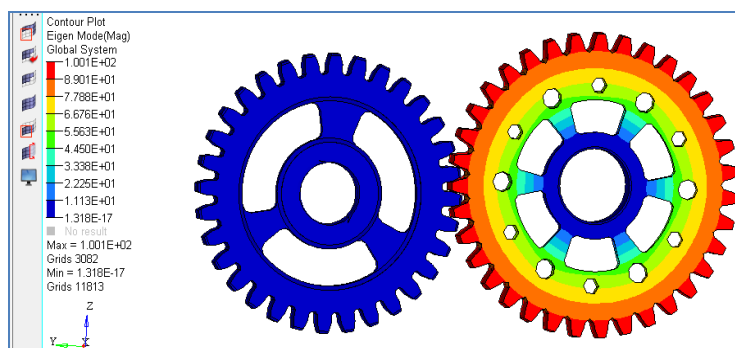


Fig. 8 Mode shape 7 in modal analysis at frequency(38184HZ)

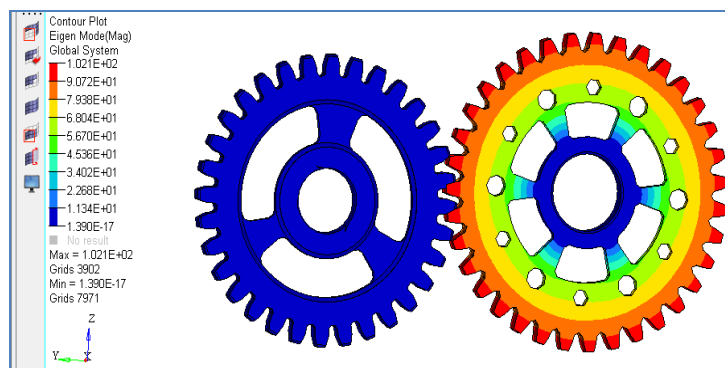


Fig. 9 Mode shape 8 in modal analysis at frequency(39975HZ)

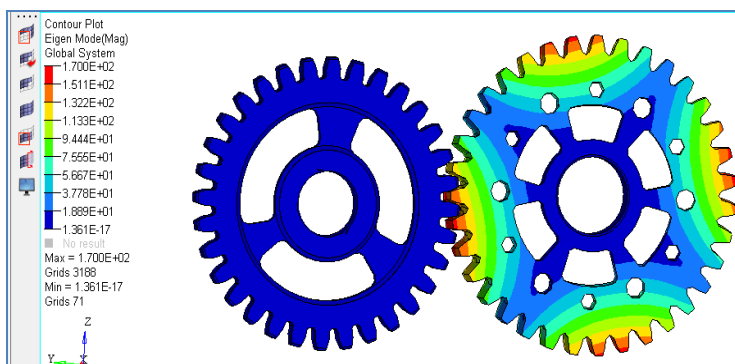


Fig. 10 Mode shape 9 in modal analysis at frequency(48730HZ)

International Journal for Research in Applied Science & Engineering Technology (IJRASET)

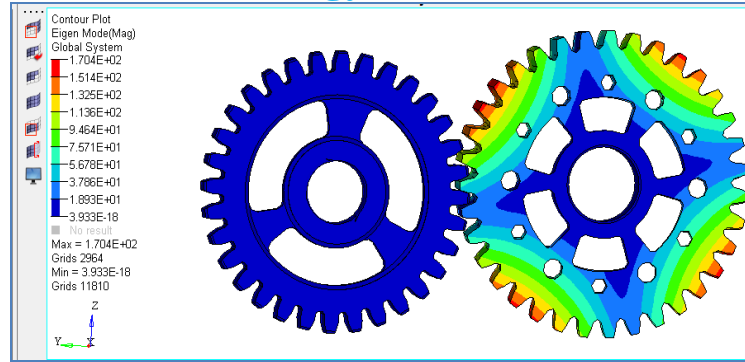


Fig. 11 Mode shape 10 in modal analysis at frequency(48736HZ)

Table 3: Frequencies Of Existing Gears(EN 9 Material)

Mode	Existing Gears frequencies in Hz
Material	EN9
1	23611
2	23664
3	25682
4	27518
5	30430
6	33706
7	38184
8	39975
9	48730
10	48736

IV. RESULTS AND DISCUSSION

Table 4: Comparison of Results

Particulars	Analytical Results	Experimental Results
Natural frequency Hz	2361.1	2502.8

It is seen that the comparative results shows decreasing trends for natural frequency, this variation is occurs due to the operating condition of the gears.

Fig 12 shows the graphical presentation of the analytical results and experimental results.

