



ISSN No. : 2321-9653

# IJRASET

**International Journal for Research in Applied  
Science & Engineering Technology**

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

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Manipulators with Smoothness and Energy Considerations*

*by  
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*after review is found suitable and has been published in  
Volume 14, Issue V, May 2026*

*in  
International Journal for Research in Applied Science &  
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