ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

ISRA Journal Impact Factor: 7.429

45.98 INDEX COPERNICUS

THOMSON REUTERS Researcher ID: N-9681-2016

10.22214/IJRASET

TOGETHER WE REACH THE GOAL SJIF 7.429

Certificate

It is here by certified that the paper ID : IJRASET76645, entitled

LQR Based Cooperative Vibration Suppression in Dual Flexible Robotic Manipulators with Unequal Load Sharing

by

Vijitha K

after review is found suitable and has been published in Volume 13, Issue XII, December 2025

in

International Journal for Research in Applied Science & Engineering Technology

(International Peer Reviewed and Refereed Journal)

Good luck for your future endeavors

Editor in Chief, iJRASET

ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

ISRA Journal Impact Factor: 7.429

45.98 INDEX COPERNICUS

THOMSON REUTERS Researcher ID: N-9681-2016

10.22214/IJRASET

TOGETHER WE REACH THE GOAL SJIF 7.429

Certificate

It is here by certified that the paper ID : IJRASET76645, entitled

LQR Based Cooperative Vibration Suppression in Dual Flexible Robotic Manipulators with Unequal Load Sharing

by

Sarvesh R

after review is found suitable and has been published in Volume 13, Issue XII, December 2025

in

International Journal for Research in Applied Science & Engineering Technology

(International Peer Reviewed and Refereed Journal)

Good luck for your future endeavors

Editor in Chief, iJRASET

ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

ISRA Journal Impact Factor: 7.429

45.98 INDEX COPERNICUS

THOMSON REUTERS Researcher ID: N-9681-2016

10.22214/IJRASET

TOGETHER WE REACH THE GOAL SJIF 7.429

Certificate

It is here by certified that the paper ID : IJRASET76645, entitled

LQR Based Cooperative Vibration Suppression in Dual Flexible Robotic Manipulators with Unequal Load Sharing

by

Dr. Anbarasi M P

after review is found suitable and has been published in Volume 13, Issue XII, December 2025

in

International Journal for Research in Applied Science & Engineering Technology

(International Peer Reviewed and Refereed Journal)

Good luck for your future endeavors

Editor in Chief, iJRASET