



ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

Certificate

It is here by certified that the paper ID : IJRASET16268, entitled

*Particle Swarm Optimization Based Real-Time Path Planning and Obstacle
Avoidance of UAVs Using Low Cost Sensors*

by

Sumana Biswas

*after review is found suitable and has been published in
ICAAA-2018, Conference, April 2018
in*

*International Journal for Research in Applied Science &
Engineering Technology
(International Peer Reviewed and Refereed Journal)
Good luck for your future endeavors*

By [Signature]

Editor in Chief, iJRASET

 ISRA

ISRA Journal Impact
Factor: 7.429



45.98

INDEX COPERNICUS



THOMSON REUTERS
Researcher ID: N-9681-2016



TOGETHER WE REACH THE GOAL
SJIF 7.429



ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

Certificate

It is here by certified that the paper ID : IJRASET16268, entitled

*Particle Swarm Optimization Based Real-Time Path Planning and Obstacle
Avoidance of UAVs Using Low Cost Sensors*

by

Sreenatha G. Anavatti

*after review is found suitable and has been published in
ICAAA-2018, Conference, April 2018
in*

*International Journal for Research in Applied Science &
Engineering Technology
(International Peer Reviewed and Refereed Journal)
Good luck for your future endeavors*

By [Signature]

Editor in Chief, iJRASET

J^ournal
ISRA
F

ISRA Journal Impact
Factor: 7.429

45.98
INDEX COPERNICUS

THOMSON REUTERS
Researcher ID: N-9681-2016

doi 10.22214/iJRASET
cross ref

Scopus
TOGETHER WE REACH THE GOAL
SJIF 7.429



ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

Certificate

It is here by certified that the paper ID : IJRASET16268, entitled

*Particle Swarm Optimization Based Real-Time Path Planning and Obstacle
Avoidance of UAVs Using Low Cost Sensors*

by

Hamish P. Krippner

*after review is found suitable and has been published in
ICAAA-2018, Conference, April 2018
in*

*International Journal for Research in Applied Science &
Engineering Technology
(International Peer Reviewed and Refereed Journal)
Good luck for your future endeavors*

By [Signature]

Editor in Chief, iJRASET

 ISRA

ISRA Journal Impact
Factor: 7.429



45.98

INDEX COPERNICUS



THOMSON REUTERS
Researcher ID: N-9681-2016



TOGETHER WE REACH THE GOAL
SJIF 7.429