



ISSN No. : 2321-9653

# iJRASET

International Journal for Research in Applied  
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : [www.ijraset.com](http://www.ijraset.com), E-mail : [ijraset@gmail.com](mailto:ijraset@gmail.com)

## Certificate

*It is here by certified that the paper ID : IJRASET56456, entitled  
2D of Robotic Arm Based on Inverse Kinematics Using Arduino  
by  
Mr. B. Sreekanth Reddy*

*after review is found suitable and has been published in  
Volume 11, Issue XI, November 2023  
in  
International Journal for Research in Applied Science &  
Engineering Technology  
(International Peer Reviewed and Refereed Journal)  
Good luck for your future endeavors*

*By [Signature]*

Editor in Chief, iJRASET

J<sup>o</sup>urnal  
ISRA  
F

ISRA Journal Impact  
Factor: 7.429



45.98  
INDEX COPERNICUS



THOMSON REUTERS  
Researcher ID: N-9681-2016



doi 10.22214/IJRASET  
cross ref



Scopus  
TOGETHER WE REACH THE GOAL  
SJIF 7.429



ISSN No. : 2321-9653

# iJRASET

International Journal for Research in Applied  
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : [www.ijraset.com](http://www.ijraset.com), E-mail : [ijraset@gmail.com](mailto:ijraset@gmail.com)

## Certificate

*It is here by certified that the paper ID : IJRASET56456, entitled  
2D of Robotic Arm Based on Inverse Kinematics Using Arduino  
by  
Panthatm Apurva*

*after review is found suitable and has been published in  
Volume 11, Issue XI, November 2023  
in  
International Journal for Research in Applied Science &  
Engineering Technology  
(International Peer Reviewed and Refereed Journal)  
Good luck for your future endeavors*

*By [Signature]*

Editor in Chief, iJRASET

JISRA  
F

ISRA Journal Impact  
Factor: 7.429

45.98  
INDEX COPERNICUS

THOMSON REUTERS  
Researcher ID: N-9681-2016

doi 10.22214/iJRASET  
cross ref

Scopus  
TOGETHER WE REACH THE GOAL  
SJIF 7.429



ISSN No. : 2321-9653

# iJRASET

International Journal for Research in Applied  
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : [www.ijraset.com](http://www.ijraset.com), E-mail : [ijraset@gmail.com](mailto:ijraset@gmail.com)

## Certificate

*It is here by certified that the paper ID : IJRASET56456, entitled  
2D of Robotic Arm Based on Inverse Kinematics Using Arduino*

*by  
Gayathri Pulla*

*after review is found suitable and has been published in  
Volume 11, Issue XI, November 2023  
in*

*International Journal for Research in Applied Science &  
Engineering Technology  
(International Peer Reviewed and Refereed Journal)  
Good luck for your future endeavors*

*By [Signature]*

Editor in Chief, iJRASET

JISRA  
F

ISRA Journal Impact  
Factor: 7.429

45.98  
INDEX COPERNICUS

THOMSON REUTERS  
Researcher ID: N-9681-2016

doi 10.22214/IJRASET  
cross ref

Scopus  
TOGETHER WE REACH THE GOAL  
SJIF 7.429



ISSN No. : 2321-9653

# iJRASET

International Journal for Research in Applied  
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : [www.ijraset.com](http://www.ijraset.com), E-mail : [ijraset@gmail.com](mailto:ijraset@gmail.com)

## Certificate

*It is here by certified that the paper ID : IJRASET56456, entitled  
2D of Robotic Arm Based on Inverse Kinematics Using Arduino*

*by*

*Udutha Sathwika*

*after review is found suitable and has been published in  
Volume 11, Issue XI, November 2023  
in*

*International Journal for Research in Applied Science &  
Engineering Technology  
(International Peer Reviewed and Refereed Journal)  
Good luck for your future endeavors*

*By [Signature]*

Editor in Chief, iJRASET

 ISRA  
JOURNAL  
IMPACT  
FACTOR

ISRA Journal Impact  
Factor: 7.429

 45.98  
INDEX COPERNICUS

 THOMSON REUTERS  
Researcher ID: N-9681-2016

 doi 10.22214/IJRASET  
cross ref

 SCOPUS  
SCIENTIFIC JOURNAL IMPACT FACTOR  
TOGETHER WE REACH THE GOAL  
SJIF 7.429



ISSN No. : 2321-9653

# iJRASET

International Journal for Research in Applied  
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : [www.ijraset.com](http://www.ijraset.com), E-mail : [ijraset@gmail.com](mailto:ijraset@gmail.com)

## Certificate

*It is here by certified that the paper ID : IJRASET56456, entitled  
2D of Robotic Arm Based on Inverse Kinematics Using Arduino*

*by*

*Manisha Perupangu*

*after review is found suitable and has been published in  
Volume 11, Issue XI, November 2023  
in*

*International Journal for Research in Applied Science &  
Engineering Technology  
(International Peer Reviewed and Refereed Journal)  
Good luck for your future endeavors*

*By [Signature]*

Editor in Chief, iJRASET

 ISRA  
J  
I  
F

ISRA Journal Impact  
Factor: 7.429

 45.98  
INDEX COPERNICUS

 THOMSON REUTERS  
Researcher ID: N-9681-2016

 doi 10.22214/IJRASET  
cross ref

 TOGETHER WE REACH THE GOAL  
SCOPUS  
SCIENTIFIC JOURNAL Impact Factor  
SJIF 7.429