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## **Comparison of Analytical and Software Based Design of Energy Efficient Induction Motor**

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Abstract: Energy Efficient Induction motor is playing a vital role in current scenario. Due to rising electrical energy demand, increased awareness of global warming, and rising fossil fuel prices, energy efficiency has become increasingly important. Apart from adding capacity, the only practical approach to deal with this situation is to make optimal use of the available energy, which may be done by using energy efficient Motors. The main objective of this paper is to calculate and Compare the Analytical and Electromagnetic Software based design for a 5HP Energy Efficient Motor. Keywords: Energy Efficient Motors, Analytical Method, Design, Induction Motor

#### I. INTRODUCTION

The most common motors found in industry are three-phase induction motors. They have been widely employed in industry in almost all applications because to their simple, durable, and easy to maintain structure. These engines are known as the industry's workhorses. Induction motors are frequently employed in industrial and domestic appliances [1]. In recent decades, both producers and end-users have become increasingly concerned about the energy efficiency of electric motors. New approaches to improve the efficiency of three-phase induction motors have been developed, and other technological solutions are emerging that could lead to even higher efficiency levels. Even though energy saving has been the most important factor in the design of general-purpose industrial motors, this was not done at the price of durability or overall motor performance. Some people believe that the drive for more efficiency would reduce motor life, and that the higher flux densities may cause application issues with the starting current [2]. The ever-increasing interest in high-efficiency motors can be attributed to two key factors nowadays. Electric motors are a large consumer of electricity. The first is the necessity of addressing ever-increasing energy demand by significantly reducing energy use in order to reduce Carbon dioxide emissions. The second benefit is the cost savings that come with using high-efficiency motors [3]. Over the life of the motor, a small increase in efficiency can save a lot of energy and money. Because Energy Efficient Motors have been demonstrated to be a durable and reliable technology [4].

#### **II. BACKGROUND**

There is a clear link between motor life and the challenges that it faces. The desired motor performance and lifespan will usually be attained as long as these stresses are suitably accommodated and controlled within stated design and operation limits [5]. The first significant lines of energy efficient motors were produced in the mid-1970s for the designated product range, with projected penetration of less than 20% of the entire population purchased during this period prior to the Energy Act of 1992.

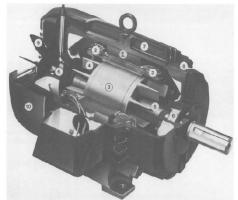


Fig. 1.Cross-sectional view of Electric Energy Efficient Motor : 1-Stator laminated steel; 2-stator windings; 3-rotor; 4-rotor fan blades; 5-shaft; 6-bearings; 7-frame; 8-brackets; 9- external fan; 10-fan cover. (Source: Reliance Electric Company.)



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#### **III.ANALYTICAL DESIGN**

A. Input KVA and output co-efficient Output co-efficient

$$C_0 = 1.1 * k_w * B_{ac} * AC * 10^{-3} \label{eq:Q}$$
   
  $Q = C_0 D * 2 * L * ns$ 

KVA input

(Where,  $k_w =$  Winding factor =  $k_c * k_d$ ,  $B_{av} =$  Specific magnetic loading, ac = Specific electric loading) D = Diameter of core, L = Length of core, s = speed in r.p.s. (rotation per second) =N/60.

$$D^2 * L = \frac{KVA}{C_0 * n\varepsilon} \qquad L = \pi * \frac{D}{p}$$

Flux per pole

D and L

$$\theta_m = R_{av} \frac{\pi DL}{v}$$

Turns per phase

$$T_S = \frac{E_N}{4.44K_{WS}*f*\phi_m}$$

 $\begin{array}{l} P_{s(h+e)} \\ P_{r(h+e)} \end{array}$ 

 $\begin{array}{c} P_{fw} \\ P_{misc} \end{array}$ 

 $P_{SCL} = 3 * I^2_{sp} * R_{sp}$ 

 $P_{rc} = 3 * I^2 * R_2$ 

 $I_s = \frac{Q}{3E_{ph}}$ 

Where,  $K_{ws} = 0.955$  (assumed).

Voltage per phase  $E_s = 4.44 K_{ws} * f * \phi_m * T_s$ 

Stator current per phase

Length of Airgap  $L_g = 0.2 + 2\sqrt{DL}$  mm

1) Iron Losses

| Stator core losses: |  |
|---------------------|--|
| Rotor core losses:  |  |

2) Copper Looses

The losses in the stator are The losses in the rotor are Friction and Windage losses: Stray load losses:

3) Total Losses

$$P_{loss} \qquad = P_{s(h+e)} + P_{r(h+e)} + P_{fw} + P_{misc}$$

4) Efficiency  $(\eta)$ 

$$\eta = \frac{P_o}{P_o + P_{loss}}$$
$$\eta = \frac{P_{ower \, Out}}{P_{ower \, In}} = \frac{P_{out}}{P_{in}}$$



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| Parameters                         | Outputs Obtained by<br>Analytical Procedure |
|------------------------------------|---|
| Frequency (Hz)                     | 50  |
| No. of Poles                       | 4   |
| Speed (RPM)                        | 1500  |
| Power Factor                       | 0.8   |
| Turns / phase                      | 228   |
| Line Current(A)                    | 7.269                                       |
| Iron Losses (W)                    | 58.96                                       |
| Copper Losses(W)                   | 264.11                                      |
| Friction and Windage<br>Losses (W) | 28.125                                      |
| Stray load losses (W)              | 91.2  |
| Efficiency (%)                     | 89.41                                       |

