



ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied
Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

Certificate

It is here by certified that the paper ID : IJRASET64601, entitled

Optimization of Motion Planning for Quadrotor-Equipped Robotic Manipulators

by

Melwin Tony V

after review is found suitable and has been published in

Volume 12, Issue XI, November 2024

in

*International Journal for Research in Applied Science &
Engineering Technology*

(International Peer Reviewed and Refereed Journal)

Good luck for your future endeavors

By [Signature]

Editor in Chief, iJRASET

JISRA
JOURNAL
IMPACT
FACTOR

ISRA Journal Impact
Factor: **7.429**


45.98
INDEX COPERNICUS


THOMSON REUTERS
Researcher ID: N-9681-2016


doi 10.22214/IJRASET
cross ref


Scopus
SCOPUS
SCIENTIFIC JOURNAL IMPACT FACTOR
TOGETHER WE REACH THE GOAL
SJIF 7.429



ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied
Science & Engineering Technology

iJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

Certificate

It is here by certified that the paper ID : IJRASET64601, entitled

Optimization of Motion Planning for Quadrotor-Equipped Robotic Manipulators

by

Perarasu P

after review is found suitable and has been published in

Volume 12, Issue XI, November 2024

in

*International Journal for Research in Applied Science &
Engineering Technology*

(International Peer Reviewed and Refereed Journal)

Good luck for your future endeavors

By [Signature]

Editor in Chief, iJRASET

JISRA
JOURNAL
IMPACT
FACTOR

ISRA Journal Impact
Factor: **7.429**

 45.98
INDEX COPERNICUS

 THOMSON REUTERS
Researcher ID: N-9681-2016

 doi 10.22214/IJRASET
cross ref

 SCOPUS
SCIENTIFIC JOURNAL IMPACT FACTOR
TOGETHER WE REACH THE GOAL
SJIF 7.429



ISSN No. : 2321-9653

iJRASET

International Journal for Research in Applied
Science & Engineering Technology

IJRASET is indexed with Crossref for DOI-DOI : 10.22214

Website : www.ijraset.com, E-mail : ijraset@gmail.com

Certificate

It is here by certified that the paper ID : IJRASET64601, entitled

Optimization of Motion Planning for Quadrotor-Equipped Robotic Manipulators

by

Dr. Anbarasi MP

after review is found suitable and has been published in

Volume 12, Issue XI, November 2024

in

*International Journal for Research in Applied Science &
Engineering Technology*

(International Peer Reviewed and Refereed Journal)

Good luck for your future endeavors

By [Signature]

Editor in Chief, iJRASET

 ISRA

ISRA Journal Impact
Factor: 7.429



45.98

INDEX COPERNICUS



THOMSON REUTERS
Researcher ID: N-9681-2016



TOGETHER WE REACH THE GOAL
SJIF 7.429