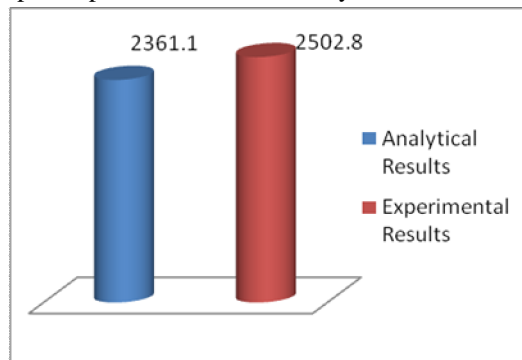


Fig. 12 Graphical Representation of Results

International Journal for Research in Applied Science & Engineering Technology (IJRASET)

V. CONCLUSION

Modal analysis result shows that the frequency value (23611 Hz) of existing gears manufacturing with EN9 steel is much higher as compared to engine frequency value and no resonance condition was found. Further modal analysis of gears made out of EN353 as per the design of existing gears (EN9) was carried out in order to reduce cost with performance at par.

REFERENCES

- [1] A. Al-shyyab, A. Kahraman, Non-linear dynamic analysis of a multi-mesh gear trains using multi-term harmonic balance method: sub-harmonic motions, *Journal of Sound and Vibration* 279 (2005) 417–451.
- [2] A. Al-shyyab, A. Kahraman, Non-linear dynamic analysis of a multi-mesh gear trains using multi-term harmonic balance method: period-one motions, *Journal of Sound and Vibration* 284 (2005) 151–172.
- [3] G. Liu, R.G. Parker, Nonlinear dynamics of idler gear systems, *Nonlinear Dynamics* 53 (2008) 345–367.
- [4] S. Theodossiades, S. Natsiavas, Non-linear dynamics of gear-pair systems with periodic stiffness and backlash, *Journal of Sound and Vibration* 229 (2000) 287–310.
- [5] T. Tobe, K. Sato, Statistical analysis of dynamic loads on spur gear teeth, *Bulletin of the Japanese Society of Mechanical Engineers* 20 (1977) 882–889.
- [6] T. Tobe, K. Sato, N. Takatsu, Statistical analysis of dynamic loads on spur gear teeth: experimental study, *Bulletin of the Japanese Society of Mechanical Engineers* 20 (1977) 1315–1320.
- [7] A.S. Kumar, M.O.M. Osman, T.S. Sankar, On statistical analysis of gear dynamic loads, *Journal of Vibration, Acoustics, Stress, and Reliability in Design* 108 (1986) 362–368.
- [8] Y. Wang, W.J. Zhang, Stochastic vibration model of gear transmission systems considering speed-dependent random errors, *Nonlinear Dynamics* 17 (1998) 187–203.
- [9] A. Naess, F.E. Kolnes, E. Mo, Stochastic spur gear dynamics by numerical path integration, *Journal of Sound and Vibration* 302 (2007) 936–950.
- [10] E. Mo, A. Naess, Nonsmooth dynamics by path integration: an example of stochastic and chaotic response of meshing gear pair, *Journal of Computational and Nonlinear Dynamics* 4 (2009) 034501.
- [11] P. Bernard, G. Fleury, Stochastic Newmark scheme, *Probabilistic Engineering Mechanics* 17 (2002) 45–61.
- [12] M. Tookaboni, L. Graham- Brady, Stochastic direct integration schemes for dynamic systems subjected to random excitations, *Probabilistic Engineering Mechanics* 25 (2010) 163–171.

AUTHORS



Mr. Subodh S. Lande has completed his bachelor's in Mechanical Engineering from ADCET, Ashta in 2012. He is pursuing masters degree in Design (Mech) engineering from ADCET, Ashta. He has three years of teaching experience. Currently he is working as Asst Professor in Department of Mechanical Engineering at Nanasahab College of Engineering, Peth, Sangli,



Mr. Akhtarhusen M. Pirjade has completed masters degree in Mechanical Design in 2007. He is pursuing PhD in design engineering as specialization. He has 15 years of teaching experience. Currently he is working as assistant professor in Department of Mechanical Engineering at ADCET, Ashta, Sangli



Mr. Pranit M. Patil has completed his bachelor's in Mechanical Engineering from RMCET, Devrukh in 2012. He has received master's degree in Design (Mech) engineering from ADCET, Ashta in 2014. He has four years of teaching experience. Currently he is working as Asst Professor in Department of Mechanical Engineering at Gharda Institute of Technology, Lavel, Khed, Ratnagiri



10.22214/IJRASET



45.98



IMPACT FACTOR:
7.129



IMPACT FACTOR:
7.429



INTERNATIONAL JOURNAL FOR RESEARCH

IN APPLIED SCIENCE & ENGINEERING TECHNOLOGY

Call : 08813907089  (24*7 Support on Whatsapp)