



ISSN No. : 2321-9653

IJRASET

**International Journal for Research in Applied
Science & Engineering Technology**

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

ISRA
JIF

ISRA Journal Impact
Factor: 7.429



45.98
INDEX COPERNICUS



THOMSON REUTERS
Researcher ID: N-9581-2016



10.22214/IJRASET



TOGETHER WE REACH THE GOAL
SJIF 7.429

Certificate

*It is here by certified that the paper ID : IJRASET7352, entitled
A Method for Mobile Robot to Navigate in Dynamic Environment using Fuzzy
Approach*

*by
S. R. Tandan*

*after review is found suitable and has been published in
Volume 5, Issue V, May 2017
in*

By [Signature]

Editor in Chief, IJRASET

*International Journal for Research in Applied Science &
Engineering Technology
(International Peer Reviewed and Refereed Journal)
Good luck for your future endeavors*



ISSN No. : 2321-9653

IJRASET

**International Journal for Research in Applied
Science & Engineering Technology**

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

Certificate

*It is here by certified that the paper ID : IJRASET7352, entitled
A Method for Mobile Robot to Navigate in Dynamic Environment using Fuzzy
Approach*

*by
Karishma Dewangan*

*after review is found suitable and has been published in
Volume 5, Issue V, May 2017
in*

*International Journal for Research in Applied Science &
Engineering Technology
(International Peer Reviewed and Refereed Journal)
Good luck for your future endeavors*

By [Signature]

Editor in Chief, IJRASET

ISRA
JIF

ISRA Journal Impact
Factor: 7.429



45.98
INDEX COPERNICUS



THOMSON REUTERS
Researcher ID: N-9581-2016



TOGETHER WE REACH THE GOAL
SJIF 7.429



ISSN No. : 2321-9653

IJRASET

**International Journal for Research in Applied
Science & Engineering Technology**

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

ISRA
JIF

ISRA Journal Impact
Factor: 7.429



45.98
INDEX COPERNICUS



THOMSON REUTERS
Researcher ID: N-9581-2016



TOGETHER WE REACH THE GOAL
SJIF 7.429

Certificate

*It is here by certified that the paper ID : IJRASET7352, entitled
A Method for Mobile Robot to Navigate in Dynamic Environment using Fuzzy
Approach*

*by
Rohit Kumar Miri*

*after review is found suitable and has been published in
Volume 5, Issue V, May 2017
in*

By [Signature]

Editor in Chief, IJRASET

*International Journal for Research in Applied Science &
Engineering Technology
(International Peer Reviewed and Refereed Journal)
Good luck for your future endeavors*