TABLE I The Performan al Procedure

#### IV. INDUCTION MOTOR DESIGN USING ELECTROMAGNETIC SOFTWARE

Geometrical data are used to describe the motor. The first piece of information presented is the machine's kind, which is a threephase induction motor.

| Stator Parameters | Value | Rotor Parameters      | Value |
|-------------------|-------|-----------------------|-------|
| Slot Number       | 36    | Rotor Bars            | 26    |
| Stator Lam Dia    | 220   | Pole Number           | 4     |
| Stator Bore       | 109   | Bar Opening [T]       | 2.5   |
| Tooth Width       | 4.8   | Bar Opening Depth [T] | 1     |
| Slot Depth        | 40    | Bar Tip Angle [T]     | 20    |
| Slot Comer Radius | 0     | Rotor Tooth Width [T] | 5.5   |
| Tooth Tip Depth   | 1     | Bar Depth [T]         | 24    |
| Slat Opening      | 3     | Bar Comer Radius [T]  | 0     |
| Tooth Tip Angle   | 60    | Airgap                | 0.4   |
| Sleeve Thickness  | 0     | Banding Thickness     | 0     |
|                   |       | Shaft Dia             | 25    |
|                   |       | Shaft Hole Diameter   | 0     |

Stator Lam Dia 220 Motor Length 225 Stator Bore 109 Stator Lam Length 110 Airgap 0.4 Rotor Lam Length 110

Value

Fig 2 Geometical Radial Corss-Section Input data.

Fig, 3. Axial Cross-Section Input data

Axial Dimensions

Value

The stator dimensions are represented by the first two columns of the radial cross-section input data and the Rotor dimensions are represented in last two columns as shown in Fig.2.

Radial Dimensions



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| 🔨 Drive 🛛 🏈 E-Magnetics 🛛 🙀 Equivalent C    | ircuit 🔅 Flux Densities | 🌞 Losses 🛛 🔛 Win |
|---|-------------------------|------------------|
| Variable                                    | Value                   | Units            |
| Stator Copper Losses (Analytic on load)     | 127.8                   | Watts            |
| Rotor Copper Losses (Analytic on load)      | 121.6                   | Watts            |
| Stray Load Losses (Analytic on load)        | 92.23                   | Watts            |
| Stator iron Loss [total] (Analytic on load) | 63.94                   | Watts            |
| Rotor iron Loss [total] (Analytic on load)  | 0.8705                  | Watts            |
| Windage Loss (adjusted)                     | 4.108                   | Watts            |
| Friction Loss (adjusted)                    | 23.23                   | Watts            |
|   |                         |                  |
| Total Losses (Analytic on load)             | 433.8                   | Watts            |
|   |                         |                  |

Fig. 4. Losses of 5Hp EEIM in Software.

The Losses obtained by the Software are presented the in Fig. 4. The total Copper losses are 249.4 watts, total Iron Losses present are 64.81watts, Friction and Windage Losses are 27.338 watts and Stary load loasses are 92.23 watts.

#### TABLE IIIII

The Performance Parameters of an 5HP Energy Efficient Induction Motor By using Software

| [                                     |                                  |  |
|---------------------------------------|----------------------------------|--|
| Parameters                            | Electromagnetic Software Outputs |  |
| Frequency (Hz)                        | 50                               |  |
| No. of Poles                          | 4                                |  |
| Speed (RPM)                           | 1500                             |  |
| Power Factor                          | 0.81                             |  |
| Turns / phase                         | 228                              |  |
| Line Current(A)                       | 7.1495                           |  |
| Iron Losses (W)                       | 65.56                            |  |
| Copper Losses(W)                      | 249.3                            |  |
| Friction and<br>Windage Losses<br>(W) | 27.446                           |  |
| Stray load losses<br>(W)              | 92.51                            |  |
| Efficiency (%)                        | 89.60                            |  |



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#### V. CONCLUSIONS

#### Table IVVVI

The Performance Parameters of an 5hp EEIM Outputs are Compared Between Analytical Procedure and Electromagnetic Software

|                       | Out        | puts            |  |
|-----------------------|------------|-----------------|--|
| Parameters            | Analytical | Electromagnetic |  |
|                       | Procedure  | Software        |  |
| Frequency (Hz)        | 50         | 50              |  |
| No. of Poles          | 4          | 4               |  |
| Speed (RPM)           | 1500       | 1500            |  |
| Power Factor          | 0.8        | 0.81            |  |
| Turns / phase         | 228        | 228             |  |
| Line Current(A)       | 7.269      | 7.1495          |  |
| Iron Losses (W)       | 58.96      | 65.56           |  |
| Copper Losses(W)      | 264.11     | 249.3           |  |
| Friction and Windage  | 28.125     | 27.446          |  |
| Losses (W)            |            | 2/110           |  |
| Stray load losses (W) | 91.2       | 92.51           |  |
| Efficiency (%)        | 89.41      | 89.60           |  |

The Analytical method and Electromagnetic Software outputs are compared in the Table III above. Considering main performance parameters like power factor, line currents(A), Iron and copper losses(W), friction and windage losses (W), stray load losses(W), and efficiency(%). It clearly shows that the Design based on Electromagnetic Software gives the better Efficiency then the Analytical procedure, because the software will consider the Saturations points of the material. Where as in Analytical procedure it is difficult to consider and Calculate the Saturation points. Thus, the Iron Losses are higher in Electromagnetic Software then Analytical Procedure but other parameters are better by designing a EEIM by Using Electromagnetic Software with an Efficiency of 89.6%.

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